# ABLE DH/DM <br> PRELIMINARY <br> USER'S GUIDE 

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## PREM

We apologize that our User's Guide for the DH/DM is not yet available. This document should answer most of your questions about the product. We will send a final User's Guide to you as soon as they are available.

## ABLE COMPUTER

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## Section 1

## How to Use This Manual

Congratulations on your purchase of a DH/DM from ABLE COMPUTER. We are sure it will provide you with years of satisfactory service. We have prepared this manual to help you maximize the effectiveness of the DH/DM in your system.

This manual is provided to assist you with the installation, use and care of $D H / D M$; it does not provide repair information. If you have problems with your DH/DM, we prefer that you let us repair it in our factory.

This manual assumes that you are familiar with the PDP-1l architecture and Unibus structure. For information about the PDP-ll, refer to the following DEC documents:

- PDP-ll Processor Handbook
- PDP-ll Peripherals Handbook
- PDP-ll Terminals and Communications Handbook

This manual is organized into the following sections:

- Section 2 provides a general description of $D H / D M$ and lists its special features. It also includes programmable line parameter information, electrical specifications, and physical specifcations. Photographs of the $\mathrm{DH} / \mathrm{DM}$ are included in this section.
- Section 3 gives a brief installation procedure, followed by detailed instructions on installation. It describes the functions of all switches on the board and tells how to set them -- address selection, vector selection, baud rate, and miscellaneous functions contained on switch S4. It provides information on maintenance features, including the microdiagnostics. This section includes information on how to prepare the system for installation, install the DH/DM, run the diagnostics, and verify installation.
- Section 4 contains information on the care of DH/DM and troubleshooting tips in the event that a problem occurs. It also tells who to contact and how to contact them for service.
- Section 5 describes a typical application for DH/DM. It provides terminal/ communications information, wiring information for modem connection, and Unibus connector information.
- Section 6 contains descriptions of data handling registers, modem registers, timing considerations for transmitter/receiver speed programming, break control, and transmitter and receiver timing. It also includes maintenance mode considerations.
- Appendix A provides an interrupt level strapping chart to alter the priority level of $\mathrm{DH} / \mathrm{DM}$.


### 2.1 GENERAL DESCRIPTION

The DH/DM is a microprocessor-based controller which connects a Unibus system to 16 asynchronous communications lines. It provides DMA (direct memory access) output capabilities and modem control. It is system software compatible with the DEC DHIl and DM1l-BB.

A basic DH/DM consists of a hex-width board, EIA distribution panel, and interconnecting cables. The DH/DM can be installed in any standard DEC DDll peripheral mounting panel. See Figures 2-1, 2-2, and 2-3.

### 2.2 FEATURES

- The DH/DM requires only one hex slot rather than the dedicated nine-slot backplane used by the DHll.
- The DMA output capability frees the processor from transmit-character request interrupt handling.
- By accessing words rather than bytes, the DH/DM provides double the DHll data transfer rate capability and cuts Unibus time in half.
- On-board clock provides a non-standard baud rate source eliminating a possible requirement for a separate clock card.
- Isolation from terminals in loopback maintenance mode eliminates unwanted printouts.
- Supports all standard DHll baud rates, plus 19.2 K baud.
- Diagnostic loopback connectors are built-in to provide ease of use.
- On-board address and vector selection switches eliminate the need for jumpers and add flexibility.


## TO BE SUPPLIED.

Figure 2-1: DH/DM PC Board Model 10103-1

TO BE SUPPLIED.

Figure 2-2: DH/DM EIA Distribution Panel

TO BE SUPPLIED.
Figure 2-3: DH/DM System Moतel 10100-1

### 2.3.1 PROGRAMMABLE LINE PARAMETERS

Character Length: 5, 6, 7, or 8 data bits
Number of Stop Bits: 1 or 2 for 6-, 7-, or 8 -bit characters; 1 or 1.5 for 5 -bit characters

Parity Generation/Detection: Odd, even, or none
Operating Modes: Full duplex
Transmitter/Receiver Speeds (Baud): 0, 50, 75, 110, 134.5, 150, 200, 300, 600, 1200, 1800, 2400, 4800, 9600, 19.2K, on'board external clock

### 2.3.2 ELECTRICAL SPECIFICATIONS

Bus Loading: The DH/DM presents one unit load to the Unibus.
Power Requirements: $4.4 \mathrm{amps} @+5 \mathrm{~V}$
$0.2 \mathrm{amps} @+15 \mathrm{~V}$
0.2 amps @ -15 V

Bus Request Level: Individually selectable for receive, transmit, and modem control at levels BR4, BR5, BR6, or BR7.

Device Addresses: The DH/DM requires eight consecutive word addresses in the floating address space which starts at 760010. All DH/DM units in a system should have consecutive word addresses.

The modem control requires two consecutive word addresses, the first of which must be a multiple of four. Floating address space has been assigned for 16 boards. The first is at 770500 ; the second starts at 770510 , and so forth.

Interrupt Vectors: DH/DM requires three consecutive interrupt vectors, XX0 for the receiver, XX4 for the transmitter, and XXX for the modem. These are in the floating vector space (000-774).

### 2.3.3 PHYSICAL SPECIFICATIONS

| Board Size: | The DH/DM is a standard hex-width board. <br> Rectangular dimensions are 15.69 x 8.4 inches. <br> Distribution Panel |
| :--- | :--- |
| The board is shown in Figure $2-1$. |  |

# Section 3 <br> How to Install DH/DM 

### 3.1 INSTALLATION PROCEDURE

Section 3 provides a detailed description of the procedure to follow when installing a DH/DM. Below is a brief step-by-step description of the entire installation procedure.

1. Determine the address assignment of the $D H$ portion and set switch S 2 accordingly (Section 3.5 and Section 3.6.1).
2. Determine the address assignment of the DM portion and set switch Sl accordingly (Section 3.5 and Section 3.6.2).
3. Determine the vector assignment of the $D H$ portion and set switch $S 5$ accordingly (Section 3.5 and Section 3.6.3).
4. Determine the vector assignment of the DM portion and set switch S 6 accordingly (Section 3.5 and Section 3.6.4).
5. Select the desired external Bbaud rate and set the switches (Section 3.7.1).
6. Refer to Table 3-9 for switch $S 4$ functions and set switch accordingly (Section 3.7.2).
7. Set maintenance switches to achieve the desired functions (Section 3.8.1).
8. If interrupt levels other than the ones factory set are required, modify the jumper connections (Section 3.9).
9. Remove power from the system (Section 3.10).
10. Locate a vacant hex slot and modify it for $D H / D M$ by removing the wire between pins CAl and CBl of the slot (Section 3.10).
11. Install DH/DM board in vacant slot (Section 3.11.1).
12. Install the EIA panel (Section 3.11.2).
13. Install the cables (Section 3.11.3).
14. Apply power to the system, checking the LEDs to verify internal operation of the board (Section 3.13).
15. Install EIA panel cables into maintenance connectors and run diagnostics (Section 3.13).

### 3.2 UNPACKING THE DH/DM

The DH/DM is shipped in special containers to prevent damage during shipment. It is recommended that these containers be saved for use in the event that the product requires subsequent reshipment. Unpack the contents carefully and inspect for any signs of damage. If damage is found, notify the carrier immediately.

### 3.3 VFRIFY THAT YOU RECEIVED WHAT YOU ORDFRED

Be sure that you received what you ordered by checking the board, panel, and cable numbers. The board number is 10103 and is found on the back side of the board in the upper right corner. The EIA panel is numbered loll4. The cables are numbered 90000186. See Figure 2-1, 2-2, and 2-3.

### 3.4 EQUIPMENT NEEDED TO USE THE DH/DM

You will need the following equipment to use the DH/DM:

- PDP-ll Unibus computer system
- One vacant hex SPC slot four mounting the DH/DM
- Panel mounting space (6 inches high) for the distribution panel
- One to 16 terminal devices with appropriate modems or null modems and interconnecting cables.


### 3.5 HOW TO DETERMINE ADDRESS AND VF:CTOR ASSIGNMENTS

The DH portion of the DH/DM uses eight words of floating address space. The floating address space begins at 760010 as shown in Figure 3-2. Addresses within this space are assigned according to rank. Table 3-1 shows the ranks assigned to devices addressed in this range.

The DH uses addresses located after any DJll's in the system. Each DH requires eight consecutive addresses starting with an address that is a multiple of 20 (octal). For example, for a system with no DJll units, register address assignments for three DH/DM units would be as follows:

| Unit | Octal Register Addresses |
| :--- | ---: |
| 1st DH/DM | $760020-760036$ |
| 2nd DH/DM | $7600 \Delta 0-760056$ |
| 3rd DH/DM | $760060-760076$ |



Figure 3-1: DH/DM Board Layout


Figure 3-2: Address Map

Notice that, although the system in this example contains no DJll units, address 760010 cannot be assigned to the first DH/DM unit because it is not a multiple of 20 (octal).

| Rank | Unibus Device |
| :---: | :---: |
| 1 | DJIl |
| 2 | DHIll |
| 2 | DH/DM |
| 3 | DQll |
| 4 | DUll |
| 5 | DPUll |
| 6 | LKllA |
| 7 | DMCll |
| 8 | DZll |
| 9 | KMCll |
| 10 | RLIl (extra) |

Table 3-1: Device Panks for Floating Address Assignment

The DM portion of the $D H / D M$ requires two additional consecutive word addresses. The addresses assigned to the registers of the first DM in a system are 770500 and 770502. The addresses for additional DM registers start at consecutive addresses which are multiples of 10 (octal). Thus, the addresses for a second DM are 770510 and 770512 ; those for a third DM/l6 board are 770520 and 770522 ; and so on.

The DH uses two interrupt vectors (for the receiver and transmitter interrupts). The $D M$ uses one interrupt vector. Vector addresses for all devices are assigned in order from 300 through 774 according to the DEC rankings listed in Table 3-2. Find the device in your system with the lowest rank number and assign this 320 , etc. Next find the device with the second lowest rank number and assign it the next consecutive vector address. Continue until all vector addresses are assigned. If a device is added to an existing system, its vector address must be inserted at the normal position and all other device addresses incremented accordingly. Table 3-3 shows the sample vector addresses for the DH/DM.


Table 3-2: Floating Interrupt Vector Devices

| Device | Channels | Vector |
| :--- | :---: | :---: | :---: |

Täble 3-3: Typical Vector Addresses

### 3.6 HOW TO SET THE DEVICE ADDRESS AND VECTOR SELECTION SWITCHES

### 3.6.1 DH DEVICE ADDRESS SWITCH (S2)

Device addresses for the $D H$ portion of the DH/DM are set using switch 52 . Refer to Figure 3-1 for the location of switch 52 and Figure 3-3 for switch descriptions. Use Table $3-4$ to determine the device address switch settings. The starting address can be determined by referring to the information in Section 3.5.

NOTE: An open switch is accomplished by pressing the side of the switch marked "OPEN."

### 3.6.2 DM DEVICE ADDRESS SWITCH (SI)

Device addresses for the DM portion of the DH/DM are set using switch Sl on the board. Refer to Figure 3-1 for the location of switch Sl and Figure 3-3 for switch descriptions. Use Table 3-5 to determine the device address switch settings. The starting address can be determined by referring to the information in Section 3.5.

