

82C621A PCI IDE Controller

Data Book

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PCI IDE Controller

1.0 Overview

The OPTi 82C621A PCI IDE Controller (PIC) is a 100-pin controller chip designed for a fast and flexible interface between the PCI bus and two IDE cables. The 82C621A implements a PCI function to directly support both the Primary and Secondary IDE in a single 100-pin PQFP. This high-integration approach reduces component count, eases board design, reduces cost and increases reliability. An integrated 4-level read-prefetch FIFO and a 4-level posted write FIFO supports zero wait-state operations, substantially improving performance over other IDE implementations. The Enhanced ATA Specification can be supported either by setting Strap Options or by programming internal registers.

2.0 Features

- · Supports 32-bit PCI Bus & Configuration Registers
- 100-pin PQFP
- Supports 4 ATA peripherals
- Optional PCI Expansion ROM support
- · 16-byte Read-Prefetch and Write-Posting FIFO
- IDE timing controlled by either Straps or Registers
- Programming interface compatible with 82C611A

2.1 Special Feature Notes

Write Posting and Read-prefetch allows CPU memory cycles to run concurrently with IDE cycles and also removes the synchronization penalty for AT-bus transfers. IDE cycles can be fine tuned by the ANSI Mode strap options or programmable registers for ANSI-standard (mode 0, 1, 2 or 3) devices or non-standard devices. 32-bit PCI cycles translated to two 16-bit IDE cycles for faster data access.

Figure 2-1 Block Diagram

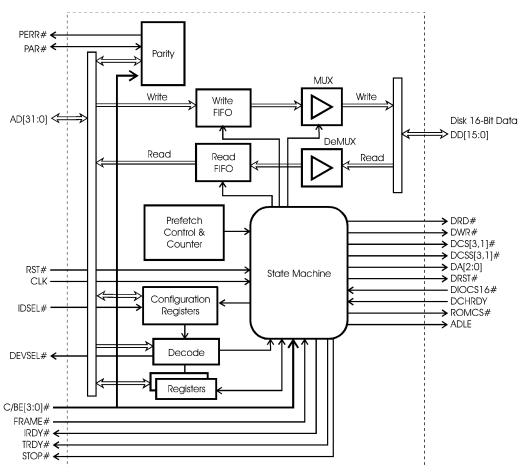
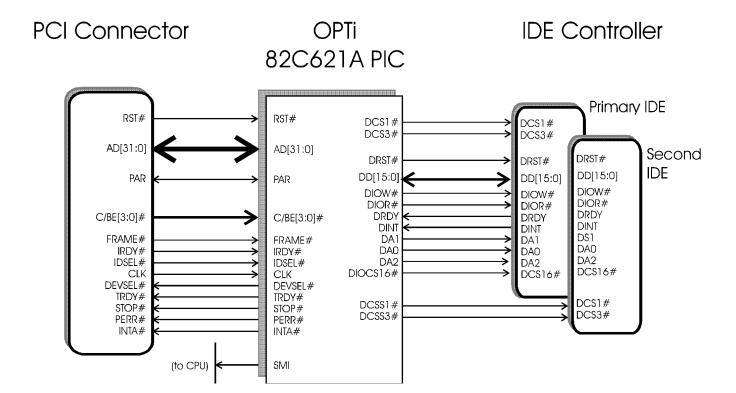


Figure 2-2 Example PCI Controller Block Diagram





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3.0 Signal Description

Figure 3-1 Pin Diagram

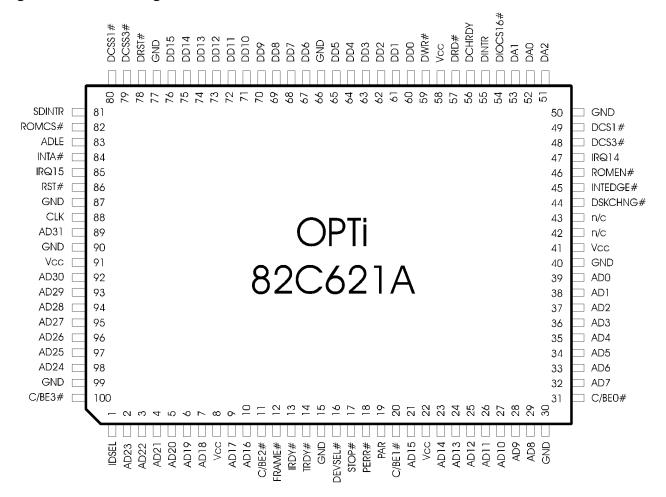


Table 3-1 Numerical Pin List

Pin	Name
1	IDSEL
2	AD23
3	AD22
4	AD21
5	AD20
6	AD19
7	AD18
8	VCC
9	AD17
10	AD16
11	C/BE2#
12	FRAME#
13	IRDY#
14	TRDY#
15	GND
16	DEVSEL#
17	STOP#
18	PERR#
19	PAR
20	C/BE1#
21	AD15
22	VCC
23	AD14
24	AD13
25	AD12

Pin	Name		Pin	Name
1	IDSEL		26	AD11
2	AD23		27	AD10
3	AD22		28	AD9
4	AD21		29	AD8
5	AD20		30	GND
6	AD19		31	C/BE0#
7	AD18		32	AD7
8	VCC		33	AD6
9	AD17		34	AD5
10	AD16		35	AD4
11	C/BE2#		36	AD3
12	FRAME#		37	AD2
13	IRDY#		38	AD1
14	TRDY#		39	AD0
15	GND		40	GND
16	DEVSEL#		41	VCC
17	STOP#		42	n/c
18	PERR#		43	n/c
19	PAR		44	DSKCHNG#
20	C/BE1#		45	INTEDGE#
21	AD15		46	ROMEN#
22	VCC		47	IRQ14
23	AD14		48	DCS3#
24	AD13		49	DCS1#
25	AD12		50	GND

Pin	Name
51	DA2
52	DA0
53	DA1
54	DIOCS16#
55	DINTR
56	DCHRDY
57	DRD#
58	VCC
59	DWR#
60	DD0
61	DD1
62	DD2
63	DD3
64	DD4
65	DD5
66	GND
67	DD6
68	DD7
69	DD8
70	DD9
71	DD10
72	DD11
73	DD12
74	DD13
75	DD14

Pin	Name	
76	DD15	
77	GND	
78	DRST#	
79	DCSS3#	
80	DCSS1#	
81	SDINTR#	
82	ROMCS#	
83	ADLE	
84	INTA#	
85	IRQ15	
86	RST#	
87	GND	
88	CLK	
89	AD31	
90	GND	
91	VCC	
92	AD30	
93	AD29	
94	AD28	
95	AD27	
96	AD26	
97	AD25	
98	AD24	
99	GND	
100	C/BE3#	

Table 3-2 Alphabetical Pin List

Name	Pin
AD0	39
AD1	38
AD2	37
AD3	36
AD4	35
AD5	34
AD6	33
AD7	32
AD8	29
AD9	28
AD10	27
AD11	26
AD12	25
AD13	24
AD14	23
AD15	21
AD16	10
AD17	9
AD18	7
AD19	6
AD20	5
AD21	4
AD22	3
AD23	2
AD24	98

Name	Pin
AD25	97
AD26	96
AD27	95
AD28	94
AD29	93
AD30	92
AD31	89
ADLE	83
C/BE0#	31
C/BE1#	20
C/BE2#	11
C/BE3#	100
CLK	88
DA0	52
DA1	53
DA2	51
DCHRDY	56
DCS1#	49
DCS3#	48
DCSS1#	80
DCSS3#	79
DD0	60
DD1	61
DD2	62
DD3	63

Name	Pin
DD4	64
DD5	65
DD6	67
DD7	68
DD8	69
DD9	70
DD10	71
DD11	72
DD12	73
DD13	74
DD14	75
DD15	76
DEVSEL#	16
DINTR	55
DIOCS16#	54
DRD#	57
DRST#	78
DSKCHNG#	44
DWR#	59
FRAME#	12
GND	15
GND	30
GND	40
GND	50
GND	66

