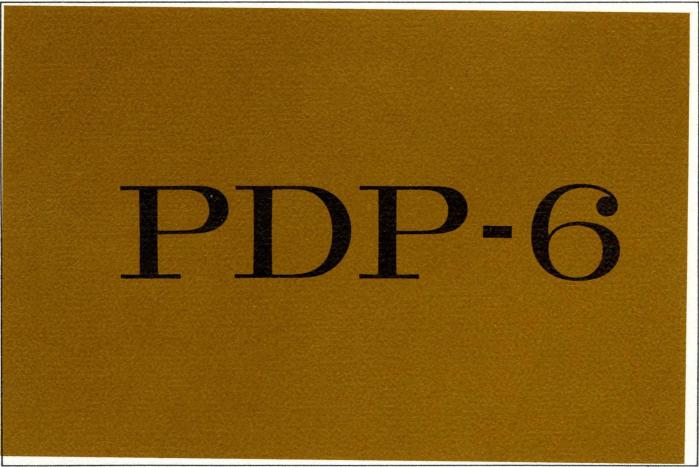
PROGRAMMING EXAMPLES



DIGITAL EQUIPMENT CORPORATION . MAYNARD, MASSACHUSETTS

PDP-6 PROGRAMMING EXAMPLES

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INTRODUCTION

This manual contains examples of programming for the PDP-6 Type 166 Processor. They have been chosen to illustrate both the arithmetic and logical capabilities of the processor. For an explanation of the instructions shown see the PDP-6 Handbook (F-65). The examples use the same instruction mnemonics as the MACRO-6 assembler. The language is described in the MACRO-6 Manual (F-64MAS).

Times based on design estimates are shown in some of the examples. All of the instruction times have been conservatively calculated. For example, no attempt has been made to take advantage of speed gains due to memory overlapping. Two of the examples show how time may be saved by moving to fast memory a short program which executes a large number of iterations. One of these, Character Manipulation, is programmed in both a straightforward manner and by being moved to fast memory in order to show the break-even point between the time gained and the increased overhead time. The second, Two-bit Testing, was programmed for 500 iterations. In this case there is a considerable gain in time by moving the program to fast memory. The last example, Any Radix Print, demonstrates the use of recursion to shorten programs.

Sixteen examples are contained in this booklet:

- 1. Single Precision Integer Arithmetic
- 2. Double Precision Integer Arithmetic
- 3. Floating Point Arithmetic
- 4. Fix a Floating Point Number
- 5. Float a Fixed Point Integer
- 6. Repetitive Calculation
- 7. Subscripts
- 8. Exponentiation
- 9. Character Manipulation
- 10. Character Translation
- 11. Character Addition
- 12. Fifteenth Degree Polynomial
- 13. Evaluation of Complex Polynomial

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- 14. Matrix Inversion
- 15. Two-Bit Testing and Depositing of Data
- 16. Any Radix Print

SINGLE PRECISION INTEGER ARITHMETIC

Assume:	1) A, B, C, D, E, F, G, H, J, K, L,	M, N, and P are arbit	rary memory locations.
	2) Arguments and instructions are in the	e same memory module.	
	3) No scaling is required.		
	4) Y indicates 1 of the 16 accumulators	s	
		Time	in microseconds
	A=B+C		
	/EY, B		4
	Y, C /EM Y, A		$\frac{4}{12}$
		Total	12
	D=E+F+G	,	
MOY	/E Y, E		4
	Y, F Y, G		4 4 $\frac{4}{16}$
	/EM Y, D		4
		Total	16
	H=JxK		
	/E Y, J		4
	L Y, K /EM Y, H		13.6 4
MO		Total	$\frac{4}{21.6}$
	L=MxN+I	P	
MOY	/E Y, M		4
	L Y, N 9 Y, P		13.6 4
	/EM Y, L		4
		Total	25.6

DOUBLE PRECISION INTEGER ARITHMETIC

Assume:

- 1) A, B, C, D, E, F, G, H, J, K, L, M, N, and P are arbitrary memory locations, each denoting a block of two consecutive memory registers.
 - 2) Each integer is stored in two consecutive memory locations with the high order integer in the first location and the low order integer in the second.
 - 3) Instructions and arguments are in same memory module.

Time in microseconds

٨	=B	±C	
- A	=D	+C	

JFCL16, . +1,	CLEAR STRAY FLAGS	2.1
MOVE 0, B		4.0
MOVE 1, B + 1		4.0
ADD 1, C+1,	ADD LOW ORDER PARTS	4.0
JFCL 2, D1,	DID LOW ORDER PARTS OFLO	2.1
D2: ADD 0, C,	ADD HIGH ORDER PARTS	4.0
MOVEM 0, A,	STORE RESULTS	4.0
MOVEM 1, A+1		4.0

D1: AOJA 0, D2

COMPENSATE FOR OVERFLOW 3.3 Total 28.2-31.5

D=E+F+G

JFCL 16, . + 1,	CLEAR STRAY FLAGS	2.1
MOVE 0, E		4.0
MOVE 1, E + 1		4.0
ADD 1, F + 1,	ADD LOW ORDER PARTS	4.0
JFCL 2, DD1,	DID LOW ORDER PARTS OFLO	2.1
DD1A: ADD 1, G + 1,	ADD LOW ORDER PARTS	4.0
JFCL 2, DD2,	OVERFLOW?	2.1
DD2A: ADD 0, F	ADD HIGH ORDER PARTS	4.0
ADD 0, G		4.0
MOVEM 0, D,	STORE ANSWERS	4.0
MOVEM 1, D+1		4.0
•		