### 3.6.3 DH VECTOR ADDRESS SWITCH (S5)

Vector addresses for the $D H$ portion of the $D H / D M$ are set using switch $S 5$ on the board. Refer to Figure 3-1 for the location of switch $S 5$ and Figure 3-3 for switch descriptions. Use Table 3-6 to determine the vector address switch settings. To determine the desired vector addresses refer to Section 3.5.
3.6.4 DH VECTOR ADDRESS SWITCH (S6)

Vector addresses for the DM portion of the DH/DM are set using switch S6. Refer to Figure 3-1 for the location of switch 56 on the board and Figure 3-3 for switch descriptions. Use Table 3-7 to determine the vector address switch settings. Section 3.5 describes how to determine the desired vector addresses.


| SWITCH S5 |  |  |
| :---: | :---: | :---: |
| 1 | $\square$ | Microdiagnostic |
| 2 | [ | Microdiagnostic |
| 3 |  | vector Bit 03 |
| 4 | $\square$ | Vector Bit 04 |
| 5 |  | Vector Bit 05 |
| 6 |  | Vector Bit 06 |
| 7 | $\square$ | Vector Bit 07 |
| 8 | $\square$ | vector Bit 08 |



Figure 3-3: DH/DM Switch Descriptions

"-" = Open; "C" = Closed

| DH <br> STARTING <br> ADDRESS | SWITCH 2 POSITIONS |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | 8 | 7 | 6 | 5 | 4 | 3 | 7. | 1 |
| 762720 | - | C | - | - | - | C | - | C |
| 762740 | - | C | - | - | - | - | C | C |
| 762760 | - | C | - | - | - | - | - | C |
| 763000 | - | - | C | C | C | C | C | C |
| 763020 | - | - | C | C | C | C | - | C |
| 763040 | - | - | C | C | C | - | C | C |
| 763060 | - | - | C | C | C | - | - | C |
| 763100 | - | - | C | C | - | C | C | C |
| 763120 | - | - | C | C | - | C | - | C |
| 763140 | - | - | C | C | - | - | C | C |
| 763160 | - | - | C | C | - | - | - | C |
| 763200 | - | - | C | - | C | C | C | C |
| 763220 | - | - | C | - | C | C | - | C |
| 763240 | - | - | C' | - | C | - | C | C |
| 763250 | - | - | C | - | C | - | - | C |
| 763300 | - | - | C | - | - | C | C | C |
| 763320 | - | - | C | - | - | C | - | C |
| 763340 | - | - | C | - | - | - | C | C |
| 763360 | - | - | C | - | - | - | - | C |
| 763400 | - | - | - | C | C | C | C | C |
| 763420 | - | - | - | C | C | C | - | C |
| 763440 | - | - | - | C | C | - | C | C |
| 763460 | - | - | - | C | C | - | - | C |
| 763500 | - | - | - | C | - | C | C | C |
| 763520 | - | - | - | C | - | C | - | C |
| 763540 | - | - | - | C | - | - | C | C |
| 763560 | - | - | - | C | - | - | - | C |
| 763600 | - | - | - | - | C | C | C | C |
| 763620 | - | - | - | - | C | C | - | C |
| 763640 | - | - | - | - | C | - | C | C |
| 763650 | - | - | - | - | C | - | - | C |
| 763700 | - | - | - | - | - | C | C | C |
| 763720 | - | - | - | - | - | C | - | C |
| 763740 | - | - | - | - | - | - | C | C |
| 763760 | - | - | - | - | - | - | - | C |

Table 3-4: DH Device Address Switch Settings (con't.)

|  | DM STARTING ADDRESS | SWITCH 1 POSITION |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 |
| $\checkmark$ | 770400 | C | C | C | C | C | C | C | C |
|  | 770410 | C | C | C | C | C | C | - | C |
|  | 770420 | C | C | C | C | C | - | C | C |
|  | 770430 | C | C | C | C | C | - | - | C |
|  | 770440 | C | C | C | C | - | C | C | C |
|  | 770450 | C | C | C | C | - | C | - | C |
|  | 770460 | C | C | C | C | - | - | C | C |
|  | 770470 | C | C | C | C | - | - | - | C |
| HST - | 770500 | C | C | C | - | C | C | C | C |
|  | 770510 | C | C | C | - | C | C | - | C |
|  | 770520 | C | C | C | - | C | - | C | C |
|  | 770530 | C | C | C | - | C | - | - | C |
|  | 770540 | C | C | C | - | - | C | C | C |
|  | 770550 | C | C | C | - | - | C | - | C |
|  | 770560 | C | C | C | - | - | - | C | C |
|  | 770570 | C | C | C | - | - | - | - | C |
|  | 770600 | C | C | - | C | C | C | C | C |
|  | 770610 | C | C | - | C | C | C | - | C |
|  | 770620 | C | C | - | C | C | - | C | C |
|  | 770630 | C | C | - | C | C | - | - | C |
|  | 770640 | C | C | - | C | - | C | C | C |
|  | 770650 | C | C | - | C | - | C | - | C |
|  | 770660 | C | C | - | C | - | - | C | C |
|  | 770670 | C | C | - | C | - | - | - | C |
|  | 770700 | C | C | - | - | C | C | C | C |
|  | 770710 | C | C | - | - | C | C | - | C |
|  | 770720 | C | C | - | - | C | - | C | C |
|  | 770730 | C | C | - | - | C | - | - | C |
|  | 770740 | C | C | - | - | - | C | C | C |
|  | 770750 | C | C | - | - | - | C | - | C |
|  | 770760 | C | C | - | - | - | - | C | C |
|  | 770770 | C | C | - | - | - | - | - | C |

Table 3-5: DM Device Address Switch Settings

| DH VECTOR |  | SWITCH 5 POSITION |  |  |  |  |  | DH VECTOR |  | SWITCH 5 POSITION |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| RECEIVE | TRANSMIT | 8 | 7 | 6 | 5 | 4 | 3 | RECEIVE | TRANSMIT | 8 | 7 | 6 | 5 | 4 |
| 000 | 004 | - | - | - | - | - | - | 400 | 404 | c | - |  | - |  |
| 010 | 014 |  | - | - | - | - | C | 4 F 0 | 414 |  | - | - | - | - |
| 020 | 024 |  | - | - | - | c | - | 420 | 424 | C | - | - | - | C |
| 030 | 034 |  | - | - | - | c | C | 430 | 434 | C | - | - | C | C |
| 040 | 044 |  | - | - | C | - | - | 440 | 444 | C | - | - |  | - |
| 050 | 054 |  | - | - | c | - | C | 450 | 454 | C | - | - | C | - |
| 060 | 064 |  | - | - | C | C | C | 460 | 464 |  |  | - |  | C |
| 070 | 074 | - | - | - | C | C | C | 470 | 474 504 | C | - | - | - | c |
| 100 | 104 |  | - | C | - | - | C | 500 510 | 504 | C | - | C | - | - |
| 110 120 | 114 | - | - | C | - | - | $\stackrel{C}{\text { C }}$ | 510 520 | 514 524 | C | - | C | - | C |
| 130 | 134 | - | - | c | - | c | C | 530 | 534 | c | - | c | - | C |
| 140 | 144 | - | - | C | C | - | - | 540 | 544 | C | - | C | C | - |
| 150 | 154 | - | - | C | C | - | C | 550 | 554 | C | - | C | C | - |
| 160 | 164 |  | - | c | C | C | - | 560 | 564 | C |  | C | C | C |
| 170 | 174 | - | - | C | C | C | C | 570 | 574 | C | - | C | C | C |
| 200 | 204 | - | C | - | - | - | - | 600 | 604 |  |  | - |  | - |
| 210 | 214 | - | C | - | - | - | C | 610 | 614 | C |  | - |  | - |
| 220 | 224 | - | C | - | - | C | C | 620 | 624 | C |  | - |  | C |
| 230 | 234 | - |  |  |  | C | C | 630 | 634 644 | C |  | - | - | - |
| 240 250 | 244 254 | - | C | - | C | - | - | 640 650 | 644 654 | C |  | - | c | - |
| 260 | 264 | - | C | - | C | C | - | 660 | 664 | c | C | - | c | c |
| 270 | 274 | - | c | - | C | C | C | 670 | 674 | c | C |  | C | C |
| 300 | 304 | - | C | C | - | - | - | 700 | 704 | c | C | C |  |  |
| 310 | 314 |  | c | c | - | - | C | 710 | 714 | c | C | c | - | - |
| 320 | 324 | - | c | C | - | C | - | 720 | 724 | C | C | C | - | C |
| 330 | 334 | - | C | C | - | C | C | 730 | 734 |  |  | C | - | C |
| 340 | 344 |  | C | C | C | - | - | 740 | 744 |  |  | $\begin{aligned} & \mathrm{C} \\ & \mathrm{C} \end{aligned}$ |  | - |
| 350 360 3 | 354 | - | C | C | C | - | C | 750 760 | 754 764 | C | C | C | C | - |
| 360 370 | 364 374 | - | C | C | C | C | - | 760 770 | 764 774 |  | C | c | C | c |

Table 3-6: DH Vector Address Switch Settings

|  | SWITCH 6 <br> POSITION |  | SWITCH 6 <br> POSITION |  | SWITCH 6 POSITION |
| :---: | :---: | :---: | :---: | :---: | :---: |
| DM VECTOR | 8765432 | DM VECTOR | 8765432 | DM VECTOR | 8765432 |
| 000 | - - - - - | 254 | - c-c-c c | 530 | C-C-C C- |
| 004 | - - - C | 260 | - C-C C- | 534 | $\mathrm{C}-\mathrm{C}-\mathrm{C}$ C C |
| 010 | - - - c | 264 | - C-C C-C | 540 | C-C C-- |
| 014 | - - - - c c | 270 | - C- C C C - | 544 | C-C C-- C |
| 020 | C | 274 | - C-C C C C | 550 |  |
| 024 | - - c-c | 300 | - C C - - - | 554 | C-C C-C C |
| 030 | - - C C - | 304 | - C C - - - C | 560 |  |
| 034 | - - c c c | 310 | - c c - - c - | 564 |  |
| 040 | - C - | 314 | - C C - - C C | 570 |  |
| 044 | - - c--c | 320 | - C C - C - | 574 | C-C C C c c |
| 050 | - - c - C - | 324 | - c c - c-c | 600 | C C - - - - |
| 054 | - - c-c c | 330 | - C C - C C - | 604 | C C - - - C |
| 060 | - - c C - | 334 | - C C - c c c | 610 | C--- C- |
| 064 | - - c c- C | 340 | - С С C - - | 614 | C C-- - c c |
| 070 | - - c c c - | 344 | - C C C - - C | 620 | C C - - C-- |
| 074 | - - c c c c | 350 | - C C C- C- | 624 | C C - - C- ${ }_{\text {c }}$ |
| 100 | - C - | 354 | - C C C-C C | 630 | C-- c c - - |
| 104 | - C - - - C | 350 | - c C C C - - | 634 | С C-- C C C |
| 110 | - C - - c - | 354 | - c C C C - C | 640 | C C-C-- - |
| 114 | - - c--c c | 370 | - c c c c c - | 644 | C C - C-- C |
| 120 | - C - C - | 374 | - c c c c c c | 650 | $\mathrm{C}^{\text {C }}$ - C- $-\mathrm{C}-$ |
| 124 | - C - c - c | 400 | C - - - - | 654 | C C - C-C C |
| 130 | - C - C C - | 404 | C - - - - C | 660 | C C-C C- - |
| 134 | - - c - c c c | 410 | C - - - C - | 664 | C C-C C- ${ }_{\text {c }}$ |
| 140 | - - C C - | 114 | C- - - c c | 670 | C C - C C C C - C C- C C C C |
| 144 | - c c - - c | 420 | C - - - c-- | 674 | C C - C C C C C C C - - |
| 150 | - - c C-C - | 424 | C-- - C-C | 700 |  |
| 154 | - - c c-c c | 430 | C--- C C - | 704 | С С С - - - ${ }_{\text {c }}$ |
| 160 | - c c c - - | 434 | C-- - c c c | 710 |  |
| 164 | - c c c - c | 440-4S | C-- c-- | 714 | C C C C - - C C C c |
| 170 | - - C C C C | 444 | C-- c - - c | 720 |  |
| 174 | - - c C C C C | 450 | C-- C-C - | 724 |  |
| 200 | - C - - - | 454 | c--c-c c | 730 | C C C - C C - |
| 204 | - c--- - c | 450 | C - - c - - | 734 |  |
| 210 | - C - - - C | 454 | C-- c C - C | 740 |  |
| 214 | - C - - c c | 470 | C-- C C C - | 744 |  |
| 220 | - C-- C-- $-\mathrm{c}-\mathrm{c}-\mathrm{c}$ | 474 500 |  | 750 754 |  |
| 224 230 | - c--c-c - c-- -c - | 500 504 | C-C- -C $\mathrm{c}-\mathrm{c}-\mathrm{-}$ c | 754 760 |  |
| 234 | - c--c c c | 510 | C- c- - c- | 764 |  |
| 240 | - C - C-- | 514 | C-C--c C | 770 | С С С С С C - |
| 244 | - c-c--c | 520 | C-C-C- | 774 | C C C C C C C |
| 250 | - C-C-C | 524 | C-C-C-C |  |  |

"-" = Open; "C" = Closed
Table 3-7: DM Vector Address Switch Settings

### 3.7 OPTION SWITCHES

### 3.7.1 EXTERNAL B BAUD RATE SELECTION (S3, S4-Position 1)

The External B baud rate for the DH/DM is set using switch S 3 and switch S 4 , position l. Table 3-8 below lists switch settings for baud rate selection. If the rate you desire is not listed in the table, find the low and high rate it falls between. Use the switch setting for the lower of the two rates. For example, if the baud rate you require is 646 , it falls between speeds 645.2 and 647.9 on the table. The switches would be set according to the lower speed, or 645.2.