Pin
77
87
90
99
1
84
45
13
47
85
42
43
19
18
82
46
86
81
17
14
8
22
41
58
91

3.1 Pin Assignments

3.1.1 PCI-BUS Interface

Name	Туре	Pin	Description
AD[31:0]	I/O	89, 92-98, 2- 7, 9,10,21,2 3-29, 32- 39	Address/Data. Multiplexed address/data lines of the PCI bus. A bus transaction includes an address phase followed by one or more data phases.
C/BE[3:0]#	I	100,11,2 0,31	Bus Command/Byte Enable. These lines define the bus command during the address phase of a bus transaction. During the data phase, these lines define the byte enables.
CLK	I	88	PCI Bus Clock. This signal provides timing for all PCI transactions.
DEVSEL#	0	16	Device Select. This output indicates that the current address on the PCI-bus is addressing the PIC.
FRAME#	I	12	<i>Cycle Frame.</i> This signal is asserted to indicate a bus transaction is beginning and de-asserted at the end of the address phase.
IDSEL	I	1	<i>Initialization Device Select.</i> This is used as a chip select during configuration read/write cycles.
INTA#/IRQ14	0	84	Interrupt A/Interrupt Request 14. When pin 79 (DCSS3#) is high at reset, this is used as IRQ14. When pin 79 is low at reset, the pin is used as INTA#. Refer to Section 3.2, Oldmode vs. Newmode for more information.
IRDY#	I	13	<i>Initiator Ready.</i> This signal indicates the bus masters ability to complete the current data phase.
IRQ15	0	85	Interrupt Request 15. This is used as IRQ15. Refer to Section 3.2, Oldmode vs. Newmode for more information.
PAR	I/O	19	Parity. This signal indicates even parity across AD[31:0] and C/BE[3:0]#.
PERR#	0	18	Parity Error. This signal is used to report data parity errors.
RST#	I	86	Reset. This signal is used to initialize the PIC and any drives attached.
STOP#	0	17	<i>Stop.</i> This signal indicates that the target is requesting the master to stop the current transaction.
TRDY#	0	14	<i>Target Ready.</i> This signal indicates the targets ability to complete the current data phase of the transaction.



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3.1.2 IDE Interface

Name	Туре	Pin	Description				
DA[1:0] / MODE[1:0]	I/O	53,52	Drive Address Lines/Mode [1:0]. These are the two lower bits of the 3-bit binary coded address asserted by the host to access a register or data port in the drive. At reset time, Mode [1,0] are sampled to set the IDE Device Modes for 16-bit Cycle Times:				
DA2/ENPREF	I/O	51	Drive Address Line 2/Enable Prefetch. This is the MSB of the 3-bit binary coded address asserted by the host to access a register or data port in the drive. At reset time, ENPREF is sampled to set the Miscellaneous Register bit 6 which decides whether to enable or disable read prefetch. 1 = Enable, 0 = Disable				
DCHRDY	I	56	I/O Channel Ready. This signal is negated to extend the host transfer cycle of any host register access (Read or Write) when the drive is not ready to respond to a data transfer request. When DCHRDY is not negated, DCHRDY is in a high impedance state.				
DCS1#/SPD0	I/O	49	Drive Chip Select 1. This is the chip select signal decoded from the host address bus used to select the Command Block Registers for the primary IDE. At reset time, SPD0 is sampled to set the Strap Register bit 0 (PCI-bus frequency select, LSB), which determines the exact PCI-bus frequency: SPD0 Frequency 0 33 MHz 1 25 MHz				
DCS3# / PCI3x7	I/O	48	Drive Chip Select 3. This is the chip select signal decoded from the host address bus used to select the Control Block Registers for the primary IDE. At reset time, PCI3x7 is sampled to set the Strap registers bit 7 for both the primary (3F7h) and secondary (377h) IDE, which decides whether or not to respond to I/O port 3F7h/377h from the local bus. 0 = 3F7h/377h read from local bus 1 = No response to 3F7h/377h read				
DCSS1# / RELOC	I/O	80	Secondary Drive Chip Select 1. This is the chip select signal decoded from the host address bus used to select the Command Block Registers for the secondary IDE. At reset time, RELOC is sampled to decide whether the I/O space addresses are relocatable through programming configuration space registers. 0 = Fixed I/O addresses (1F0h-1F7h, 3F6h for primary; 170h-177h, 376h for secondary). 1 = Relocatable I/O addresses.				



3.1.2 IDE Interface (cont.)

Name	Туре	Pin	Description
DCSS3#/ INTMODE	0	79	Secondary Drive Chip Select 3. This chip select signal is decoded from the host address bus used to select the Control Block Registers for the secondary IDE. Interrupt Mode. When pin 79 is high during reset, the INTA# and IRQ15 interrupt functions remain the same (oldmode). When pin 79 is low during reset, a different definition for the interrupt pins (84 and 85) is set (newmode). Refer to section 3.2 oldmode vs. newmode for more information.
DD[15:0]	I/O	76-67, 65-60	Disk Data Bus Lines 0 to 15. These sixteen data bus lines require an external pull-up.
DIOCS16#	I	54	Drive 16-bit I/O. DIOCS16# indicates that the 16-bit data port has been addressed and that the drive is prepared to send or receive a 16-bit data word. If DIOCS16# is not asserted, transfers are 8-bit using DD[7:0]. If DIOCS16# is asserted, transfers are 16-bit using DD[15:0].
DRD#	0	57	Drive I/O read. This is the Read strobe signal. The low level of DRD# enables data from a register or the data port of the drive onto the data bus DD[7:0] or DD[15:0].
DWR#	0	59	Drive I/O write. This is the Write strobe signal. The rising edge of DWR# samples data from the data bus DD[7:0] or DD[15:0] into a register or the data port of the drive.
DINTR	1	55	Drive interrupt. This signal is used to interrupt the host system for the primary IDE. DINTR is asserted only when the drive has a pending interrupt, the drive is selected, and the host has cleared nIEN in the Device Control Register. DINTR is negated by assertion of DRST#, the setting of SRST of the Device Control Register, the host writing the Command Register, or the host reading the Status Register DINTR is asserted at the beginning of each data block to be transferred. A data block is typically a single sector, except when declared otherwise by use of the Set Multiple command. An exception to this occurs on Format Track, Write Sector(s), Write Buffer and Write Long commands where DINTR is not asserted at the beginning of the first data block to be transferred.
DRST#	0	78	Drive reset. This signal is asserted for at least 25 μsec after voltage levels have stabilized during power on and negated thereafter unless some event requires that the drive(s) be reset following power on.
SDINTR	I	81	Secondary Drive interrupt. This signal is used to interrupt the host system for the secondary IDE. SDINTR is asserted only when the drive has a pending interrupt, the drive is selected, and the host has cleared nIEN in the Device Control Register. SDINTR is negated by assertion of DRST#, the setting of SRST of the Device Control Register, the host writing the Command Register, or the host reading the Status Register SDINTR is asserted at the beginning of each data block to be transferred. A data block is typically a single sector, except when declared otherwise by use of the Set Multiple command. An exception to this occurs on Format Track, Write Sector(s), Write Buffer and Write Long commands where DINTR is not asserted at the beginning of the first data block to be transferred.

3.1.3 AT-Bus Interface

Name	Туре	Pin	Description
DSKCHNG#	I	44	Disk-Change-Line. For configurations including a floppy controller, this signal can be connected to the drive-change line.



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3.1.4 ROM Support/Power Management Interface

Name	Туре	Pin	Description
ADLE/FNC0	I/O	83	Address Latch Enable/Function 0. ADLE output is used to latch ROM addresses 0 through 7 when ROM is enabled. At reset time, Function 0 is sampled to enable different functions of the chip, as follows: ENCO Eunction 0 Both Primary and Secondary IDE enabled 1 Primary IDE only
ROMEN#	I	46	ROM Enable. At reset time, this pin is sampled to enable or disable expansion ROM. 0 = Enable. 1 = Disable.
ROMCS#/ SMI#/ TMOD#	I/O	82	ROM Chip Select/System Management Interrupt/Test Mode. ROM Chip Select is used to enable the ROM output and ROM data buffer. SMI# is used to signal to the host system that an SMI event has occurred. The function of this pin is determined by the sampling of ROMEN# strap option. At reset time, TMOD# is sampled to enable test mode. This line requires an external pull up, and must be sampled high at the end of reset for normal operation. 0 = Test mode. 1 = User mode.

3.1.5 Miscellaneous Pins

Name	Туре	Pin	Description
IRQ14	0	47	Interrupt Request 14. This pin is normally used as IRQ14 when pin 79 is high at reset. Refer to Section 3.2, Oldmode vs. Newmode for more information on this function.
INTEDGE#	I	45	Interrupt Level/Edge. When pin 79 is high at reset, this pin is sampled to decide whether INTA# and IRQ15 are edge or level triggered interrupts. 0 = Edge triggered (Active high). 1 = Shared level triggered (Active low). When pin 79 is low at reset, the strap function is disabled.

3.1.6 Power and Ground Pins

Name	Type	Pin	Description
GND	I	15,30,40,50,66,77,87,90,99	Vss or Ground
VCC	I	8,22,41,58,91	Vcc or +5v

3.2 Oldmode vs. Newmode

A new strap option has been added to pin 79 (DCSS3#) to select the mode that the 82C621A will run in. The features that are affected by this strap are:

- 1. When pin 79 is high during reset, the INTA# and IRQ15 interrupt functions remain the same. This is called oldmode. When pin 79 is low during reset, a different definition for the interrupt pins (84 and 85) is given in the table below. This is called newmode. Pin 79 is pulled high internally.
- 2. Interrupt pins 84 and 85, and pin 47 are renamed and redefined based on the newmode strap option.