### 3.7.2 MISCELLANEOUS FUNCTIONS

Switch S4 contains a variety of functions for the DH/DM. Table 3-9 lists these functions.

| $\begin{aligned} & \text { SWITCH S4 } \\ & \text { POSITION } \end{aligned}$ | OPEN/CLOSED | FUNCTIONAL DESCRIPTION |
| :---: | :---: | :---: |
| 1 | $X \quad C$ | This switch is used in setting the baud rate. Refer to Section 3.7.1. |
| 2 | Closed | A closed switch will assert Data Terminal Ready on all lines. |
| 2 | Open | An open switch allows Data Terminal Ready to be controlled by the DM. |
| 3 | Open | This switch is reserved for future use. It should remain open at all times. |
| 4 | Open | This switch is reserved for future use. It should remain open at all times. |
| 5 | Open | This switch is reserved for future use. It should remain open at all times. |
| 6 |  |  |
| 7 |  |  |
| 8 | Open | This switch should normally be set open. It enables the cable maintenance mode. |
| 8 | closed | When closed, this switch disables cable maintenance mode so that the diagnostic cannot be run. |

Table 3-9: Switch S4 Functions


Table 3-8: Baud Rate Switch Settings

| 54 | 53 |  |  |  |  |  |  |  |  | 54 |  |  |  |  | S3 |  |  |  | Low rate |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 1 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | Low rate | 1 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 |  |
| C | 0 | C | C | 0 | C | C | C | 0 | 270:3 | c | C | 0 | C | 0 | 0 | C | $\square$ | C | 432. 8 |
| C | 0 | c | C | 0 | C | C | C | C | 272. 2 | c | C | 0 | c | 0 | 0 | C | C | 0 | 437.6 |
| C | 0 | C | C | C | 0 | 0 | 0 | 0 | 274. 1 | C | C | 0 | C | 0 | 0 | C | C | C | 442. 5 |
| C | 0 | C | C | C | 0 | 0 | - | C | 276. 0 | c | C | 0 | C | 0 | C | 0 | 0 | 0 | 447.5 |
| C | 0 | C | C | C | 0 | 0 | C | 0 | 277.9 | C | C | 0 | C | 0 | C | 0 | 0 | C | 452.6 |
| c | 0 | c | c | C | 0 | 0 | c | C | 279.9 | c | C | 0 | c | 0 | C | 0 | C | 0 | 457. B |
| C | 0 | C | C | C | 0 | C | 0 | 0 | 281.9 | C | C | 0 | c | 0 | C | 0 | C | C | 463. 2 |
| C | 0 | C | C | C | 0 | C | 0 | C | 283. 9 | c | C | 0 | c | 0 | c | C | 0 | - | 468. 7 |
| C | 0 | C | C | C | 0 | $C$ | C | 0 | 285. 9 | c | C | 0 | c | 0 | C | C | 0 | C | 474. 3 |
| C | 0 | C | C | C | 0 C | C | C | C | 288. 0 | c | c | 0 | C | 0 | C | C | C | 0 | 480. 0 |
| C | 0 | C | C | C | C | 0 | 0 | 0 | 290. 1 | C | c | 0 | c | 0 | C | C | C | C | 485. 9 |
| C | 0 | c | c | C | $C$ | 0 | 0 | c | 292. 3 | C | c | 0 | c | C | 0 | 0 | 0 | $\square$ | 491. 9 |
| C | 0 | C | C | C | c | $\square$ | C | 0 | 294.4 | c | c | 0 | c | c | 0 | 0 | 0 | C | 498. 1 |
| C | 0 | C | C | C | c | 0 | C | C | 296. 6 | C | c | 0 | c | C | 0 | 0 | C | - | 504. 5 |
| C | 0 | C | C | C | C | C | 0 | 0 | 298. 9 | c | c | 0 | c | c | 0 | 0 | c | C | 511.0 |
| C | 0 | C | C | C | C | C | 0 | C | 301.1 | c | c | 0 | $c$ | c | - | C | 0 | 0 | 517.7 |
| C | 0 | C | C | C | $C$ | C | C | 0 | 303.5 | c | c | 0 | c | C | 0 | C | 0 | C | 524.5 |
| C | 0 | C | C | C | C | C | C | c | 305. 8 | C | C | 0 | c | C | 0 | C | C | 0 | 531.6 |
| C | C | 0 | 0 | 0 | 0 | 00 | 0 | 0 | 308. 2 | c | C | 0 | c | c | 0 | C | C | C | 538.8 |
| C | C | 0 | 0 | 0 | 00 | 0 | 0 | c | 310.6 | c | c | 0 | C | c | C | 0 | 0 | 0 | 546. 2 |
| C | C | 0 | 0 | 0 | 0 | 0 | C | 0 | 313.0 | c | C | 0 | c | C | C | 0 | 0 | C | 553. 9 |
| C | C | 0 | 0 | 0 | 00 | 0 | c | C | 315.5 | C | C | 0 | C | C | C | 0 | c | 0 | 561.7 |
| C | C | 0 | 0 | 0 | 0 C | C | $\square$ | 0 | 318. 1 | c | c | 0 | c | c | C | 0 | c | C | 569. 8 |
| C | C | 0 | 0 | 0 | $\square$ | C | $\square$ | c | 320. 7 | c | c | 0 | c | c | C | C | 0 | - | 578. 1 |
| C | C | 0 | 0 | 0 | 0 C | C | c | 0 | 323. 3 | c | C | 0 | c | C | C | C | - | C | 586. 7 |
| C | c | 0 | 0 | 0 | $\square$ | C | c | c | 325.9 | c | c | 0 | c | c | C | C | $c$ | $\square$ | 595. 5 |
| C | C | 0 | 0 | 0 | C | 0 | 0 | 0 | 328.6 | C | C | 0 | c | C | C | C | c | C | 604.6 |
| C | C | 0 | 0 | 0 | $C$ | 00 | 0 | c | 331.4 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 614.0 |
| C | C | 0 | 0 | 0 | C 0 | - | C | $\square$ | 334. 2 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | C | 620.0 |
| C | C | 0 | 0 | 0 | C 0 | 0. | c | c | 337.0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | C | 0 | 622.4 |
| C | C | - | 0 | 0 | C | C 0 | 0 | 0 | 339.9 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | c | C | 624. 9 |
| c | C | 0 | 0 | - | $\bigcirc$ | C | $\square$ | C | 342. 9 | 0 | 0 | 0 | 0 | 0 | - | c | 0 | 0 | 627.3 |
| C | C | 0 | 0 | - | $c$ | c 6 | $c$ | 0 | 345.9 | 0 | 0 | 0 | 0 | 0 | - | c | 0 | C | 629. 8 |
| c | c | 0 | $\bigcirc$ | 0 | C 0 | $C$ | c | c | 349.9 | 0 | 0 | 0 | 0 | 0 | 0 | C | C | 0 | 632. 3 |
| c | C | 0 | 0 | c | 00 | 00 | c | O | 352. 0 | 0 | 0 | 0 | 0 | 0 | 0 | C | C | c | 634. 9 |
| c | C | 0 | 0 | C | $\bigcirc$ | 0 | - | C | 355. 2 | - | 0 | 0 | 0 | 0 | C | 0 | 0 | 0 | 637.4 |
| C | C | 0 | 0 | C | 0 | 0 C | C | 0 | 358. 4 | 0 | 0 | 0 | 0 | 0 | c | 0 | $\bigcirc$ | C | 640.0 |
| C | C | 0 | 0 | C | 0 | 0 | C | C | 361.7 | 0 | 0 | 0 | 0 | 0 | C | 0 | c | 0 | 642.6 |
| C | C | 0 | 0 | c | 0 C | C | 0 | 0 | 365. 0 | 0 | 0 | 0 | 0 | 0 | C | 0 | c | C | 645. 2 |
| C | C | 0 | 0 | C | 0 C | $C$ | 0 | C | 368.4 | 0 | 0 | 0 | 0 | 0 | C | C | 0 | 0 | 647.9 |
| C | C | 0 | 0 | c | $\square \mathrm{C}$ | C | C | 0 | 371.8 | 0 | 0 | 0 | 0 | 0 | C | C | 0 | C | 650.5 |
| C | C | 0 | 0 | C | 0 C | C | C | C | 375.4 | 0 | 0 | 0 | 0 | 0 | c | C | C | 0 | 653. 2 |
| C | C | 0 | - | C | $C$ | 0 | 0 | 0 | 379. 0 | 0 | 0 | 0 | 0 | 0 | C | C | C | C | 655.9 |
| C | C | 0 | 0 | C | $C$ O | 0 | 0 | c | 382. 6 | 0 | 0 | 0 | 0 | c | 0 | 0 | 0 | 0 | 658. 6 |
| C | C | 0 | 0 | c | $C$ O | 0 O | C | 0 | 386. 4 | 0 | 0 | 0 | 0 | C | 0 | $\square$ | 0 | C | 661.4 |
| C | C | 0 | 0 | C | $C$ | 0 O | c | C | 390. 2 | 0 | 0 | 0 | 0 | C | 0 | 0 | c | 0 | 664. 2 |
| C | C | 0 | 0 | c | $C$ | C 0 | 0 | $\square$ | 394. 0 | 0 | 0 | 0 | 0 | C | 0 | 0 | C | C | 667.0 |
| c | C | 0 | 0 | C | $C^{\prime}$ | C 0 | 0 | C | 398. 0 | $\square$ | 0 | 0 | 0 | C | 0 | C | 0 | - | 669.8 |
| C | C | 0 | 0 | C | $C$ | $C$ C | C | 0 | 402.0 | 0 | 0 | 0 | 0 | C | 0 | C | 0 | C | 672.6 |
| c | C | 0 | 0 | c | C C | C C | c | C | 406. 2 | 0 | 0 | 0 | 0 | C | 0 | C | C | 0 | 675.5 |
| c | c | 0 | c | 0 | 0 | 00 | 0 | 0 | 410.4 | 0 | 0 | 0 | 0 | c | 0 | c | C | C | 678. 4 |
| C | C | 0 | C | 0 | 0 | 0 | 0 | C | 414.7 | 0 | 0 | 0 | 0 | C | C | 0 | 0 | D | 681.3 |
| C | C | 0 | c | 0 | 0 | 0 C | C | $\square$ | 419.1 | 0 | 0 | 0 | 0 | C | C | 0 | 0 | C | 684.2 |
| C | C | 0 | c | 0 | 0 | 0 C | C | C | 423. 5 | 0 | 0 | 0 | 0 | C | c | 0 | C | 0 | 687.2 |
| C | C | 0 | c | 0 | 0 C | C 0 | 0 | 0 | 428. 1 | 0 | 0 | 0 | 0 | C | C | 0 | C | C | 690.2 |

Table 3-8: Baud Rate Switch Settings (Con't.)