The new names are:

Pin	Name
84	INTA#
85	IRQ15
47	IRQ14

The new definitions are:

Actual mode of operation ¹	Interrupt level	Pin (oldmode)			Pin (newmode)		
	Strap	84	85	47	84	85	47
Legacy	Edge	14	15	14	3st ²	15	14
Legacy	Level	14# ³	15#	14	3st	15	14
Native	Edge	14	15	3st	INTA#	3st	3st
Native	Level	14#	15#	3st	INTA#	3st	3st

Refer to Section Section 4.6, Class Code Register (09h, R/W), bits 7:0 for information on setting Legacy and Native modes.

Note Oldmode is only for compatibility with older versions of the 82C621. All new designs should use newmode for software compatibility with other vendor's devices.

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^{2. 3}st = Tri-state

^{3. # =} active low

4.0 Configuration Register Descriptions

This section describes the registers implemented in the 256 byte configuration space. All registers not implemented always return zero during read cycles.

Optionally, the PIC will support an expansion ROM on the PCI IDE plug-in board. This support will require two extra TTLs, as address latch and data buffer, on board. Also this will require a 32 bit register in the configuration space that normally would not be enabled. The expansion ROM base address register (offset 30h-33h) will be enabled only if the ROMEN# strap pin is sampled low at the time of reset.

4.1 Vendor ID Register (00h, Read Only)

Bits	Mnemonic	Description	Default
15:0	VID	Vendor ID: This register identifies the OPTi ID.	1045h

4.2 Device ID Register (02h, Read Only)

Bits	Mnemonic	Description	Default
15:0	DID	Device ID: This register identifies the ID of the PIC.	C621h

4.3 Command Register (04h, R/W)

Bits	Mnemonic	Description	Default
[15:7]		Reserved - Read only.	0
6	PEN	Parity Checking Enable: When this bit is set, PIC generates PERR# if a parity error occurs during I/O write cycles. If the bit is reset, parity checking is ignored. For I/O read cycles, PIC always generates the parity bit.	0
[5:2]		Reserved - Read only.	0
1	MEMEN	Memory Enable: When this bit is set and the expansion ROM enable bit is set (in the EPROM Register), the ROM space becomes available for reading.	0
0	IOEN	Input/Output Enable: When this bit is set, PIC enables the I/O accesses. If reset, all I/O accesses are disabled.	1

4.4 Status Register (06h, R/W)

Bits	Mnemonic	Description	Default
15	PER	Parity Error: This bit is set whenever the PIC detects a parity error. This bit is cleared by writing 8000h to this register.	0
[14:11]		Reserved - Read Only.	0
[10:9]	SELTIM	Select Timing: These are read only bits indicating allowable timing assertion for DEVSEL#.	01
8		Reserved - Read only.	0
7	ВТВ	Back-To-Back Transactions. This is a read only bit, set to 1 to allow fast back-to-back transactions.	1
[6:0]		Reserved - Read only.	0

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4.5 Revision ID Register (08h, Read Only)

Bits	Mnemonic	Description	Default
7:0	REVID	Revision ID: This register identifies the revision number of the PIC.	0

4.6 Class Code Register (09h, R/W)

Bits	Mnemonic	Description	Default
23:8	CCODE (read only)	Class Code: The MSB indicates the base class code for the mass storage controller. The middle byte indicates the sub class code (IDE controller).	0101h
7:0	PI	Programming Interface. When this register is defined as read/write, the first byte is used to define the IDE as relocatable (native mode) or fixed (legacy mode). Bits 0 and 1 are used for the primary IDE and bits 2 and 3 are used for the secondary IDE. Bits 0 and 2 show whether the IDE is in native mode or legacy mode and bits 1 and 3 show the setting of the RELOC strap option (0=low, 1=high). Bits 4 through 7 are reserved and set to 0. If the RELOC strap is low during reset, the IDE configuration is fixed (no relocatable) and the PI register bits are set to 0. If the RELOC strap is high during reset, the configuration space is definable and the PI register is accessible: bits 1 and 3 are set to 1 and bits 0 and 2 are used to define the IDE mode. Also, if the FNC0 strap is set to support the primary IDE only, bits 2 and 3 will not be used.	

4.7 Header Type Register (0Eh, Read Only)

Bits	Mnemonic	Description	Default
7:0	HDR	Header Type: Single function device.	00h

4.8 Command Block Base Address Register (10h, R/W) (Primary IDE)

Bits	Mnemonic	Description	Default
31:0	IO1	Command Block Base Address: This register is the I/O space indicator for the Drive Command Block. The address block has a size of 8 bytes. Bit [2:0] of this register are read only and default to 001. Bits [31:3] are writable if RELOC strap is set to 1. If the RELOC strap is set to 0, bits [31:0] are read only and return 0.	1F1h w/ RELOC=1

4.9 Control Block Base Address Register (14h, R/W) (Primary IDE)

Bits	Mnemonic	Description	Default
31:0	IO2	Control Block Base Address: This register is the I/O space indicator for the Drive Control Block. The address block has a size of 4 bytes. Bit [1:0] of this register are read only and default to 01. Bits [31:2] are writable if RELOC strap is set to 1. If the RELOC strap is set to 0, bits [31:0] are read only and return 0.	3F5h w/ RELOC=1

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4.10 Command Block Base Address Register (18h, R/W) (Secondary IDE)

Bits	Mnemonic	Description	Default
31:0	IO3	Command Block Base Address: This register is the I/O space indicator for the Drive Command Block. The address block has a size of 8 bytes. Bit [2:0] of this register are read only and default to 001. Bits [31:3] are writable if RELOC strap is set to 1. If the RELOC strap is set to 0, bits [31:0] are read only and return 0.	171h w/ RELOC=1 FNC0=0

4.11 Control Block Base Address Register (1Ch, R/W) (Secondary IDE)

Bits	Mnemonic	Description	Default
31:0	104	Control Block Base Address: This register is the I/O space indicator for the Drive Control Block. The address block has a size of 4 bytes. Bit [1:0] of this register are read only and default to 01. Bits [31:2] are writable if RELOC strap is set to 1. If the RELOC strap is set to 0, bits [31:0] are read only and return 0.	375h w/ RELOC=1 FNC0=0

4.12 External ROM Base Address Register (30h, R/W)

Bits	Mnemonic	Description	Default
31:0	EROM	External ROM Base Address: This register contains the expansion ROM address. The address block has a size of 16KB. Bits [13:1] of this register are always read only and default to 0. Bits [31:14, 0] are writable if the ROMEN# strap is sampled low. Bits [31:14] define the base address of the expansion ROM. Bit 0 enables/disables the expansion ROM decode (0 = disable, 1 = enable). If the ROMEN# strap is sampled high, this register is read only (always 0) and ROM decode is disabled.	x

4.13 Interrupt Line Register (3Ch, R/W)

Bits	Mnemonic	Description	Default
7:0	INTL	Interrupt Line. This register indicates which input of the system interrupt controller the INTA# interrupt pin is routed to.	Eh

4.14 Interrupt Pin Register (3Dh, Read Only)

Bits	Mnemonic	Description	Default
7:0	INTP	Interrupt Pin. The content of this register is 1 (i.e., INTA# will be used).	1

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5.0 I/O Register Descriptions

5.1 I/O Registers for Primary IDE

The register addresses are referred to in this section by their power-up default addresses. If the power-up default is modified by writing to configuration register IO1, then these registers will be relocated accordingly.

The PIC contains registers at seven I/O ports accessible after two consecutive 16-bit I/O reads from address 1F1h. Any other I/O cycle between these two reads will disable access to the PIC registers.

5.1.1 Internal ID Register (1F2h, Write Only)

Bits	Mnemonic	Description	Default
7	CNFDIS	Configuration Disable: This bit must be set to '0' in order to access 621A Internal Registers. Any write to this register with CNFDIS = 1 will disable all accesses to the 621A registers until another two consecutive I/O reads from 1F1h.	1
6	CNFOFF	Configuration Off. This bit must be set to '0' in order to access 621A Internal Registers. Any write to this register with CNFOFF = 1 will disable all accesses to the 621A registers until power down or reset.	0
[5:2]		Reserved - Must be written 0.	
[1:0]		Reserved - Must be written 11.	