| 54 | 53 |  | 54 | 53 |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| A | 87654321 | 1 Low rate | 1 |  | 765 | 432 |  | Low rate |
| 0 | ooocccoo | O 693. 2 | 0 | 00 | c 0 | 00 C | C | 913.0 |
| 0 | Oodeccoc | C 696.3 | 0 | 0 c | 0 C | $\bigcirc \mathrm{C} 0$ | 0 | 918. 3 |
| 0 | ooocceco | 06993 | 0 | 0 c | 0 C | 0 C 0 | C | 923.6 |
| 0 | - o occ c c c | C 702.4 | 0 | 0 O | 0 O | $\bigcirc \mathrm{C}$ | 0 | 929.0 |
| 0 | 00 COOO 0 | - 705.6 | 0 | 0 | 0 O | 0 c | c | 934.5 |
| 0 | 00600000 | C 708.7 | 0 | 0 | 0 C | c 0 | 0 | 940.1 |
| 0 | - ¢ ¢ o oco | - 711.9 | 0 | 0 | 0 C | C 0 | c | 945.7 |
| 0 | OOCOOOC 0 | C 715.1 | 0 | 0 c | O 0 | $\bigcirc 0$ | 0 | 951.4 |
| 0 | ○ ocoocoo | - 718.4 | 0 | 0 | O 0 |  | c | 957.1 |
| 0 | OOCOOCOC | C 721.6 | 0 | 0 | 0 C | c $C^{\circ}$ | 0 | 962. |
| 0 | oocoocco | O 724.9 | 0 | 0 | 0 O | c C O | C | 968. 8 |
| 0 | - ocooc co | C 728. 3 | 0 | 0 | 0 O | $C^{C}$ | 0 | 974.8 |
| 0 | Oococooo | - 731.6 | 0 | 0 | c 0 | $\bigcirc \mathrm{C}$ | c | 980.8 |
| 0 | 0 Ococooc | C $\quad 735.0$ | 0 | 0 | c 0 | 00 | 0 | 986. 9 |
| 0 | OOcococo | - 738.5 | 0 | 0 | c 0 | 00 | C | 993. 1 |
| 口 | Oоcococ c | C 741.9 | 0 | 0 | c 0 | $00^{0}$ | O | 999. |
| 0 | oococ coo | - 745.4 | 0 | 0 | c C | $0{ }^{\circ} \mathrm{C}$ | C | 1,006 |
| 0 | Oоcoccoc | C 748.9 | 0 | 0 | c $c$ | 0 c | 0 | 1,012 |
| 0 | o ococeco | - 752. 5 | 0 |  | c 0 | $\bigcirc \mathrm{C} 0$ | C | 1, 019 |
| 0 | ○ococcco | C 756.1 | 0 | 0 | c 0 | 0 C | 0 | 1, 025 |
| 0 | ○ occooo | $0 \quad 759.7$ | 0 | 0 | c c | $\bigcirc \mathrm{C}$ | C | 1,032 |
| 0 | O ¢ c ¢ O O | C $\quad 763.4$ | 0 | 0 | $c \mathrm{c} 0$ | c 0 | 0 | 1,039 |
| 0 | ooccooco | O 767.1 | 0 | 0 | c 0 | c 0 | C | 1,046 |
| 0 | ooccooco | - 770. | 0 | 0 | c $c$ | C D C | 0 | 1, 053 |
| 0 | ○ ¢ c c coo | - 774.6 | 0 | 0 | c 0 | c 0 | C | 1. 060 |
| 0 | O ¢ c cococ | C 778.4 | 0 | 0 | co | c co | O | 1,067 |
| 0 | ooccocco | - 782. 2 | 0 | 0 | c 0 | c c o | C | 1,074 |
| 0 | ○ occoccc | C 786. 1 | 0 | 0 | c 0 | C C C | 0 | 1, 081 |
| 0 | oocccooo | - 790.0 | 0 | 0 | c 0 | C C C | c | 1,089 |
| 0 | ooccacoc | C 794.0 | 0 | 0 | C C | 000 | 0 | 1. 096 |
| 0 | oocccoco | - 798.0 | 0 |  | c ${ }^{\text {c }}$ | 00 | C | 1,104 |
| 0 | oocccoco | - 9020 | 0 | 0 | c ${ }^{\text {c }}$ | 006 | 0 | 1,112 |
| 0 | Ooccocoo | - 806. 1 | 0 | 0 | c $\quad$ c | 00 | C | 1,119 |
| 0 | oocccaoc | C 810.2 | 0 | 0 ¢ | c $c^{\text {c }}$ | $\bigcirc \mathrm{C} 0$ | 0 | 1, 127 |
| 0 | oocccca | - 814.4 | 0 | 0 | c C | $\bigcirc \mathrm{C} 0$ | C | 1,135 |
| 0 | oocccacc | C 318.6 | 0 | 0 c | c $c$ | 0 C | 0 | 1,144 |
| 0 | ○cooboob | - 822.9 | 0 | 0 | c ${ }^{\text {c }}$ | $\bigcirc \mathrm{C}$ | c | 1,152 |
| 0 | 0 C 00000 c | C 327. 2 | 0 | 0 | c C | c 00 | 0 | 1,160 |
| 0 | Ocooboco | O 831.5 | 0 | 0 | c c | c 0 | C | 1.169 |
| 0 | ○cooboc | C 835.9 | 0 | 0 | c C |  | 0 | 1.178 |
| 0 | ○cooocoo | - 840.3 | 0 | 0 | c ${ }^{\text {c }}$ | $\bigcirc{ }^{\circ} \mathrm{C}$ | - | 1,187 |
| 0 | Ocoobcoc | C 844. ${ }^{\text {8 }}$ | 0 | 0 | c C | C $C^{\circ}$ | 0 | 1, 195 |
| 0 | Ocoorcco | - 849.3 | 0 | 0 | c c | c $C^{\circ}$ | C | 1,205 |
| 0 | ocooocco | C 853.9 | 0 | 0 | c c | c C C | 0 | 1,214 |
| 0 | Ocoocooo | - 858.5 | 0 | 0 | c c | c C C | C | 1,223 |
| - | Ocoocooc | C 863.2 | 0 | C | - 0 | - 0 | 0 | 1,233 |
| - | Ocoococo | 0868.0 | 0 | c | 0 | 000 | c | 1,242 |
| 0 | - c o ococ c | C 872.7 | 0 | c | 00 | $00^{\circ}$ | 0 | 1, 252 |
| 0 | ○ c o oc coo | O 877.6 | 0 | c | 00 | $\bigcirc 0$ | c | 1,262 |
| 0 | ○ c o occoc | C 882. 5 | 0 | c | 00 | $\bigcirc \mathrm{C} 0$ | 0 | 1,272 |
| 0 | ○cooc c co | - 887.4 | 0 | c | 00 | 0 c 0 | C | 1,283 |
| 0 | ocoocc c c | C 892.4 | 0 | c | 00 | $\bigcirc$ | 0 | 1,293 |
| 0 | Ococooo | 0897.5 | 0 | c | 00 | 0 c | C | 1,304 |
| 0 | Ococoo c | C 902.6 | 0 | c | 0 | c 0 | 0 | 1,315 |
| 0 | OCOCOO | $0 \quad 907.7$ | 0 |  | - | 00 |  | 1.326 |

Table 3-8: Baud Rate Switch Settings (Con't.)

| S4 | S3 |  |  |  |  |  |  |  |  | S4 | 53 |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 1 | B | 7 | 6 | 5 | 4 | 3 | 2 | 1 | Low rate | 1 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | Low ra | ate |
| 0 | C | 0 | 0 | 0 | C | 0 | c | 0 | 1.337 | 0 | C | C | 0 | 0 | 0 | 0 | 0 | C | 2. 495 |  |
| 0 | C | 0 | 0 | 0 | C | 0 | C | C | 1.348 | - | C | C | 0 | 0 | 0 | 0 | C | 0 | 2,535 |  |
| 0 | C | 0 | 0 | 0 | C | $C$ | 0 | - | 1,360 | 0 | C | C | 0 | 0 | 0 | 0 | C | C | 2. 576 |  |
| 0 | C | D | 0 | 0 | c | C | - | c | 1,371 | 0 | C | C | 0 | 0 | 0 | C | 0 | 0 | 2,618 |  |
| 0 | C | 0 | 0 | 0 | C | C | C | 0 | 1,383 | 0 | C | C | 0 | 0 | 0 | C | 0 | C | 2.662 |  |
| 0 | c | D | 0 | 0 | C | C | C | c | 1,396 | 0 | C | C | 0 | 0 | 0 | C | C | 0 | 2,708 |  |
| 0 | c | 0 | 0 | C | 0 | 0 | 0 | 0 | 1,408 | 0 | C | C | 0 | 0 | 0 | C | c | C | 2,755 |  |
| 0 | C | 0 | - | c | 0 | - | 0 | c | 1,421 | 0 | C | C | 0 | 0 | c | 0 | 0 | 0 | 2. 804 |  |
| 0 | C | 0 | 0 | C | 0 | 0 | C | 0 | 1,434 | 0 | C | C | 0 | 0 | C | 0 | 0 | C | 2, 854 |  |
| 0 | c | - | 0 | c | 0 | 0 | c | c | 1,447 | 0 | C | C | 0 | 0 | c | 0 | C | 0 | 2.907 |  |
| 0 | C | 0 | 0 | C | $\square$ | c | 0 | 0 | 1,460 | 0 | C | C | 0 | 0 | c | 0 | C | C | 2,961 |  |
| 0 | C | 0 | 0 | c | 0 | c | - | C | 1,474 | 0 | C | C | 0 | O | c | C | 0 | 0 | 3. 017 |  |
| 0 | C | 0 | O | C | 0 | c | C | 0 | 1,487 | 0 | C | c | 0 | 0 | C | C | - | C | 3. 076 |  |
| 0 | C | 0 | 0 | C | - | C | C | C | 1,501 | D | C | C | 0 | 0 | C | C | C | 0 | 3, 137 |  |
| 0 | C | 0 | 0 | C | c | 0 | 0 | 0 | 1,516 | 0 | C | C | 0 | 0 | C | C | C | C | 3. 200 |  |
| 0 | C | 0 | - | C | C | 0 | - | C | 1,530 | 0 | C | C | 0 | c | 0 | 0 | 0 | 0 | 3. 266 |  |
| 0 | C | 0 | 0 | C | C | 0 | C | 0 | 1,545 | 0 | C | c | 0 | c | 0 | 0 | 0 | C | 3. 335 |  |
| 0 | C | 0 | - | C | C | 0 | C | C | 1. 561 | 0 | C | C | 0 | C | $\square$ | 0 | C | 0 | 3,407 |  |
| 0 | C | 0 | 0 | C | C | $C$ | 0 | 0 | 1,576 | 0 | C | C | 0 | c | 0 | 0 | c | C | 3,482 |  |
| 0 | C | 0 | 0 | C | C | $C$ | 0 | C | 1.592 | 0 | C | C | 0 | C | 0 | C | 0 | 0 | 3, 560 |  |
| 0 | C | 0 | 0 | C | C | C | C | 0 | 1,608 | 0 | C | c | 0 | C | 0 | c | 0 | C | 3. 642 |  |
| 0 | C | D | 0 | C | C | c | C | C | 1,625 | - | C | C | 0 | C | 0 | C | C | 0 | 3. 728 |  |
| 0 | C | D | C | 0 | 0 | - | 0 | 0 | 1,641 | 0 | C | C | 0 | c | 0 | c | C | C | 3. 817 |  |
| 0 | C | 0 | C | $\bigcirc$ | 0 | 0 | 0 | C | 1,659 | 0 | C | C | 0 | C | C | 0 | 0 | 0 | 3.912 |  |
| 0 | C | 0 | C | 0 | 0 | 0 | C | 0 | 1,676 | 0 | C | C | 0 | c | C | 0 | 0 | C | 4, 011 |  |
| 0 | C | 0 | c | 0 | 0 | $\bigcirc$ | c | C | 1,694 | 0 | C | C | 0 | c | C | 0 | C | O | 4, 115 |  |
| 0 | C | 0 | C | 0 | 0 | C | 0 | 0 | 1,712 | 0 | C | C | 0 | c | C | 0 | C | C | 4. 225 |  |
| 0 | C | 0 | C | 0 | 0 | C | 0 | c | 1,731 | 0 | C | C | 0 | C | C | C | 0 | 0 | 4, 341 |  |
| 0 | C | 0 | C | 0 | - | C | C | 0 | 1,750 | 0 | c | C | 0 | C | C | C | 0 | C | 4,463 |  |
| 0 | C | 0 | C | 0 | $\square$ | C | C | C | 1,770 | 0 | C | C | 0 | C | C | C | C | 0 | 4,592 |  |
| 0 | C | 0 | C | 0 | c | 0 | 0 | 0 | 1.790 | - | c | C | 0 | C | C | C | C | C | 4, 729 |  |
| 0 | c | 0 | C | 0 | C | 0 | 0 | - | 1.810 | 0 | C | C | C | 0 | 0 | 0 | 0 | 0 | 4,875 |  |
| 0 | c | 0 | C | 0 | C | 0 | c | 0 | 1, 831 | 0 | C | C | c | 0 | 0 | 0 | 0 | C | 5, 030 |  |
| 0 | c | 0 | c | 0 | C | 0 | C | c | 1, 853 | 0 | C | C | C | 0 | 0 | 0 | C | 0 | 5, 195 |  |
| 0 | C | 0 | c | 0 | C | $C$ | 0 | $\square$ | 1,875 | 0 | C | C | C | 0 | 0 | 0 | C | C | 5,371 |  |
| 0 | c | 0 | C | 0 | c | C | 0 | C | 1.897 | 0 | C | C | C | 0 | 0 | C | 0 | 0 | 5,560 |  |
| 0 | C | 0 | c | 0 | C | C | C | - | 1.920 | 0 | c | C | C | 0 | 0 | C | 0 | C | 5,762 |  |
| 0 | C | 0 | C | 0 | c | C | C | C | 1.944 | 0 | C | C | C | 0 | 0 | C | C | 0 | 5,979 |  |
| 0 | c | 0 | c | C | 0 | 0 | 0 | - | 1.968 | 0 | c | c | C | 0 | 0 | C | C | C | 6. 214 |  |
| 0 | C | 0 | C | C | 0 | 0 | 0 | C | 1.993 | 0 | C | C | C | 0 | C | 0 | 0 | 0 | 6. 468 |  |
| 0 | C | 0 | c | C | 0 | 0 | C | 0 | 2.018 | 0 | C | C | C | 0 | C | 0 | 0 | C | 6.743 |  |
| 0 | C | 0 | C | C | 0 | 0 | C | C | 2. 044 | 0 | C | C | C | 0 | C | 0 | C | 0 | 7,043 |  |
| 0 | C | 0 | C | C | 0 | $C$ | 0 | 0 | 2. 071 | 0 | C | C | C | 0 | C | 0 | C | C | 7,371 |  |
| 0 | C | 0 | C | C | 0 | C | 0 | C | 2.098 | 0 | C | C | C | 0 | C | C | 0 | 0 | 7,731 |  |
| 0 | C | 0 | C | C | 0 | C | C | 0 | 2.126 | - | C | C | C | 0 | C | C | 0 | C | 8, 128 |  |
| 0 | C | 0 | C | C | 0 | C | C | C | 2. 155 | 0 | C | C | C | 0 | C | C | C | 0 | 8. 568 |  |
| 0 | C | 0 | C | C | c | 0 | 0 | 0 | 2. 185 | 0 | C | C | C | 0 | c | C | C | C | 9, 059 |  |
| 0 | c | 0 | C | C | C | 0 | 0 | C | 2, 215 | 0 | C | C | C | C | 0 | 0 | 0 | 0 | 9,609 |  |
| 0 | C | 0 | C | C | C | $\square$ | C | 0 | 2, 247 | 0 | C | C | C | C | 0 | 0 | 0 | C | 10.230 |  |
| 0 | C | 0 | c | C | C | 0 | C | c | 2, 279 |  |  |  |  |  |  |  |  |  |  |  |
| 0 | C | 0 | C | C | C | C | 0 | 0 | 2,313 |  |  |  |  |  |  |  |  |  |  |  |
| 0 | c | 0 | c | C | C | c | $\square$ | c | 2,347 |  |  |  |  |  |  |  |  |  |  |  |
| 0 | C | 0 | C | C | C | C | C | 0 | 2,382 |  |  |  |  |  |  |  |  |  |  |  |
| 0 | C | 0 | C | C | c | c | C | C | 2,418 |  |  |  |  |  |  |  |  |  |  |  |
| D | C | C | 0 | 0 | 0 | 0 | 0 | 0 | 2,456 |  |  |  |  |  |  |  |  |  |  |  |

Table 3-8: Baud Rate Switch Settings (Con't.)

### 3.8 MAINTENANCE FEATURES

### 3.8.1 MAINTENANCE FEATURES

For maintenance purposes, the DH/DM contains three switch positions to control the resident microcoded diagnostic. The switch positions are switch S5, positions 1 and 2, and switch S6, position 1. Refer to Table 3-10 for definitions and functions of these switches. -Table 3-11 lists the execution sequence of the microdiagnostic.

For normal operation, set the switches as follows:

Switch S5, position 1 - CLOSED
Switch S5, position 2 - OPEN
Switch S6, position 1 - OPEN

| SWITCH S6 | SWITCH S5 |  | FUNCTIONAL DESCRIPTION |
| :---: | :---: | :---: | :---: |
| 1 | 2 | 1 |  |
| OPEN | X | OPEN | Run microdiagnostic, omit Bus and UART section, exit to emulation after end of test or first error. |
| OPEN | X | CLOSED | Run microdiagnostic, omit Bus and UART section, exit to emulation if no errors. Will not proceed to emulation routine if an error is detected. |
| CLOSED | OPEN | OPEN | Loop in entire microdiagnostic test, including the Bus and UART section. will not enter emulation. |
| CLOSED | OPEN | CLOSED | Hang in section if error occurs. Will not enter emulation. LED 1,2 , and 3 will display section error has occured in. ERR LED will display error, if any. |
| CLOSED | CLOSED | OPEN | Loop on section. Will not proceed into another section or into emulation. LED 1, 2, and 3 will display section. ERR LED will display error, if any. |
| CLOSED | CLOSED | CLOSED | Loop on section, hang if error. Will not proceed into emulation. LED 1, 2, and 3 will display section. ERR LED will display error, if any. |

NOTE: l. Bus and UART section are bypassed when switches are set to proceed into emulation due to the time required to perform the UART test, and because the Bus tests may disturb the system.
2. Any error detected in the first section of the microdiagnostic will cause a hang regardless of the switch settings.
3. The "ERR" indicator is reset at the beginning of each section of the microdiagnostic.

| EXECUTION <br> SEQUENCE | SECTION |
| :---: | :--- |
| Power Up |  |
| 1 |  |
| 2 | Section 7-SEQ <br> 3 <br> 4 |
| 5 | Section 3-DATA (2901) <br> Section 5-PROM <br> Section 4-BUFF |
| 6 | Section 6-BUS (NPR, BR) <br> 7 |
| Section 2-UART <br> If S5-1 is open, Section 6 and 2 <br> are bypassed and emulation is <br> entered after Section 4. |  |

Table 3-11: Microdiagnostic Execution Chart

### 3.8.2 MAINTENANCE DISPLAY

The DH/DM contains four LEDs for maintenance display purposes. These LEDs are located at the top of the board, between connectors J1 and J2. Figure 3-1 shows the location of the LEDs. Refer to Table 3-12 for descriptions of the LED displays. Section 3.13 provides more information on the LEDs.

| DISPLAY |  |  |  | DESCRIPTION |
| :---: | :---: | :---: | :---: | :---: |
| ERR | 1 | 2 | 3 |  |
| off | off | off | off | END PASS / EMULATION |
| off | off | off | on | Testing Section 1 - DBIT |
| off | off | on | off | Testing Section 2 - UART |
| off | off | on | on | Testing Section 3 - DATA (2901) |
| off | on | off | off | Testing Section 4 - BUFF |
| off | on | off | on | Testing Section 5 - PROM |
| off | on | on | off | Testing Section 6 - BUS (NPR, BR) |
| off | on | on | on | Testing Section 7 - SEQ |
| on | off | off | off | Error - Undefined problem |
| on | off | off | on | Error in Section 1 - DBIT Error |
| on | off | on | off | Error in Section 2 - UART Error |
| on | off | on | on | Error in Section 3 - DATA (2901) Error |
| on | on | off | off | Error in Section 4 - Error BUFF |
| on | on | off | on | Error in Section 5 - Error PROM |
| on | on | on | off | Error in Section 6 - Error BUS |
| on | on | on | on | Error in Section 7 - SEQ Error |

Table 3-12: Maintenance Display Chart

### 3.9 PRIORITY SELECTION

The standard priority interrupt levels for the DH/DM are BG5 for the DH and BG4 for the DM. These levels are factory wired and require no user adjustment.

If you wish to change interrupt levels for the $D H$ or $D M$, use the strapping chart in Appendix A.

### 3.10 PREPARING YOUR SYSTEM FOR THE DH/DM

To prepare your system for installing the $D H / D M$, remove power from the system. Use either the front panel switch or the master breaker switch at the bottom of the cabinet. We suggest that both switches be turned off.

Once power is removed from the system, locate a vacant hex SPC slot that can accomodate the DH/DM board. Normally, this will be slots two or three in the DDll-C four slot backplane, or slots two through eight of the DDll-D nine slot backplane. Remove any previously installed bus grant continuity cards from this slot. Modify the backplane to accomodate $\mathrm{DH} / \mathrm{DM}$ by removing the wire between pins CAl and CBl of that slot.

### 3.11.1 BOARD"INSTALLATION

Prior to installing the DH/DM board, verify that the address and vector switches are set to the desired settings. Insert the board into the selected vacant slot, using the card guides to ensure that it is properly positioned. Insert the board until the two card extractor devices on the DH/DM can be used to further insert the board into the SPC connector blocks.
3.11.2 EIA PANEL INSTALLATION

The EIA panel is usually mounted at the rear of the computer cabinet to allow easy access to panel controls. Four mounting locations are provided to mount the panel directly into the cabinet. If preferred, right angle brackets are supplied to recess the panel.
3.11.3 INTERCONNECTING CABLE INSTALLATION

Locate the cable end marked "Panel" and connect it to the distribution panel connector J3 by aligning the triangles during insertion. Attach the other end of this cable to connector Jl on the DH/DM board by aligning the triangles during insertion. Locate the end marked "Panel" on the second cable and connect it to the distribution panel connector J4 by aligning the triangles during insertion. Attach the other end of this cable to connector J2 on the DH/DM board by aligning the triangles during insertion.

### 3.12 DIAGNOSTICS

Here are some of the diagnostics which can be used to verify operation of DH/DM and/or your system.

ZDHM This test program is designed to aid in acceptance testing, installation checkout, and corrective maintenance. It consists of 48 logically sequenced diagnostic tests which verify that the DH/DM is operating in accordance with its design specifications.

DEC/Xll This program provides the means to generate, run, control, and update interactive hardware system exerciser programs for PDP-ll systems.

ZDHN This program is divided into three tests: Data Reliability Test All lines are tested at one time with all combinations of line parameters.

Single Line Echo Test

Data:Patterns/Cable Test

Tests any line by using an asynchronous terminal device. Operates in send mode and echo mode.

Tests any line using an H315 test connector to terminate the line under test. This program would normally be used for troubleshooting a specific problem.

Running these first three diagnostics will verify completely the operation of DH/DM. The following diagnostics are all contained in ZDHM and can be used when it is not available.

ZDHA This program tests the correct function of all read/write bits in the system control register, line parameter register, break control register, and silo status register. Additionally, it checks the function of read-only bits in maintenance mode, register addressability, and the function of master clear. Each function is tested in an individual test loop.

ZDHB This program tests the byte count and bus address memories of the DH/DM. Each memory is tested for addressability and data read/write capability.

ZDHC This program checks the basic transmitter and receiver functions. These functions include interrupts, transmitter NPR logic, and receiver silo logic.

ZDHD This program verifies proper operation of speed selection functions of the line parameter for each transmitter and receiver line. Pransmitter timing is checked first, and then receiver timing. The program uses a relative timing comparison to determine if line speed selection is correct.

ZDHE This program verifies that character length on each line can be selected correctly, and the correct line number and character status are received on each line selectèd:fór transmission.

ZDHF This test verifies that each line can transmit and receive all 256 combinations of characters ( 8 bits per character) at all speeds. It also verifies that each line can transmit and receivie ałl character lengths (8-5) at a speed of 9600 baud.

ZDHG This test checks that the parity error flag asserts for all 16 lines of the $\mathrm{DH} / \mathrm{DM}$, one line at a time. The test transmits binary count patterns on all 16 lines simultaneously. The test also verifies parity generation logic and parity reception logic (odd. and even parity for $5,6,7$, and 8 level codes ).

| ZDHH | This test verifies the functions of auto echo logic of the DH/DM transmitter and receiver. |
| :---: | :---: |
| ZDHI | This program checks break control logic and verifies that the USART's receive only one break character on a given line. The test also verifies that no characters are received on a line when the half duplex function for that line is selected. |
| ZDHJ | This program is divided into two tests: The echo test verifies that all characters will echo on each line. The cable test verifies that ali characters are transmitted and received on a per line basis. |
| ZDHK | This program is divided into four tests, two of which pertain to the DH/DM. Test 0 verifies that all, line scanner and line multiplexer functions are operable. Test 0 does not require use of a maintenance connector or distribution panel cables. Test $l$ is a single line cable test using distribution panel cables and the maintenance connector. |

### 3.13 INSTALLATION VERIFICATION

Once the DH/DM has been installed into the system, power can be applied. During the power-up sequence, the $D H / D M$ performs an internal diagnostic. This diagnostic verifies the majority of internal operations of the DH/DM. With the maintenance switch set for normal operation, it does not check devices that are used to interface to the Unibus.

The diagnostic mode is switch selectable. Refer to Section 3.8 for proper switch settings.

By monitoring four LEDs near the top of the board, proper internal operation of the DH/DM can be verified. Figure 3-1 shows the location of the LEDs. When power is applied, all four LEDs should light up and after a wery short flash, should all turn off. Any LED which remains lit indicates a malfunction and requires investigation. Section 3.8.3 defines the functions of the four LEDs and Section 4 provides troubleshooting tips in case an LED remains lit.

If all four LED displays turn off after power has been applied to the system, address the DH/DM through the operator front panel or ODT. Examine the second address assigned to the DH/DM and the next eight word locations. Address $76 \times X X 2$ is the $N R C R$ register and will contain the DH and DM vector selection information. Refer to Figure 3a4 for switch verification. If the vector settings are not correct, re-check the settings as described in Section 3.5.

If all four LEDs turn off after the power-up sequence and addresses have been verified, continue to verify installation of the DH/DM by executing the software diagnostic. The ZDHM diagnostic can be loaded and executed at location 200. It automatically auto-sizes to determine the number of DH/DM's in the system and performs verification of the DH/DM in the internal loop-back mode. The diagnostic also prints the address and vector assignments: Compare these with your selections to verify correct address and vector assignments.

NOTE: Prior to running the diagnostics; except DECX $/ 11$, the cables must be installed in maintenance connectors J7 and J8 on the distribution panel. Figure 3-5 shows cables installed in maintenance connectors.