5.1.2 Read Cycle Timing Register-A (1F0h, Index-0, R/W)

This register shares the I/O address with the Read Cycle Timing Register-B, indexed by the Miscellaneous Register bit 0. It controls the read cycle timing of IDE data register for the drive selected by the Control register bits [3:2]. The bit field of this register is defined as follows:

Bits	Mnemonic	Description	Default
[7:4]	RDPW[3:0]	Read Pulse Width: The value programmed in this register determines the DRD# pulse width in CLKs (for a 16-bit read from the IDE Data Register). See Table 5-6.	xxxx
[3:0]	RDREC[3:0]	Read Recovery Time: The value programmed in this register determines the recovery time between the end of DRD# and the next DA[2:0]/DCSx# being presented (after a 16-bit read from the IDE Data Register), measured in CLKs. See Table 5-7.	xxxx

5.1.3 Read Cycle Timing Register-B (1F0h, Index-1, R/W)

This register shares the I/O address with the Read Cycle Timing Register-A, indexed by the Miscellaneous Register bit 0. It controls the read cycle timing of IDE data register for the drive not selected by the Control register bits [3:2], if the Control Register bit 7 is set The bit fields of these registers is defined as follows:

Bits	Mnemonic	Description	Default
[7:4]	RDPW[3:0]	Read Pulse Width: The value programmed in this register determines the DRD# pulse width in CLKs (for a 16-bit read from the IDE Data Register). See Table 5-6.	xxxx
[3:0]	RDREC[3:0]	Read Recovery Time: The value programmed in this register determines the recovery time between the end of DRD# and the next DA[2:0]/DCSx# being presented (after a 16-bit read from the IDE Data Register), measured in CLKs. See Table 5-7.	xxxx

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5.1.4 Write Cycle Timing Register-A (1F1h, Index-0, R/W)

This register shares the I/O address with the Write Cycle Timing Register-B, indexed by the Miscellaneous Register bit 0. It controls the write cycle timing of IDE data register for the drive selected by the Control register bits [3:2]. The bit field of this register is defined as follows:

Bits	Mnemonic	Description	Default
[7:4]	WRPW[3:0]	Write Pulse Width: The value programmed in this register determines the DWR# pulse width in CLKs (for a 16-bit write from the IDE Data Register). See Table 5-6.	xxxx
[3:0]	WRREC[3:0]	Write Recovery Time: The value programmed in this register determines the recovery time between the end of DWR# and the next DA[2:0]/DCSx# being presented (after a 16-bit write from the IDE Data Register), measured in CLKs. See Table 5-7.	xxxx

5.1.5 Write Cycle Timing Register-B (1F1h, Index-1, R/W)

This register shares the I/O address with the Write Cycle Timing Register-A, indexed by the Miscellaneous Register bit 0. It controls the write cycle timing of IDE data register for the drive not selected by the Control register bits [3:2], if the Control Register bit 7 is set The bit fields of these registers is defined as follows:

Bits	Mnemonic	Description	Default
[7:4]	WRPW[3:0]	Write Pulse Width: The value programmed in this register determines the DWR# pulse width in CLKs (for a 16-bit write from the IDE Data Register). SeeTable 5-6.	xxxx
[3:0]	WRREC[3:0]	Write Recovery Time: The value programmed in this register determines the recovery time between the end of DWR# and the next DA[2:0]/DCSx# being presented (after a 16-bit write from the IDE Data Register), measured in CLKs. See Table 5-7.	xxxx

5.1.6 Control Register (1F3h, R/W)

Bits	Mnemonic	Description	Default
7	REGTIM2	Enable Timing Registers-B. When set, this bit enables cycle-timing registers-B (1F0h & 1F1h of the Index-1) to override the IDE timing set by the strap options for any drive not selected by 1F3h bit [3:2]. It also enables the miscellaneous timing register 1F6h bits [5:1] to override the timing set by the strap options.	0
[6:5]		Reserved: Must always be written with '0'.	0
4	EN1WSRD	Enable 1-Wait State Read. 1 = 1 WS minimum for data reads, 0 = 2 WS minimum.	0
3	REGTIM1	Enable Timing Register-A, Drive 1: When set, this bit enables cycle-timing registers-A (1F0h & 1F1h of the Index-0) to override the IDE timing set by the strap options for Drive-1.	0
2	REGTIM0	Enable Timing Register-A, Drive 0: When set, this bit enables cycle-timing registers-A (1F0h & 1F1h of the Index-0) to override the IDE timing set by the strap options for Drive-0.	0
1	ENSMI	Enable SMI: When set, this bit generates an SMI upon access to any IDE I/O address, if ENDO is 1 and CNFDIS is 1. Clearing this bit will reset SMI and disables it.	0
0		Reserved - Must be written 1.	1

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NOTE

For all new software controls the IDE timing through registers programming, bits 2, 3 and 7 of the Control register should be enabled after the Cycle Timing Registers and Miscellaneous Register are programmed. See Table 5-1 for programming options.

5.1.7 Strap Register (1F5h)

Bits	Mnemonic	Description	Default
7	PCI3F7	 PCI 3F7 Read (Read/Write). Decides whether or not read access to 3F7h comes from local bus. 0 = 3F7h read from local bus. 1 = No response to 3F7h read. 	
[6:5]	REV[1:0]	Revision Number Register (Read Only). When the value of this register is set to 11, the content of REVID register should be used to find the revision level of the chip.	11
4	DINTR	DINTR Status (Read Only). Returns the state of DINTR input.	
[3:2]	MODE[1:0]	Mode (Read Only). Returns information about drive speed as determined by MODE[1:0] strap options. Please refer to the Mode Strap description for specific information.	
1		Reserved - Must be written 1.	
0	SPD0	CLK Speed (Read/Write). PCI-Bus CLK frequency select. At reset time, the value of these bits is set by the sampling of SPD0 strap options. SPD0 CLK 0 33 MHz 1 25 MHz	

5.1.8 SMI Address Register (1F2h, Read Only)

Bits	Mnemonic	Description	Default
7	SMI	SMI Status: This reflects the state of the SMI output from the PIC.	х
6	SMIW/R#	SMI Last W/R#: The value of W/R# during the cycle that last caused an SMI.	х
5	SMIA9	SMI Last A9: The value of HA9 during the cycle that last caused an SMI.	х
4	SMIA2	SMI Last A2: The value of HA2 during the cycle that last caused an SMI.	х
[3:0]	SMIBE[3:0]	SMI Last BEx#: The value of BE[3:0] during the cycle that last caused an SMI.	xxxx

5.1.9 SMI Data Register (1F4h, Read Only)

Bits	Mnemonic	Description	Default
[7:0]	SMIDATA	SMI Data: If an 8-bit write cycle caused an SMI, this register returns the data written in that cycle.	xxxx xxxx

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5.1.10 SMI Data Register (1F4h, Write Only))

Bits	Mnemonic	Description	Default
7	IRQTRAN	IRQ14, IRQ15, INTA# Transition Bit: Transition of IRQ14, IRQ15, and INTA# from inactive to active during data read prefetch. 0 = Enable 1 = Disable	0
[6:4]		Reserved - Must be written 0.	000
[3:0]	GPRI	General Purpose Register Index: This is the index port for sixteen 8-bit registers located at data port 1F7h. Index Fh is reserved.	

5.1.11 Miscellaneous Register (1F6h, R/W)

Bits	Mnemonic	Description	Default
7	IDEFLOAT	IDE Pins Float: When set, tri-states all the outputs and bi-directional pins connected to the IDE drive. (DRST#, DRD#, DWR#, DCS#3, DCS1#, DA[2:0] and DD[15:0])	0
6	ENPREF	Enable Read Prefetch: Enables/Disables Read Prefetch. At reset time, the value of this register is set by ENPREF strap option. 1 = Enable, 0 = Disable.	
[5:4]	ASU[1:0]	Address Setup Time: The value programmed in this register determines the address setup time between the DRD# or DWR# going active and the DA[2:0], DCS3#, DCS1# being presented, measured in CLKs. See Table 5-4.	Х
[3:1]	DRDY[2:0]	DRDY Delay: The value programmed in this register determines the minimum number of CLKs between DRDY# going high and DRD# or DWR# going inactive. See Table 5-5.	xx
0	INDEX-0	Index-0: This bits is used to select between Cycle Timing Registers-A and -B located at 1F0h and 1F1h.	0

5.1.12 Index Data Register (1F7h, R/W)

Bits	Mnemonic	Description	Default
[7:0]	GPREG	General Purpose Data Register: This is the data port for sixteen 8-bit registers indexed at data port 1F4h.	xxxx xxxx

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5.2 I/O Registers for Secondary IDE

The register addresses are referred to in this section by their power-up default addresses. If the power-up default is modified by writing to configuration register IO3, then these registers will be relocated accordingly.

The PIC contains registers at seven I/O ports accessible after two consecutive 16-bit I/O reads from address 171h. Any other I/O cycle between these two reads will disable access to the PIC registers.

5.2.1 Internal ID Register (172h, Write Only)

Bits	Mnemonic	Description	Default
7	CNFDIS	Configuration Disable: This bit must be set to '0' in order to access 621A Internal Registers. Any write to this register with CNFDIS = 1 will disable all accesses to the 621A registers until another two consecutive I/O reads from 171h.	1
6	CNFOFF	Configuration Off. This bit must be set to '0' in order to access 621A Internal Registers. Any write to this register with CNFOFF = 1 will disable all accesses to the 621A registers until power down or reset.	0
[5:2]		Reserved - Must be written 0.	
[1:0]		Reserved - Must be written 11.	

5.2.2 Read Cycle Timing Register-A (170h, Index-0, R/W)

This register shares the I/O address with the Read Cycle Timing Register-B, indexed by the Miscellaneous Register bit 0. It controls the read cycle timing of IDE data register for the drive selected by the Control register bits [3:2]. The bit field of this register is defined as follows:

Bits	Mnemonic	Description	Default
[7:4]	RDPW[3:0]	Read Pulse Width: The value programmed in this register determines the DRD# pulse width in CLKs (for a 16-bit read from the IDE Data Register). See Table 5-6.	xxxx
[3:0]	RDREC[3:0]	Read Recovery Time: The value programmed in this register determines the recovery time between the end of DRD# and the next DA[2:0]/DCSSx# being presented (after a 16-bit read from the IDE Data Register), measured in CLKs. See Table 5-7.	xxxx

5.2.3 Read Cycle Timing Register-B (170h, Index-1, R/W)

This register shares the I/O address with the Read Cycle Timing Register-A, indexed by the Miscellaneous Register bit 0. It controls the read cycle timing of IDE data register for the drive not selected by the Control register bits [3:2], if the Control Register bit 7 is set The bit fields of these registers is defined as follows:

Bits	Mnemonic	Description	Default
[7:4]	RDPW[3:0]	Read Pulse Width: The value programmed in this register determines the DRD# pulse width in CLKs (for a 16-bit read from the IDE Data Register). See Table 5-6.	xxxx
[3:0]	RDREC[3:0]	Read Recovery Time: The value programmed in this register determines the recovery time between the end of DRD# and the next DA[2:0]/DCSSx# being presented (after a 16-bit read from the IDE Data Register), measured in CLKs. See Table 5-7.	xxxx

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5.2.4 Write Cycle Timing Register-A (171h, Index-0, R/W)

This register shares the I/O address with the Write Cycle Timing Register-B, indexed by the Miscellaneous Register bit 0. It controls the write cycle timing of IDE data register for the drive selected by the Control register bits [3:2]. The bit field of this register is defined as follows:

Bits	Mnemonic	Description	Default
[7:4]	WRPW[3:0]	Write Pulse Width: The value programmed in this register determines the DWR# pulse width in CLKs (for a 16-bit write from the IDE Data Register). See Table 5-6.	xxxx
[3:0]	WRREC[3:0]	Write Recovery Time: The value programmed in this register determines the recovery time between the end of DWR# and the next DA[2:0]/DCSSx# being presented (after a 16-bit write from the IDE Data Register), measured in CLKs. See Table 5-7.	xxxx

5.2.5 Write Cycle Timing Register-B (171h, Index-1, R/W)

This register shares the I/O address with the Write Cycle Timing Register-A, indexed by the Miscellaneous Register bit 0. It controls the write cycle timing of IDE data register for the drive not selected by the Control register bits [3:2], if the Control Register bit 7 is set The bit fields of these registers is defined as follows:

Bits	Mnemonic	Description	Default
[7:4]	WRPW[3:0]	Write Pulse Width: The value programmed in this register determines the DWR# pulse width in CLKs (for a 16-bit write from the IDE Data Register). See Table 5-6.	xxxx
[3:0]	WRREC[3:0]	Write Recovery Time: The value programmed in this register determines the recovery time between the end of DWR# and the next DA[2:0]/DCSSx# being presented (after a 16-bit write from the IDE Data Register), measured in CLKs. See Table 5-7.	xxxx

5.2.6 Control Register (173h, R/W)

5.2.0	Control Hegister	(17611, 1777)						
Bits	Mnemonic	Description	Default					
7	REGTIM2	Enable Timing Registers-B. When set, this bit enables cycle-timing registers-B (170h & 171h of the Index-1) to override the IDE timing set by the strap options for any drive not selected by 173h bit [3:2]. It also enables the miscellaneous timing register 176h bits [5:1] to override the timing set by the strap options.						
[6:4]		Reserved: Must always be written with '0'.						
3	REGTIM1	REGTIM1 Enable Timing Register-A, Drive 1: When set, this bit enables cycle-timing registers-A (170h & 171h of the Index-0) to override the IDE timing set by the strap options for Drive-1.						
2	REGTIM0 Enable Timing Register-A, Drive 0: When set, this bit enables cycle-timing registers-A (170h & 171h of the Index-0) to override the IDE timing set by the strap options for Drive-0.							
1	ENSMI Enable SMI: When set, this bit generates an SMI upon access to any IDE I/O address, if ENDO is 1 and CNFDIS is 1. Clearing this bit will reset SMI and disables it.							
0		Reserved - Must be written 1.	1					

NOTE For all new software controls the IDE timing through registers programming, bits 2, 3 and 7 of the Control register should be enabled after the Cycle Timing Registers and Miscellaneous Register are programmed. See Table 5-1 for programming options.

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5.2.7 Strap Register (175h)

Bits	Mnemonic	Description	Default
7	PCI377	PCI 377 Read (Read/Write). Decides whether or not to respond to 377h read from local bus.	
		0 = 377h read from local bus.	
		1 = No response from 377h read.	
[6:5]	REV[1:0]	Revision Number Register (Read Only). When the value of this register is set to 11, the content of REVID register should be used to find the revision level of the chip.	11
4	SDINTR	SDINTR Status (Read Only). Returns the state of SDINTR input.	
[3:2]		Reserved - Must be written 0.	
1		Reserved - Must be written 1.	
0		Reserved - Must be written 0.	

5.2.8 SMI Address Register (172h, Read Only)

Bits	Mnemonic	Description	Default		
7	SMI	SMI Status: This reflects the state of the SMI output from the PIC.	х		
6	SMIW/R#	SMI Last W/R#: The value of W/R# during the cycle that last caused an SMI.	х		
5	SMIA9	SMI Last A9: The value of HA9 during the cycle that last caused an SMI.			
4	SMIA2	SMI Last A2: The value of HA2 during the cycle that last caused an SMI.			
[3:0]	SMIBE[3:0]	SMI Last BEx#: The value of BE[3:0] during the cycle that last caused an SMI.	xxxx		

5.2.9 SMI Data Register (174h, Read Only)

Bits	Mnemonic	Description	Default
[7:0]	SMIDATA	SMI Data: If an 8-bit write cycle caused an SMI, this register returns the data written in that cycle.	xxxx

5.2.10 Miscellaneous Register (176h, R/W)

Bits	Mnemonic	Description	Default			
7		Reserved - Must be written 0.	0			
6	ENPREF	Enable Read Prefetch: Enables/Disables Read Prefetch. At reset time, the value of this register is set by ENPREF strap option. 1 = Enable, 0 = Disable.				
[5:4]	ASU[1:0]	Address Setup Time: The value programmed in this register determines the address setup time between the DRD# or DWR# going active and the DA[2:0], DCSS3#, DCSS1# being presented, measured in CLKs. See Table 5-4.				
[3:1]	DRDY[2:0]	DRDY Delay: The value programmed in this register determines the minimum number of CLKs between DRDY# going high and DRD# or DWR# going inactive. See Table 5-5.	xx			
0	INDEX-0	Index-0: This bits is used to select between Cycle Timing Registers-A and -B located at 170h and 171h.	0			

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5.3 Programming the IDE Controller Registers

The following steps describe how to program the 82C621A index registers to support different IDE modes. The chip should be booted at 50MHz, mode 0 (from strapping), before you program different modes.

- 1. Program proper values into 1F0h and 1F1h, they are the default for Timing Register-A.
- 2. Set bit 0 of 1F6h to 1 to switch to Timing Register-B.
- 3. Program proper values into 1F0h and 1F1h, they reflect Timing Register-B.
- 4. Program proper values into bits [5:1] of 1F6h. It affects both Timing Register-A and Timing Register-B.
- 5. Enable bits 2, 3 and 7 in 1F3h. The following table describes the options for programming these three bits:

Table 5-1 REGTIMx Programming Options

REGTIM0	REGTIM1	REGTIM2	Drive 0 Control	Drive 1 Control
1 ¹	0	1	Index-0	Index-1
0	1	1	Index-1	Index-0
0	0	1	Index-1	Index-1
1	0	0	Index-0	Straps
0	1	0	Straps	Index-0
0	0	0	Straps	Straps
1	1	Х	Index-0	Index-0

^{1.} Recommended Configuration

The following tables show the recommended index register clock settings to interface to different modes of the IDE drives.