Further information on operation of the diagnostic can be found in the diagnostic listing. Proper performance of the diagnostic will be indicated by pass counts displayed on the local terminal. We suggest running at least two passes. Once the diagnostic has been verified, return the cables to their normal connectors.

If your system adequately performs these diagnostics, DH/DM installation is verified and ready for use with your operating system.

If any errors occur in the $Z D H M$ diagnostic, analyze the error printout. If the error is in the $D H / D M$ address space, verify the switch settings. If the system still fails, contact our Product Support group as described in Section 4.

If DECX/ll fails, try to use operator selections to isolate the problem. If $D H / D M$ seems to be the source of the error, verify the steps in Section 3 again. If the problem persists, contact the Able Product Support group as described in Section 4. So we can be more responsive to your needs, keep the error printout on hand when calling us.


Figure 3-4: Next Received Character Register (NRCR)


Figure 3-5: Cables Installed For Maintenance Mode

## Section 4

## What to Do if DH/DM Does Not Work

### 4.1 HOW TO CARE FOR DH/DM

ABLE products are designed to provide years of service with a minimum of care. Here are a few tips to help you avoid problems.

- If a printed circuit board is frequently inserted and removed, it tends to build up a gum-like residue on the contacts. Clean this residue off using alcohol or freon. Use of a pencil eraser can remove some of the gold on the contacts, so if you choose to use one, go easy.
- Every six months remove each printed circuit board and clean off any accumulated dust. Dust can impede air flow. While the board is out, inspect it for any visual evidence of a potential problem such as damaged components, loose connections, etc.
- Schematics for your DH/DM can be ordered from the ABLE factory. Document numbers are listed below.

| 10103003 | DH/DM PC Board |
| :--- | :--- |
| 10114003 | EIA Distribution Panel |

- If you wish to maintain a spare parts inventory, refer to the recommended list in Appendix A.
- If a problem arises with the operation of your DH/DM, follow the steps outlined in the following sections.


### 4.2 TROUBLESHOOTING TIPS

4.2.1 "ERR" LED ON

### 4.2.2 VERIFY CONFIGURATION AND INSTALLATION

Experience has shown that the greatest number of problems with DH/DM involve configuration or installation errors. An address, vector, or priority level assignment may be inconsistent with system definitions. A correct assignment may be incorrectly specified to the system generator or incorrectly implemented by switch settings or jumper placements.
l. Using Sections 3.5 and 3.6 verify that address and vector assignments and switch settings are correct.
2. Using Section 3.9, check that interrupt priority jumpers are correctly placed and are making contact.
3. Using Section 3.10, verify that the wire between pins CAl and CBl of the DH/DM backplane slot has been removed.
4. If the problem involves 200 baud or external $B$ speed selections, use Section 3.7 to check that the correct baud range is selected.
5. Use a voltmeter to verify that the $+5 \mathrm{~V},+15 \mathrm{~V}$, and -15 V are within $+5 \%$ of their nominal value. If not, adjust the associated power supplies. See Table 4-1 for the backplane pins at which these voltages appear.

| Voltage | Backplane Pins |
| :--- | :--- |
| +5 V | $\mathrm{AA} 2, \mathrm{BA} 2, \mathrm{CA} 2, \mathrm{DA} 2, \mathrm{EA} 2, \mathrm{FA} 2$ |
| +15 V |  |
| -15 V. | CU 1 |
| Ground | $\mathrm{CB} 2, \mathrm{DB} 2, \mathrm{~EB} 2, \mathrm{FB} 2$ |

Table 4-1: Voltage Sources on Backplane
Once you are certain that $D H / D M$ is correctly configured and installed and is receiving appropriate input power, DEC diagnostic ZDHM can be used to assign trouble between the $\mathrm{DH} / \mathrm{DM}$ and external equipment or cabling.

It should be noted that this diagnostic will detect a speed error unless the external B frequency is set for 200 baud.

If a fault in a DH/DM board is indicated, call ABLE as described in Sections 4.3 and 4.4.

### 4.2.3 FAILS ZDHM DIAGNOSTIC

If an error is reported when running the ZDHM diagnostic, we suggest you take the following steps:

1. Verify that none of the DH/DM LEDs are lit.
2. Verify that the cables are installed in the maintenance connectors (J7 and J8) on the EIA panel.
3. Remove the $D H / D M$ board and re-verify that the desired address and vector assignments are set correctly.
4. Re-install the board and run the diagnostic again.

If the error persists, please contact the ABLE Product Support Center as described in Sections 4.3 and 4.4.

### 4.2.4 FAILS SYSTEM SOFTWARE

If the DH/DM is suspected of causing failures within the system software, we request that you run a diagnostic to determine whether the DH/DM unit is good or bad. If the DH/DM operates the diagnostic properly and only fails the system software, check the address and vector assignments to ensure that they conform to SYSGEN parameters.

If the failure persists, contact the ABLE Product Support Center as described in Sections 4.3 and 4.4.

### 4.3 WHO TO CALL FOR SERVICE WITHIN THE UNITED STATES

ABLE's goal is to provide each customer with a product that works well in his system. We design and build our products to provide high reliability and to minimize problems. When a problem does arise, it is our intent to do everything in our power to quickly and efficiently solve it.

If your DH/DM does not function properly and you are within the United States, contact our Product Support Center before sending it for repair: (Have serial numbers available when calling.)

```
ABLE COMPUTER
1751 Langley Avenue
Irvine, California 92714
(714) 979-7030
TWX 910-595-1729
```

If your DH/DM requires repair, we prefer that you return it to the factory.

When shipping the DH/DM use the original container or a corregated cardboard carton with at least one inch of cushioning material on all sides. Ship it to the above address. Include a description of the problem and a hard copy of the failure mode or a diagnostic printout when available. Be sure to include your name, address, and telephone number.

### 4.4 WHO TO CALL FOR SERVICE OUTSIDE THE UNITED STATES

ABLE's goal is to provide each customer with a product that works well in his system. We design and build our products to provide high reliability and to minimize problems. When a problem does arise, it is our intent to do everything in our power to quickly and efficiently solve it.

If your DH/DM does not function properly, contact your local distributor or telex ABLE COMPUTER for the name and address of your local distributor:

## Section 5 <br> How to Use DH/DM

### 5.1 TYPICAL APPLICATIONS

The DH/DM connects a PDP-ll or VAX sẏstem to sixteen tērmínals dèsigned to interface with asynchronous communications lines. It provides direct memory access (DMA) ouput capabilities.

Figure 5-1 illustrates typical interfaces between the DH/DM and local or remote terminals.

The DH/DM is used to interface with local terminal devices or, via modems and dedicated lines, with remote terminal devices. When commumicating with remote terminals via datasets interfacing over switched networks, modem control is available for all lines.


Figure 5-1: DH/DM Applications

### 5.2 TERMINAL/COMMUNCATIONS LINK INTERFACE INFORMATION

Table 5-1 lists the pin assignments on connectors $J 1$ and $J 2$ on the DH/DM. These connectors provide the interface with the external distribution system "for a DH/DM.

Table 5-2 lists pin assignments for the EIA RS232-C connectors on the EIA distribution panel. Notice that certain internal lines are hard-wired to connector pins and others are connected through jumpers installed on the EIA distribution panel. Jumper placements have been selected to provide compatibility with the greatest possible number of modem interfaces. Modifications to jumper placements may be required for certain interfaces. Figure 5-2 shows the location of the jumpers on the panel. Figure 5-3 provides wiring information for modem connection.

### 5.3 UNIBUS CONNECTOR INFORMATION

Table 5-3 lists the Unibus signals accepted or supplied by the DH/DM via the connectors on the board.

|  | J1 |  |  |
| :---: | :---: | :---: | :---: |
| DTROO-H | 1 | 2 | CARROO-H |
| DTRO1-H | 3 | 4 | CARRO1-H |
| DTR02-H | 5 | 6 | CARRO2-H |
| DTRO3-H | 7 | 8 | CARPO3-H |
| DTR04-H | 9 | 10 | CARRO4-H |
| DTR05-H | 11 | 12 | CARR05-H |
| DTR06-H | 13 | 14 | CARR06-H |
| DTR07-H | 15 | 16 | CARR07-H |
| GND | 17 | 18 | GND |
| TXD00-H | 19 | 20 | RINGOO-H |
| RXD00- | 21 | 22 | GND |
| TXDO1-H | 23 | 24 | RINGO1-H |
| RXDO1-H | 25 | 26 | GND |
| TXD02-H | 27 | 28 | RINGO2-H |
| RXD02-H | 29 | 30 | GND |
| TXD03-H | 31 | 32 | RINGO3-H |
| RXD03-H | 33 | 34 | GND |
| TXD04-H | 35 | 36 | RINGO4-H |
| RXD04-H | 37 | 38 | GND |
| TXD05-H | 39 | 40 | RING05-H |
| RXD05- H | 41 | 42 | GND |
| EXD06-H | 43 | 44 | RINGO6-H |
| RXD06-H | 45 | 46 | GND |
| TXD07-H | 47 | 48 | RING07-H |
| RXD07-H | 49 | 50 | GND |
|  |  |  |  |
| DTR08-H | 1 | 2 | CARR08= H |
| DTRÖ9-H | 3 | 4 | CARR09-H |
| DTR10̄-H | 5 | 6 | CARR10-H |
| DTR1I-H | 7 | 8 | CARR11-H |
| DTR12-H | 9 | 10 | CARR12-H |
| DTR13-H | 11 | 12 | CARR13-H |
| DTR14-H | 13 | 14 | CARR14-H |
| กTRI5-H | 15 | 16 | CARR15-H |
| GND | 17 | 18 | GND |
| TXD08-H | 19 | 20 | RING08-H |
| RXD08-H | 21 | 22 | GND |
| TXD09- H | 23 | 24 | RING09-H |
| रXDŌ9-H | 25 | 26 | GND |
| TXD10-H | 27 | 28 | RING10-H |
| RXDlō- H | 29 | 30 | GND |
| TXD11-H | 31 | 32 | RING11-H |
| KXDII-H | 33 | 34 | GND |
| TXD12-H | 35 | 36 | RING12-H |
| RXD12-H | 37 | 38 | GND |
| TXD13-H | 39 | 40 | RING13-H |
| RXD13-H | 41 | 42 | GND |
| TXD14-H | 43 | 44 | RING14-H |
| RXD14-H | 45 | 46 | GND |
| TXD15-H | 47 | 48 | RING15-H |
| RXD15-H | 49 | 50 | GND |

Table 5-1: Connectors on DH/DM Board

INFORMATION TO BE SUPPLIED.

Table 5-2: RS232-C Connector Pin Assignments




[^0]

[^1]

Figure 5-3: Wiring Chart For Modem Connection (Con't.)




Figure 5-3: Wiring Chart For Modem Connection (Con't.)

| CONNECTOR A |  |  |
| :---: | :---: | :---: |
| SIDE 1 | PIN | SIDE 2 |
|  | A | $+5 \mathrm{~V}$ |
|  | B |  |
|  | C | GND |
|  | D |  |
|  | E |  |
|  | F |  |
|  | H |  |
|  | J |  |
|  | K |  |
|  | L |  |
|  | M |  |
| BUS-A21-L | N | - |
| BUS-A20-L | P |  |
|  | R |  |
|  | S |  |
| GND | T |  |
|  | U |  |
|  | V |  |


| CONNECTOR B |  |  |
| :---: | :---: | :---: |
| SIDE 1 | PIN | SIDE 2 |
|  | A | +5V |
|  | B |  |
|  | C | GND |
| BUS-Al9-L | D |  |
|  | E | BUS-A18-L |
|  | F |  |
|  | H |  |
|  | J |  |
|  | K |  |
|  | M |  |
|  | N |  |
|  | P |  |
|  | R |  |
|  | S |  |
|  | T |  |
|  | U |  |
|  |  |  |


| CONNECTOR C |  |  |
| :---: | :---: | :---: |
| SIDE 1 | PIN | SIDE 2 |
| BUS-NPG-IN-H | A | +5V |
| BUS-NPGO-H | B | -15V |
|  | C | GND |
|  | D | BUS-D15-L |
|  | E | BUS-D14-L |
|  | F | BUS-D13-L |
| BUS-D11-L | H | BUS-D12-L |
|  | J | BUS-D10-L |
|  | K | BUS-D09-L |
|  | L | BUS-D08-L |
| BUS-DCLO-L | M | BUS-D07-L |
|  | N | BUS-D04-L |
|  | P | BUS-D05-L |
| BUS-PB-I | R | BUS-D01-L |
| GND | S | BUS-D00-L |
| +l5V | T | BUS-D03-L |
|  | U | BUS-D02-L |
|  | V | BUS-D06-L |


| CONNECTOR D |  |  |
| :---: | :---: | :---: |
| SIDE 1 | PIN | SIDE 2 |
| BUS-INIT-L | A | $+5 \mathrm{~V}$ |
|  | B |  |
|  | C | $\cdots$ GND |
|  | D | BUS-BR7-L |
|  | E | BUS-BR6-L |
|  | F | BUS-BR5-L |
|  | H | BUS-BR4-L |
|  | J |  |
|  | K | BUS-BG7-IN-H |
|  | L | BUS-BG7-OUT-H |
|  | M | BUS-BG6-IN-H |
|  | N | BUS-BG6-OUT-H |
|  | P | BUS-BG5-IN-H |
|  | P. | BUS-BG5-OUT-H |
|  | S | BUS-BG4-IN-H |
|  | T | BUS-BG4-OUT-H |
|  | U |  |
|  | V |  |