Table 5-2 16-Bit Timing (LCLKs)

		PCI Bus Frequency						
	25MHz, 40ns 33MHz, 30					, 30ns		
Mode	0	1	2	3	0	1	2	3
Address Setup	2	2	1	1	3	2	2	1
Command Pulse	5	4	3	2	6	5	4	3
Recovery Time	8	4	2	2	11	6	2	2
DRDY	2	2	2	2	2	2	2	2

Table 5-3 8-Bit Timing (LCLKs)

		PCI Bus Frequency						
	25MHz, 40ns 33MHz, 30r					, 30ns		
Mode	0	1	2	3	0	1	2	3
Address Setup	2	2	1	1	3	2	2	1
Command Pulse	8	8	8	8	10	10	10	10
Recovery Time	6	6	6	6	9	9	9	9
DRDY	3	3	3	3	4	4	4	4

NOTE The 8-bit settings are fixed and cannot be programmed.

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Table 5-4 Address Setup

Bit 5	Bit 4	Timing, in LCLKs
0	0	1
0	1	2
1	0	3
1	1	4

NOTE Index Registers 1F6h/176h bits [5:4]

Table 5-5 DRDY Delay

Bit 3	Bit 2	Bit 1	Timing, in LCLKs
0	0	0	2
0	0	1	3
0	1	0	4
0	1	1	5
1	0	0	6
1	0	1	7
1	1	0	8
1	1	1	9

NOTE Index Registers 1F6h/176h bits [3:1]

Table 5-6 Read/Write Command Pulse

				Timing, in LCLKs		
Bit 7	Bit 6	Bit 5	Bit 4	Read Command 1F0h/ 170h	Write Command 1F1h/ 171h	
0	0	0	0	1	1	
0	0	0	1	2	2	
0	0	1	0	3	3	
0	0	1	1	4	4	
0	1	0	0	5	5	
0	1	0	1	6	6	
0	1	1	0	7	7	
0	1	1	1	8	8	
1	0	0	0	9	9	
1	0	0	1	10	10	
1	0	1	0	11	11	
1	0	1	1	12	12	
1	1	0	0	13	13	
1	1	0	1	14	14	
1	1	1	0	15	15	
1	1	1	1	16	16	

NOTE Index Registers 1F0h/170h (Read) or 1F1h/171h (Write), Index 0/1, bits [7:4]

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Table 5-7 Read/Write Recovery Time

				Timing, in LCLKs		
Bit 3	Bit 2	Bit 1	Bit 0	Read Recovery 1F0h/ 170h	Write Recovery 1F1h/ 171h	
0	0	0	0	2	2	
0	0	0	1	3	3	
0	0	1	0	4	4	
0	0	1	1	5	5	
0	1	0	0	6	6	
0	1	0	1	7	7	
0	1	1	0	8	8	
0	1	1	1	9	9	
1	0	0	0	10	10	
1	0	0	1	11	11	
1	0	1	0	12	12	
1	0	1	1	13	13	
1	1	0	0	14	14	
1	1	0	1	15	15	
1	1	1	0	16	16	
1	1	1	1	17	17	

Note Index Registers 1F0h/170h (Read) or 1F1h/171h (Write) Index 0/1, bits [3:0]

6.0 AC Characteristics

Temperature: 0°C to 70°C, Vcc: 5V \pm 5%, 50pF load

Sym.	Description	Min (ns)	Typ (ns)	Max (ns)
t1	FRAME#, IRDY#, AD[31:0], PAR, C/BE[3:0]#, IDSEL setup time to CLK ↑	7.0		
t2	FRAME#, IRDY#, AD[31:0], PAR, C/BE[3:0]#, IDSEL hold time to CLK ↑	0.0		
t3	CLK ↑to DEVSEL#, TRDY#, STOP#, PERR# valid	1.0		11.0
t4	CLK ↑to DEVSEL#, TRDY#, STOP#, PERR# invalid	1.0		11.0
t5	CLK ↑to DEVSEL#, TRDY#, STOP#, PERR# float	1.0		11.0
t6	CLK ↑to AD[31:0], PAR valid (continuous data stepping)	2.0		25.0
t7	CLK ↑to AD[31:0] float	2.0		25.0
t8	CLK \downarrow to AD[31:0] valid (1-WS read: continuous data stepping)	3.0		25.0
t9	CLK \uparrow to DRD#, DWR#, DA[2:0], DCS3#, DCS1#, DCSS3#, DCSS1#, ROMCS# valid	2.0		30.0
t10	CLK \uparrow to DRD#, DWR#, DA[2:0], DCS3#, DCS1#, DCSS3#, DCSS1#, ROMCS# invalid	2.0		30.0
t11	CLK ↑to DD[15:0] valid	2.0		
t12	CLK ↑ to DD[15:0] float	1.0		30.0
t13	CLK ↑to ADLE valid	1.0		20.0
t14	DSKCHNG# active to AD[31:0] valid	1.0	9.0	30.0
t15	CLK ↑ to CHRDY# valid	3.0	9.0	20.0
t16	CLK ↑ to CHRDY# float	3.0	9.0	20.0
t17	CLK ↑ to SMI active	3.0	14.0	40.0
t18	CLK ↑ to RD3F7# active	6.0	17.0	33.0
t19	IORC# active to RD3F7# active	2.0	10.0	33.0
t20	IORC# inactive to RD3F7# inactive	2.0	10.0	33.0
t21	RST# active to DRST# active delay	2.0	10.0	20.0

6.1 Absolute Maximum Ratings

Sym	Description	Min	Max	Units
Vcc	Supply Voltage		6.5	V
Vı	Input Voltage	-0.5	Vcc+0.5	V
Vo	Output Voltage	-0.5	Vcc+0.5	V
Тор	Operating Temperature	0	70	°C
Tstg	Storage Temperature	-40	125	°C

OPTi

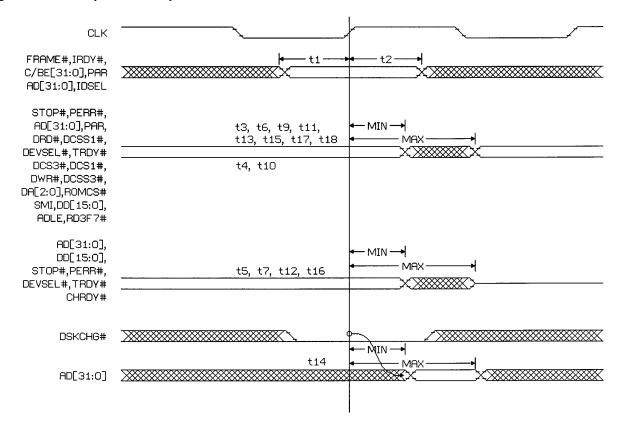
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6.2 DC Characteristics

Sym	Description	Min	Max	Units
VIL1	Input Low Voltage for SPD0, ISA3F7, ENPREF, MODE[1:0], RELOC, FNC0, INTLEV, TOMD#		1.35	V
VIH1	Input High Voltage for SPD0, ISA3F7, ENPREF, MODE[1:0], RELOC, FNC0, INTLEV, TOMD#	3.85		V
VIL2	Input Low Voltage for all other pins		.08	V
VIH2	Input High Voltage for all other pins	2.0		V
VOL	Output Low Voltage 4mA for AD[31:0], INTA#, RD3F7#, ROMCS#/SMI, ADLE, INTB#, PAR 6mA for DEVSEL#, TRDY#, STOP#, PERR# 16mA for CHRDY#, DRST#, DA[2:0], DD[15:0], DRD#, DWR#, DCS1#, DCS3#, DCSS1#, DCSS3#		0.5	V
Voн	Output High Voltage 4mA for AD[31:0], RD3F7#, ROMCS#/SMI, ADLE, PAR 6mA for DEVSEL#, TRDY#, STOP#, PERR# 16mA for DRST#, DA[2:0], DD[15:0], DRD#, DWR#, DCS1#, DCS3#, DCSS1#, DCSS3#	2.4		V
lıL	Input Leakage Current (VIN = VCC)		10	uA
loz	Tri-state Leakage Current		10	uA
CIN	Input Capacitance		10	pF
Соит	Output Capacitance		10	pF
Cio	I/O Capacitance		12	pF
Icc	Power Supply Current		TBA	mA
Iccs	Power Supply Current, Standby		TBA	mA

6.3 Timing Waveforms

Figure 6-1 Input and Output Waveform



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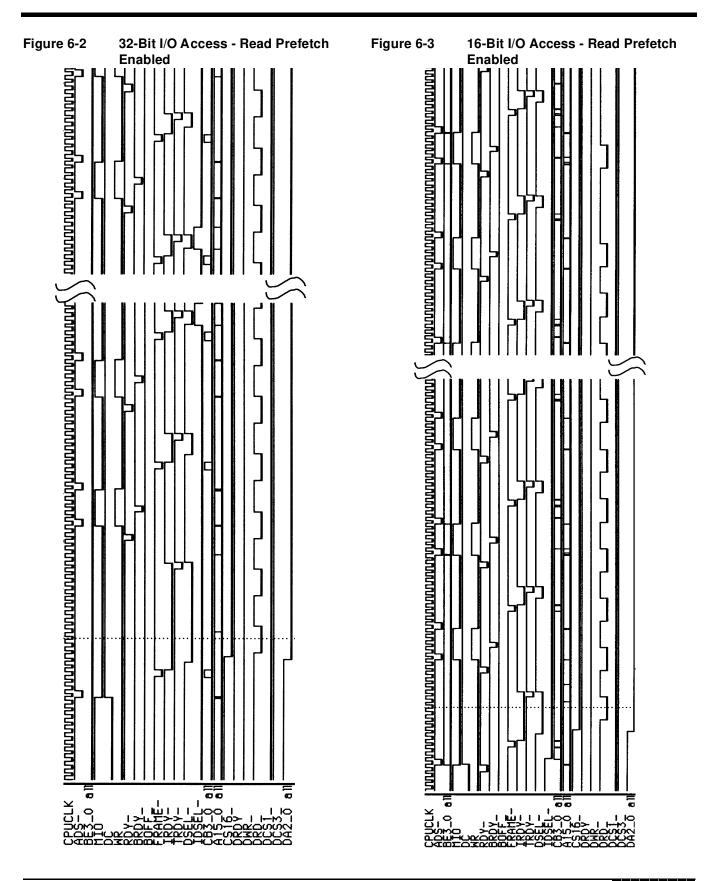




Figure 6-4 32-Bit I/O Access -Buffer Full

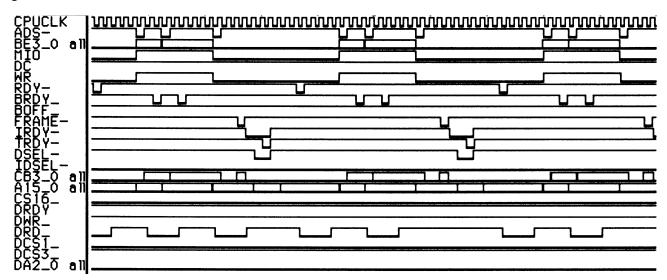
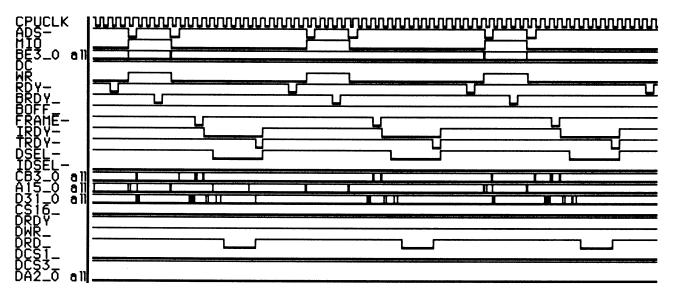


Figure 6-5 16-Bit I/O Access - No Prefetch





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Figure 6-6 32-Bit I/O Access - No Prefetch



Figure 6-7 32-Bit I/O Write

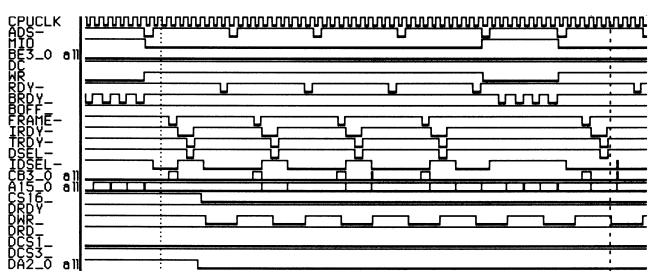




Figure 6-8 16-Bit I/O Write

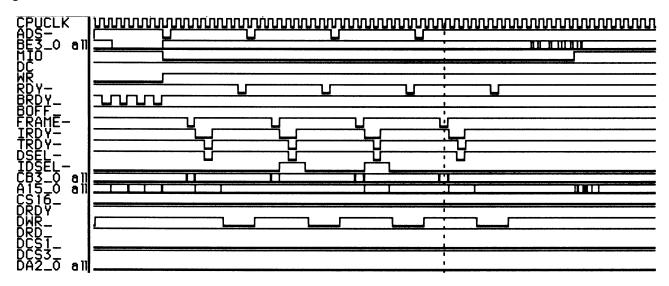
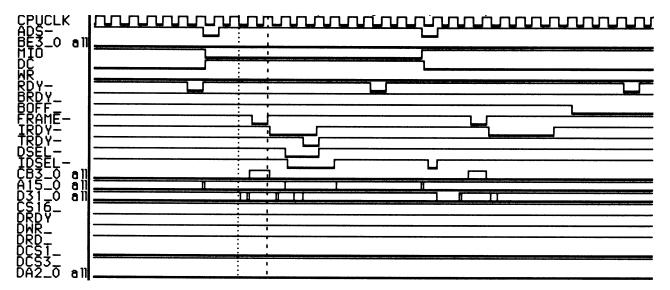


Figure 6-9 PCI Configuration Read Cycle





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Figure 6-10 PCI Configuration Write Cycle

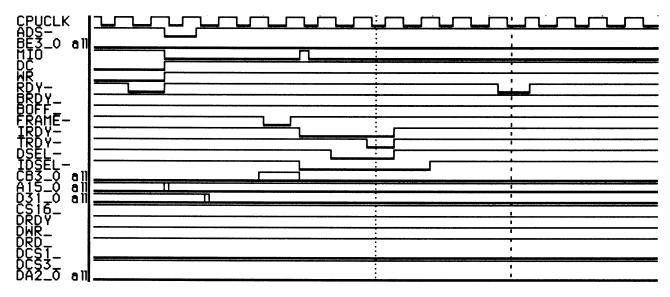
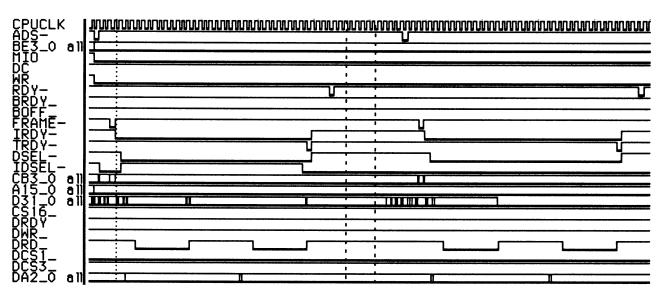
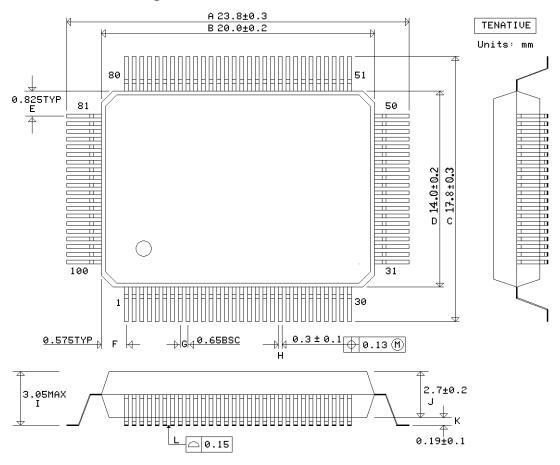


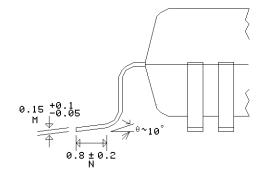
Figure 6-11 Enter 611 Register Programming Mode (Read 1F1h twice)



7.0 Mechanical Package



DIM	MILLIM	1ETERS	INC	HES	DESCRIPTION
DIII	MIN	MAX	MIN	MAX	DESCRIPTION
A	23.5	24.1	.925"	.949"	Maximum Width LEAD TO LEAD
В	19.8	20.2	.779"	.795"	Maximum Width PACKAGE ENVELOPE
С	17.5	18.1	.689"	.713"	Maximum Height LEAD TO LEAD
D	13.8	14.2	.543"	.559"	Maximum Height PACKAGE ENVELOPE
Ε	0.82	5 TYP	.0325" TYP		LEAD CENTER TO PERP. LEAD PLANE
F	0.57	5 TYP	.0226" TYP		LEAD CENTER TO PERP. LEAD PLANE
G	0.6	0.65 BSC		" BSC	LEAD TO LEAD CENTER SPACING
Н	0.2	0.4	.008" .016"		LEAD WIDTH
I	_	3.05	_	.120"	PACKAGE HEIGHT LEAD PLANE TO TOP
J	2.5	2.9	.098"	.114"	MAXIMUM THICKNESS PACKAGE ENVELOPE
К	0.09	0.29	.0035".0114"		LEAD PLANE TO PACKAGE BOTTOM
L		0.15	.006"		LEAD PLANE SKEW
М	0.1	0.25	.004"	.010"	LEAD THICKNESS
N	0.6	1.0	.024"	.039"	LEAD FOOTPRINT





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Appendix A. Accessing the BBS

The OPTi BBS offers a wide range of useful files and utilities to our customers, from Evaluation PCB Schematics to HPGL/PostScript format Databooks that you can copy directly to your laser printer. The only requirements for accessing and using the BBS is a modem and an honest response to our questionnaire.