Table 5-3: DH/DM Board Interface with Unibus Connectors
A Through F

| CONNECTOR E |  |  |
| :---: | :---: | :---: |
| SIDE 1 | PIN | SIDE 2 |
|  | A | $+5 \mathrm{~V}$ |
|  | B |  |
| BUS-A12-L | C | GND |
| BUS-A17-L | D | BUS-A15-L ${ }^{\text { }}$ |
| BUS-MSYN-L | E | BUS-Al6-L |
| BUS-A02-L | F | BUS-Cl-L |
| BUS-AOI-L | H | BUS-A00-L |
| BUS-SSYN-L | J | BUS-C0-L |
| BUS-A14-L | K. | BUS-Al3-L |
| BUS-A11-L | L |  |
|  | M | BUS-A08-L |
|  | N | BUS-A07-L |
| BUS-A10-L | P |  |
| BUS-A09-L | R |  |
|  | S |  |
| GND | T |  |
| BUS-A06-L | U | BUS-A04-L |
| BUS-A05-L | V | BUS-A03-L |


| CONNECTOR F |  |  |
| :---: | :---: | :---: |
| SIDE 1 | PIN | SIDE 2 |
|  | A | +5V |
|  | B |  |
|  | C | GND |
| BUS-BBSY-H | D |  |
|  | E |  |
|  | F |  |
|  | H |  |
| BUS-NPR-L | J |  |
|  | K |  |
|  | L |  |
| BUS-INTR-L | M |  |
|  | N |  |
|  | P |  |
|  | R |  |
|  | S |  |
| GND | T | BUS-SACK-L |
|  | U |  |
|  | V |  |
| . |  |  |
|  |  |  |
|  |  |  |

Table 5-3: DH/DM Board Interface with Unibus Connectors A Through $F$ (Con't.)

## Section 6

## How to Program DH/DM

### 6.1 DATA HANDLING REGISTERS

The data handling portion of the DH/DM is software compatible with the DEC DHll. It contains eight Unibus addressable registers. Table 6-1 contains general information about these registers. As illustrated in Figure 6-1, three of these are actually 16 -register groups with one register for each line. When one of these register groups is addressed, the particular register within the group that is selected is determined by the line number currently held in the four least significant bit positions of the system control register (SCR). Figure 6-2 illustrates register format.

The following paragraphs describe the function of each register.

| Register | Address | Access | Word/Byte Addressable |
| :---: | :---: | :---: | :---: |
| System Control Register | X00 | Mixed <br> See 6.1.1 | Word/Byte |
| Next Received Character Register | XO 2 | Read Only | Word Only |
| Line Parameter Register (Group) | X04 | Read/Write | Word Only |
| Current Address Register | X06 | Read/Write | Word Only |
| Byte Count Register (Group) | X10 | Read/Write | Word Only |
| Buffer Active Register | X12 | Read/Write | Word Only |
| Break Control Register | X14 | Read/Write | Word/Only |
| Silo Status Register | X16 | Mixed <br> See 6.1.8 | Word/Byte |

Table 6-1: Data Handling Register List


NEXT RECEIVED CHARACTER REGISTER (X02) (See Section 6.1.2)


LINE PARAMETER REGISTER (X04) (See Section 6.1.3)


Current Address of the Line Selected in the System Control Register

CURRENT ADDRESS REGISTER (X06) (See Section 6.1.4)

Figure 6-2: Data Handling Register Formats


Two's Complement of the Number of Bytes to be Transmitted on the Line Specified in the System Control Register

BYTE COUNT REGISTER (XIO) (See Section 6.1.5)

| 15 | 14 | 13 | 12 | 11 | 10 | 09 | 08 | 07 | 06 | 05 | 04 | 03 | 02 | 01 | 00 |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |

Transmit Enable, Line 15 - 00

BUFFER ACTIVE REGISTER (X12) (See Section 6.1.6)


BREAK CONTROL REGISTER (X14) (See Section 6.1.7)


SILO STATUS REGISTER (X16) (See Section 6.1.8)

Figure 6-2: Data Handling Register Formats
(con't.)
Bit Description

15

Transmitter Interrupt. This read/write bit is set when the final character in a message buffer is loaded into a UART transmitter holding register. It causes an interrupt if bit 13 is set.

Storage Interrupt. This bit is set when a character transfer from a receiver holding register to the silo is inhibited because the silo is full. It causes an interrupt if bit 12 is set. This bit is read only in the normal mode and read/ write in the maintenance mode. When not in the maintenance mode, the silo has a 255 character capacity.

Transmit and Non-Existent-Memory Interrupt Enable. When set, this read/write bit enables an interrupt in response to the setting of bit 10 or bit 15 .

Storage Interrupt Enable. When set, this read/write bit enables an interrupt in response to the setting of bit 14:

Master Clear. When set, this read/write bit places the data handling portion of the DH/DM in the initialized status in which the silo, the UARTs, and most register bits are cleared.

Non-Existent-Memory Interrupt. This bit is set if no slave sync response is received within 20 microseconds of the assertion of master sync by the DH/DM during an NPR transaction. The lack of response indicates that the addressed memory location does not exist. Setting this bit causes an interrupt if bit 1.3 is set. This bit is read only in the normal mode and read/write in the maintenance mode.

Maintenance. When set, this read/write bit places the DH/DM in the maintenance mode.

Clear Non-Existent-Memory Interrupt. When set, this bit clears bit 10 and itself.

Receiver Interrupt. This bit is set when the number of characters stored in the silo exceeds the alarm level specified by the low byte of the silo status register. It generates an interrupt if bit 06 is set. This bit is read only in the normal mode and is read/write in the maintenance mode. If there are fewer than sixteen characters in the silo, there may be a delay. of up to 20 ms hefore setting this bit. This reduces interrupt overhead.

Receiver Interrupt Enable. When set, this read/write bit enables an interrupt in response to the setting of bit 07

that line number must first be written into the system control register. The line parameter register is a read/write operation register, but when read it reflects the value last written, and not the value for the currently selected line.

Bit
Description
15
Auto-Echo-Enable. When this bit is set, characters received on the line are automatically transmitted back (echoed) on the line by DH/DM.

14
Full Duplex. In the full duplex mode, transmission and reception can occur simultaneously.

13-10 Transmitter Speed. These bits define the transmitter baud rate as summarized in the table below.

| 13 | 12 | 11 | 10 | Speed <br> (paud) | 13 | 12 | 11 | 10 | Speëd <br> (Baud) |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 0 | 0 | 0 | 0 | Lero | 1 | 0 | 0 | 0 | 600 |
| 0 | 0 | 0 | 1 | 50 | 1 | 0 | 0 | 1 | 1200 |
| 0 | 0 | 1 | 0 | 75 | 1 | 0 | 1 | 0 | 1800 |
| 0 | 0 | 1 | 1 | 110 | 1 | 0 | 1 | 1 | 2400 |
| 0 | 1 | 0 | 0 | 134.5 | 1 | 1 | 0 | 0 | 4800 |
| 0 | 1 | 0 | 1 | 150 | 1 | 1 | 0 | 1 | 9600 |
| 0 | 1 | 1 | 0 | 200 | 1 | 1 | 1 | 0 | 19200 |
| 0 | 1 | 1 | 1 | 300 | 1 | 1 | 1 | 1 | External |

Note: There are the following two restrictions associated with speed selection:

1. The 200 and External rates are actually obtained from a common clock on the DH/DM. Thus, if this clock is set for the 200 baud rate, that also becomes the external rate. Conversely, if that clock is set for some other external rate, then the 200 baud rate is unavailable.
2. Different receiver and transmitter speeds can be selected for a given line if only one of these is zero or obtained from the clock shared by the External and 200 selection values.

09-06 Receiver Speed. These bits define the receiver bit rate in the same manner and with the same restrictions that bits 13 - 10 define the transmitter baud rate.

```
05, 04 Odd Parity and Parity Enabled. The combined states of these
    bits determine the parity generated by the JART transmitter and
    the parity required by the UART receiver for the line as
    follows:
```

| 05 | 94 | Parity |
| ---: | ---: | :--- |
| 0 | 0 | None |
| 0 | 1 | Even |
| 1 | 0 | None |
| 1 | 1 | Oda |

03 Not used.
02 Two Stop Bits. When this bit is set, 1.5 stop bits are appended to transmitted characters having 5 data bits and 2 stop bits are appended transmitted characters having from 6 through 8 data bits. When this bit is reset, one stop bit is appended to all transmitted characters regardless of"length.

Note: Unlike some asynchronous receivers, the DH/DM receiver can be programmed to receive one or two stop bits. When two stop bits are specified, the receiver checks for two stop bits. Data that is received with only one stop bit can cause receiver èrrors. To ensure error-free operation, set this field as it would normally be set--with the number of stop bits for the $\mathrm{DH} / \mathrm{DM}$ receiver matching the number of stop bits in the received data.

01, 00 Character Length. These two bits specify the number of data bits in received and transmitted characters as follows:

Data

| 01 | 00 | Bits |
| ---: | :---: | :---: |
| 0 | 0 | 5 |
| 0 | 1 | 6 |
| 1 | 0 | 7 |
| 1 | 1 | 8 |

6.1.4 CURRENT ADDRESS REGISTER (X06)

Prior to transmitting a message over a line, the program must write the starting address of the data buffer containing the message into the current address register for that line. This involves first writing the line number and the address extension bits into the system control register and then transferring the remainder of the starting address directly to the current address register. During this second transfer, Unibus bits 00 through 15 are written into bit positions 00 through 15 of the current address register and the address extension bits from bit positions 04 and 05 of the system control register are written into bit positions 16 and 17 of the current address register.

To read the current address for a line, the program must write the line number into the system control register. It can then read bits 00 through 15 of the current address by reading the current address register and bits 16 through 17 by reading the silo status register which contains these bits in bit positions 06 and 07.

### 6.1.5 BYTE COUNT REGISTER (X10)

Prior to transmitting a message over a line, the program must also write the 2's complement of the number of characters (bytes) in the message into the byte count register. As in the case of the line parameter and current address register, the line number must first be written into the system control register in order to address the byte count register for the line. The byte count register can then be either written or read by the program.

### 6.1.6 EUFFER ACTIVE REGISTER (X12)

This register contains one bit for each line; where bit $n$ is the bit for line $n$. The program sets bit $n$ to start transmission of a message over line $n$ after the message has been written in a data buffer in PDP-ll memory and the starting address and length of the data buffer have been transferred to the current address register and byte count register for the line. The DH/DM subsequently resets the bit for the line at the time that the last character of the message is loaded into the UART holding register. Because the $\mathrm{DH} / \mathrm{DN}$ resets the bits in this register, the program must use BIS instructions to亡u set these bits.

### 6.1.7 BREAK CONTROL REGISTER (X14)

This register contains one bit for each line; where bit $n$ is the bit for line n. The program sets the bit for a line to start the transmission of a break on that line and resets the bit to terminate the transmission of the break. (Refer to paragraph 6.4 for break control timing information.)
6.1.8 SILO STATUS REGISTER (X16)
Eit Description

15 Silo Maintenance. When set, this read/write bit causes a fixed binary pattern to be sent to the silo for checking.

14 Not used.

13 - 08 Silo Fill Level. These read-only bits indicate the number of characters currently held in the siło. 000000 can indicate either an empty silo or a silo with more than 63 characters. For an empty silo, the valid data present bit (15) of the next received character register is reset while for a silo with more than 63 characters, it is set. Also if an attempt has been
made to load another character into a full silo, then the storage overflow bit (14) of the system control register is set.

07, 06 Read Extended Memory. These read-only bits are Al7 and Al6 of the current address register for the line whose number is held in the line selection field (bits 03 through 00) of the system control register.

05-00 Silo Alarm Level. When the silo fill level exceeds the value written into this read/write field by the program, receiver interrupt bit 07 of the system control register is set. If receiver interrupt enable bit 06 of the system control register is set, this causes an interrupt. If there are fewer than sixteen characters in the silo, there may be a delay of up to 20 ms before setting this bit. This reduces interrupt overhead.

### 6.2 MODEM REGISTERS

The DM portion implements a software compatible subset of the DEC DM1l-BB. It contains two Unibus addressable registers, the control and status register and the line status register. As illustrated in Figure 6-3, the byte-wide line status register is actually a register group that includes one register for each line. When the line status register group is addressed, the particular register is read or written as determined by the line number held in the control and status register. The following paragraphs describe the two registers. Figure 6-4 illustrates register formats.

Note: The only actual signals are Ring, Carrier, and Data Terminal Ready. All others exist for software compatibility.

### 6.2.1 CONTROL AND STATUS REGISTER

Bit Description

15 Ring Flag. This read-only bit and DONE (bit 7) are set when a transition from OFF to ON is detected for the RING signal from the line specified by bits 3 through 0 . Setting CLEAR SCAN (bit ll) resets the stored value of RING so that an existing ON condition appears as a transition and sets this bit and DONE.

14 Carrier Flag. This read-only bit and DONE (bit 7) are set when any transition of the CARRIER signal from the line specified by bits 3 through 0 is detected. Setting CLEAR SCAN (bit ll) resets the stored value of CARRIER so that an


Figure 6-3: Modem Registers


CONTROL AND STATUS REGISTER (770XXO) (See Section 6.2.1)


LINE STATUS REGISTER (770XX2) (See Section 6.2.2)

Figure 6-4: Modem Register Formats
existing on condition appears as a transition and sets this bit and DONE.

Clear to Send Flag. This read-only bit and DONE. (bit 7) are set when any transition of the CLEAR TO SEND signal from the line specified by bits 3 through 0 is detected. Setting CLEAR SCAN (bit ll) resets the stored value of CLEAR TO SEND so that an existing ON condition appears as a transition and sets this bit and DONE.

Secondary Receive Flag. This read-only bit and DONE (bit 7) are set when any transition of the SECONDARY RECEIVE signal from the line specified by bits 3 through 0 is detected. Setting CLEAR TO SCAN (bit ll) resets the stored value of SECONDARY RECEIVE so that an existing ON condition appears as a transition and sets this bit and the DONE bit.

Clear Scan. Writing a ONE into this write-ONE-only bit generates a pulse which clears bits $9,7,6,5$, and 3 through 0 and initiates a sequence which.clears the scan memory. With the scan memory cleared, any ON condition of a RING, CARRIER, CLEAR-TO-SEND, or SECONDARY RECEIVE signal is detected as a change of state during subsequent scanning and causes the associated change flag (bits 15 through 12) to set.

Clear Multiplexer. Writing a ONE into this write-ONE-only bit generates a pulse which clears bits 3 through 0 (SECONDARY TRANSMIT, REQUEST TO SEND, DATA TERMINAL READY, LINE ENABLE) of all 16 line status registers.

Maintenance Mode. Setting this read/write bit forces the RING, CARRIER, CLEAR TO SEND, and SECONDARY RECEIVE inputs to the line scanner to the ON condition for test purposes. If this is preceded by the writing of a ONE into CLEAR SCAN (bit ll) then an interrupt (if enabled) should be generated for every line that is scanned.

Step. Each time that a ONE is written into this write-ONEonly bit, a STEP sequence having a duration of $1 \mu \mathrm{sec}+10 \%$ is initiated. During this sequence, the line number held in bits 3 through 0 is incremented, signals from the newly addressed line are evaluated for transitions, and change flags (bits 15 through 12) and the DONE flag (bit 7) are set if any transitions are detected. This bit can be used rather than SCAN ENABLE (bit 5) to provide a scan rate controlled by the program. Note, however, that this scan rate should be high enough so that CARRIER signals will not switch ON and OFF during the interval between successive
scans of a line. Note also that DONE does not inhibit STEP.

07 Done. This read/write bit is set when bit 15, 14, 13, or 12 sets. With DONE set, the line scanner is disabled so that bits 3 through 0 continue to contain the number of the line associated with the condition which causes DONE to set. If INTERRUPT ENABLE bit 6 is also set, an interrupt normally resets DONE so as to release the line scanner. This bit is also reset by INITIALIZE and by CLEAR SCAN (bit ll).

06 Interrupt Enable. When this read/write bitt is set, the DM interrupt function is enabled. The bit is cleared by INITIALIZE and by CLEAR SCAN (bit ll).

Scan Enable. When this read/write bit is set the DM is placed in the automatic scanning mode. In this mode, the scanner increments the line number held in bits 03 through 00 and checks for transitions of the signals from the newly addressed line at a rate of approximately 1 microsecond per line until a transition is found. At this time the appropriate transition flag (bits 15 through 12) and DONE (bit 07) are set. Scanning is then inhibited until the program resets the DONE bit.

04 Busy. This read-only bit is set when lines are being scanned. Program should change line number (bits 03 through 0) only when BUSY is 0.

03 - 00 Line Number. These read/write bits, held in a counter, point to one of the 16 line-status registers and select inputs from one of the 16 lines for transition detection. The line number is incremented at the start of each scan cycle and is reset to 0000 by INITIALIZE or by CLEAR SCAN (bit 11). Notice, that since the incrementing of the count occurs at the start of each scan cycle, the first line tested after a reset is 0001 rather than 0000.

### 6.2.2 LINE STATUS REGISTER

Bit Description

07 Ring. This read-only bit indicates the status of the modem RING signal.

06
Carrier. This read-only bit indicates the status of the modem CARRIER signal.

```
November 4, 1983
```

TO: All Engineers
FROM: John G. Poffenroth
SUBJ: Able Dh/DM Settings
The following are switch settings for Able DH/DM for
following address. Please retain for future use.
DHØ 7 6øø2ø @ $4 \varnothing \varnothing$
DMØ $77 \emptyset 5 \emptyset \varnothing$ @ $44 \varnothing$
S1 ----- 5 Open
S2 ----- 2 Open
S3 ---- 1,3,7,8, Open
S4 ---- 2, 3, 4,5,6,7,8, Open
S5 ----- 2,3,4,5,6,7, Open
S6 ----- 1,2,3,4,6,7, Open

Thank you,
JGP/crew

## DISTRIBUTION:

G. Maxwell
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C. Reams
S. Wesinger

05 Clear to Send. This read-only bit indicates the status of the modem CARRIER signal.

Secondary Receive. This read-only bit indicates the status of the modem SECONDARY RECEIVE signal.

Secondary Transmit. When set, this read/write bit presents a MARK to the SECONDARY TRANSMIT input of the modem. This bit is reset by INITIALIZE or by CLEAR MUX (bit"IO) of the control and status register.

Request to Send. This is used to condition the modem to transmit if all other conditions are met. The bit is cleared by INITIALIZE and CLEAR MUY. It is Read/write.

01 Data Terminal Ready. This bit allows the modem to enter and maintain the data mode. It is cleared by INITIALIZE and CLEAR MUX. This bit is Read/hrite.

00 Line Enable. This bit enables the state of RING, CARRIER, CLEAR TO SEND, and Sec Rx to be sampled by the program and tested for transitions. It is cleared by INITIALIZE and CLEAR MUX. This bit is Read/Write.

## 6.3

TRANSMITTER/RECEIVER SPEED PROGRAMMING CONSIDERATIONS
In the DHil, speed code 1110 selects External Input A. In the DH/DM, this speed code selects 19.2 K baud. In the DHll, speed code 1111 selects External Input B. In the DH/DM, this speed code selects the output of a clock on the board that can be set for any speed in the range from 150 to 9600 baud. The output of this source is also selected in response to speed code 0110 which in the DHll, selects 200 baud. The DH/DM is shipped with this source set to provide the 200 baud rate. Thus, the user has the option of retaining the 200 baud rate selection in response to the DH1l 200 baud speed code or, if this rate is not required, of obtaining a selèctable rate in response to the DHll External E speed code.

In the $D H / D M$, different non-zero receiver and transmitter speeds can be selected for a given line only if one of these rates is obtained from the source shared by the 200 baud and External P speed codes. If this restriction is not observed, the programmed transmitter speed determines both the transmitter and the receiver speeds for the line.

The zero baud selection provides the means by which the program can turn off any line. A useful application of this capability involves turning off unused line receivers in the presence of excessive circuit noise so as to avoid the receipt of spurious characters.

### 6.4 BREAK CONTROL TIMING

In order to time the transmission of a break so that no significant message characters are lost, the transmitter interrupt associated with a dürmy. message containing two null characters is used to time the setting of the EREAK bit for the line.

The use of the dummy message is necessary because the transmitter interrupt indicates the completion of the message transfer from the message buffer in the computer memory to the DH/DM rather than the completion of the message transmission by the DH/DM. This interrupt timing allows the program to write message ( $n+1$ ) in the message buffer and write the starting address and word count for this message while the final characters of message $n$ are being transmitted. Specifically, at the time of the transmitter interrupt, there are two message characters still to transmitted, one in the UART transmit holding register. Thus, by using the interrupt associated with the dummy message to time the setting of the EREAK bit, the break is started when the two null characters of this message reside in these registers. (The break begins at the instant that the PREAK bit for the line is set in the break control register.)

A second dummy message can be used to time the duration of the break. This message should be made up of null characters, since the last two characters are actually transmitted after the transmitter interrupt associated with the message has been used to time the resetting of the EREAK bit for the line. This timing method provides a break duration equal to the character period times the number of characters in the second dummy message. (The break ends before the final two characters of the second dummy message are transmitted but it includes the two character periods of the first dummy message transmission.)

### 6.5 TRANSMITTER AND RECEIVER TIMING CONSIDERATIONS

Because characters are transmitted asynchronously, message integrity is not affected by the speed with which characters are supplied to the UART. Continous transmission is achieved if the UART transmit holding register receives character ( $n+1$ ) during the period when character $n$ is being transmitted. Since the DH/DM uses word accesses to PDP-ill memory, only one DMA access is required for every two transmit characters. However, to maintain continous transmission each access must be completed within one character period of its initiation.

The 255 -word silo provdes buffer storage for received characters. If the silo becomes full, then characters cannot be transferred to it from UART receiver holding registers. Thus, if this happens, characters may be overwritten in one or more UART modules. The amount of time that the program has to service a receiver interrupt depends upon the number of lines from which messages are currently being received, the receiver speeds, and the silo alarm level value that has been written in the silo
status register. A low silo alarm level value increases the time available to respond to the interrupt. However, if the program responds immediately, the lower value increases program overhead because more interrupts will have to be serviced to transfer a given number of characters. The DH/DM decreases this overhead by interrupting after sixteen characters have been received or after 20 ms have passed since the first character is received.

If the transfer of a character from the holding register of a UART receiver has to be inhibited because the silo is full, STORAGE INTERRUPT bit 14 of the system control register is set and if STORAGE INTERRUPT ENA ELE bit 12 is set, an interrupt request is initiated to inform the program that the silo is full. The program may still have time to empty the silo before an overrun occurs.

### 6.6 MAINTENANCE MODE CONSIDERATIONS

When maintenance bit 9 of the system control register) is set, the UART modules are placed in the local loopback mode. In this mode, the receiver input from the line is ignored, the transmitter output to the line is held at the marking level, and the serial output from each UART transmitter shift register is connected to the serial input of the receiver shift register so that each character transmitted by the transmitter section is received by the receiver section. The silo is reduced to 64 words and the clock is forced to 200 baud.

Also, when MAINTENANCE is set, the PDP-ll program can write the STORAGE INTERRUPT, NON-EXISTENT-MEMORY INTERRUPT, and RECEIVER-INTERRUPT (system control register bits 14,10 , and 07 ) which are normally read only.

When SILO MAINTENANCE bit 15 of the silo status register) is set, a 1010101010101010 is loaded into the silo. Each successive clearing and setting of SILO MAINTENANCE loads another copy of this pattern into the silo. In order to fill the silo with this test pattern, all receiver speeds must be set to zero baud and the silo must be emptied of previously received line characters.

When the DH/DM cables are installed in the loopback connectors, the following occur:

- Silo size is reduced to 64 words.
- On-board clock is forced to 200 baud.
- Secondary transmit and secondary receive are internally looped together.
- Clear to Send is the same as Carrier.
- Ring and Request to Send are internally looped together.


## Appendix A

Priority Strapping

This appendix contains a wiring chart for priority interrupt levels. The DH/DM is factory set to level $R 2$ for the DH and BR4 for the DM. For most users these are the correct interrupt levels and no strapping changes are needed.


OPTIONAL INTERRUPT LEVEL STRAPPING
(Use only if you wish to use Priority Interrupt Levels, that differ from standard DEC levels.)


[^0]:    Figure 5-3: Wiring Chart For Modnm Connection

[^1]:    Figure 5-3: Wiring Chart For Modem Connection (Con't.)