A.1 Paging the SYSOP

Currently, Paging the SYSOP is not a valid choice for the OPTi BBS. Once a full-time SYSOP is created, then there will be hours available for paging the SYSOP and getting immediate help.

For now, you must send [C] Comments to the SYSOP with any questions or problems you are experiencing. They will be answered promptly.

Note

Each conference has its own Co-SYSOP (the application engineer responsible for that product line), so specific conference questions can be addressed that way, but general, BBS-wide, questions should be sent to the SYSOP from the [0] - Private E-Mail conference.

A.2 System Requirements

The OPTi BBS will support any PC modem up to 14,400 baud, with 8 bits, no parity, and 1 stop bit protocol. The baud rate, handshaking, and system type will automatically be detected by the OPTi BBS.

A.3 Calling In/Hours of Operation

The OPTi BBS phone number is (408) 980-9774. The BBS is on-line 24 hours a day, seven days a week. Currently there is only one line, but as traffic requires additional lines will be installed.

A.4 Logging On for the First Time

To log on to the BBS for the first time,

- 1. Call (408) 980-9774 with your modem.
- 2. Enter your first name.
- 3. Enter your last name.
- 4. Verify that you have typed your name correctly.
- 5. Select a password (write it down).
- 6. Reenter the password to verify spelling.
- 7. You must then answer the questionnaire that follows.

After you have answered the questionnaire, you are given Customer rights. To change your profile (security level, pass-

word, etc.), you must send a [C]omment to the SYSOP explaining why.

After you have logged on for the first time, each subsequent log on will bypass the questionnaire and put you directly at the bulletin request prompt. As bulletins will be added on a regular basis in the future, it is recommended that you read the new bulletins on a regular basis.

A.5 Log On Rules and Regulations

- As a FULLUSER you can download from any conference.
- You will be limited to 45 minutes per day of access time (note that once a download has started, it will finish, even if the daily time limit is exceeded). If you have not entered any keystrokes after 5 minutes, you will automatically be logged off.
- You can upload to the Customer Upload Conference¹
 only. This area is used for our customers/contacts to
 send data to OPTi. You will not be able to download any
 files from this area.

A.6 Using the BBS

This section will describe how to use the BBS on a daily basis.

The BBS is divided into Conferences that are specific to a product (for example, the Viper Desktop Chipset), or an application group (for example, the Field Application Conference is used by OPTi Field Application Engineers to send data to their contacts in the field). As a general rule, the files in the application specific areas will be for specific application and may contain a password. If a file is password protected, and you know you need that file, you must contact your OPTi sales representative for the password.

The files in the Product Conferences are released data that can be used for evaluating the OPTi product line.

To access a feature of the BBS, you should type the letter in brackets that precedes each menu item. This document places the appropriate letter in brackets whenever you are told to access a feature.

A.6.1 Reading Bulletins

The OPTi BBS will present you with a set of bulletins each time you log on that are global bulletins applying to OPTi in general. In addition to these, each Product Conference will have its own set of bulletins that apply to that product. These

^{1.} See Section A.6.5 for more information on uploading.

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bulletins will announce new product information, documentation updates, and bug fixes and product alerts.

It is recommended that you read any new bulletins on a regular basis to keep up to date on the OPTi product line.

A.6.2 Sending/Receiving Messages

The Message Menu can be used to send and receive messages from OPTi employees, or other BBS users. The Message menu can also be used to attach files for the receiver to download after they read the message. This method will be used often to send customer specific files to OPTi customers.

Messages to the SYSOP depend upon the conference you are in. Each Product Conference sends Comments and Messages to the SYSOP to the Application Engineer responsible for that conference.

A.6.3 Finding Information

To find information on the OPTi BBS, you must use the [J] Join a Conference option and then list all of the conferences available. They are arranged by product number and name.

Once you are in the correct conference, you should read all applicable bulletins and messages. Then you can [L] List all the files that are available from the File Menu.

A.6.4 Downloading Files From OPTi

The easiest way to download files from OPTi, is to [L] List the files from the File Menu, the [M] Mark and files you want from the list. After you have marked all the files you need, you can [D] Download all the marked files and then logoff automatically.

A.6.5 Uploading Files To OPTi

There are two ways to upload a file to OPTi. The first is similar to the download option. You should [J] Join the Customer Upload Conference (this is the only conference that allows

uploads from users) and [U] Upload the file to this conference.

If you are sending the file to a specific person, you should use the Message Menu to [E] Enter a new message to that person and then [A] Attach the file to the message. This way, the person receiving the message can download the file to his or her system without leaving behind a file that will not be used by anyone else on the BBS.

A.6.6 Logging Off

Once you have completed your visit to the OPTi BBS, you must say [G] Goodbye.

A.6.7 Logging Back on Again

To log back on to the BBS,

- 1. Call (408) 980-9774 with your modem.
- Enter your first name.
- 3. Enter your last name.
- 4. Verify that you have typed your name correctly.
- 5. Enter your password.

You will not have to answer the questionnaire after the initial log-on. You will also be in the conference you were in when you last logged-on.

A.7 The Menus

There are four major menus that OPTi customers will use, the Main Menu, the File Menu, the Bulletin Menu and the Message Menu.

Note

The following menus are for the Customer Profile (FULLUSER) only, if your user profile has been changed, you may see slightly different menus.

Figure A-1 The Main Menu

Figure A-2 The Bulletin Menu

```
Bulletin Menu

[1] - Sample Bulletin 1 Title

[2] - Sample Bulletin 2 Title

Bulletins updated: NONE
Enter bulletin # [1..3], [R]elist menu, [N]ew, [ENTER] to quit? []
```

Figure A-3 The File Menu

Figure A-4 The Message Menu

A.7.1 Menu Selections

- [B] Bulletin MenuMenu(s): main Access the Bulletin Menu.
- [C] Check for personal mailMenu(s): message See if you have any mail.
- [C] Comments to the sysopMenu(s): main Leave a private comment for the SYSOP.
- [D] Download a file(s)Menu(s): file
 Download a file from the BBS to your computer. If you
 have marked files it will display these files. If you have
 not marked any files, it will ask you for a file name. The
 file must be present in the current conference for you to
 be able to enter its name.
- [E] Edit Marked ListMenu(s): file
 Change the entries that you have selected as Marked for
 downloading.
- [E] Enter a new messageMenu(s): message Send a new message to someone on the BBS.
- [F] File MenuMenu(s): main, message Access the File Menu.
- [G] Goodbye and logoffMenu(s): main, message, file Logoff the system.
- [J] Join a ConferenceMenu(s): main, message, file Change conferences (product areas).
- [K] Kill a messageMenu(s): message Delete a message.

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- [L] List available filesMenu(s): file
 List the files in the current conference. Note that most
 conferences have sub-categories of files (Schematics,
 JOB, etc.) that you will be asked for (or you can press
 enter the list all of the categories).
- [M] Message MenuMenu(s): main, file Access the Message Menu.
- [Q] Quit to Main MenuMenu(s): message, file Leave current menu and return to the Main Menu.
- [R] Read MessagesMenu(s): message
 Read messages in the current conference or all conferences.
- [S] Scan for FilesMenu(s): file
 Scan for particular files (by name, or extension, etc.).

- [S] Scan messagesMenu(s): message
 Search for message by specific qualifier (date, sender etc.).
- [U] Upload a file(s)Menu(s): file
 Send a file from your computer to OPTi. This can only be done in the Customer Upload Conference.
- [U] Userlog ListMenu(s): main
 Lists the user database, in order of logon. This is useful if
 you are sending a message and are looking for the spell ing of a persons name.
- [Y] Your settingsMenu(s): main
 Show you settings and allow you to make changes.
 These include password, name, address, etc.



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