•

DD1: AOJA 0, DD1A, DD2: AOJA 0, DD2A, COMPENSATE FOR OVERFLOW 3.3 COMPENSATE FOR OVERFLOW 3.3 Total 38.3-44.5

Time in microseconds

K=J_xK

MOVE 0, J		4.0
MULO, K,	MULTIPLY HIGH ORDER PARTS	14.0
MOVE 2, J + 1		4.0
MUL 2, K,	MULTIPLY LOW (J); HIGH (K)	14.0
JFCL 16, . + 1,	CLEAR STRAY FLAGS	2.1
ADD 1, 2,	SUM PRODUCTS	4.0
JFCL 2, M1	OVERFLOW?	2.1
MIA: MOVE 2, J,	MULTIPLY HIGH (J), LOW (K)	4.0
MUL 2, K + 1		14.0
ADD 1, 2,	SUM PRODUCTS	4.0
JFCL 2, M2	OVERFLOW?	2.1
M2A: MOVEM 1, H + 1,	STORE RESULTS	4.0
MOVEM, H		4.0
M1: AOJA 0, M1A	COMPENSATE OVERFLOW	3.3
MA2 A CO LA O MA2A	COMPENIENTE OV/EDELOW/	2 2

M2: AOJA 0, M2A

COMPENSATE OVERFLOW 3.3 COMPENSATE OVERFLOW 3.3 Total 76.3-82.9

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FLOATING POINT ARITHMETIC

Assume:	1) A, B, C, D, E, F, G, H, J, K, L, M, N, and P are arbitrary memory locations.		
	2) Arguments and instructions are in the same memory module.		
	3) Y indicates 1 of the 16 accumulators.		
	A=B+C		
MOVE Y FAD Y, (MOVEM		4.0 5.8 <u>4.0</u> Total 13.8	
	D=E+F+G		
MOVE Y FAD Y, F FAD Y, O MOVEM	: G	4.0 5.8 5.8 <u>4.0</u> Total <u>19.6</u>	
	H=J×K		
MOVE Y FMP Y, I MOVEM		4.0 12.6 <u>4.0</u> Total 20.6	
MOVE Y FMP Y, I FAD Y, I MOVEM	, M N S	4.0 12.6 5.8 <u>4.0</u> Total <u>26.4</u>	

PROBLEM: Consider an eight block table with 100 entries in each block. Let A, B, C, D, E, F, G, and H denote the first location of each block. For each entry find:

$$G = (A-B)^{2} + (C-D)^{2}$$

H = (G/E) x F

Assume: 1) All entries in normalized floating point.

2) Argument and instructions are in the same memory module.

FLOATING POINT ARITHMETIC (continued)

Time in microseconds

BEGIN:	MOVSI 1, 🕈 D100	2
	MOVE 2, A(1)	4
	FSB 2, B(1)	6.2
	FMP 2, 2	12.3
	MOVE 3, C(1)	4
	FSB 3, D(1)	6.2
	FMP 3, 3	12.3
	FAD 2, 3	5.5
	MOVEM 2, G(1)	4
	FDV 2, E(1)	18.0
	FMP 2, F(1)	12.8
	MOVEM 2, H(1)	4.0
	AOBJN 1, BEGIN+1	3.3

The total time for 100 repetitions: 92.6 \times 100 + 2 = 9.26 milliseconds

FIX A FLOATING POINT NUMBER

Assume: 1) A floating point number in any accumulator from 1–15 designated by F. The result is returned in F+1 module 16.

MULIF, 400,	EXPONENT IN F, FRACTION IN F+1
TSC F, F,	COMPLEMENT EXPONENT IF NEGATIVE
ASH F+1, -243(F),	TRUNCATE TO GREATEST INTEGER

FLOAT A FIXED POINT NUMBER

Assume: 1) A fixed point integer less than 2²⁷ in magnitude in accumulator C. TLC C, 233000, XOR INTO WORD

FAD C, 0, FLOATING ADD ZERO TO NORMALIZE

2) A fixed point integer I, $-2^{35} \le 1 < 2^{35}$, in accumulator F.

Note: Accumulator F+1 is used in the calculation.

IDIVI	F,400,	DIVIDE WORD INTO TWO PIECES
SKIPE	F;	SKIP IF NORMALIZED ZERO
TLC	F,243000,	XOR EXPONENT INTO F
TLC	F+1,233000,	XOR EXPONENT INTO F+1
FAD	F, F+1,	COMBINE AND NORMALIZE

REPETITIVE CALCULATION

The following are repeated 10000 times: A=B+C, D=E+F+G, H=JxK

Assume: 1) A, B, C, D, E, F, G, H, J, K, L, M, N, and P are arbitrary memory locations.

2) Arguments are in floating point.

3) Arguments and instructions are in the same memory module.

Time in microseconds

	MOVEI 2, D10000,	INITIALIZE COUNTER	2
B1:	MOVE 0, B		4
	FAD 0, Ć		5.2
	MOVEM 0, A		4
	MOVE 0, E		4
	FAD 0, F		5.2
	FAD 0, G		5.2
	MOVEM 0, D		4
	MOVE 0, J		4
	FMP 0, K		12.6
	MOVEM 0, H		4
	SOJN 2, B1,	COUNT	3
			55.2
		The total time for 10000	
		ropotitions	

repetitions:

 $55.2 \times 10000 + 2 = 0.552$ sec.

SUBSCRIPTS

Compute for I=1, 100 A(I)=B(I)+C(I) D(I)=E(I)+F(I)+G(I) H(I)=A(I)xD(I)

Assume: 1) The data is arranged in memory as follows:

B1, B2, ---B100, C1, C2, ---C100, E1, F1, G1, E2, F2, G2 ---E100, F100, G100, A1, D1, A2, D2 ---A100, D100, H1, H2, ---H100

Time in microseconds

	CLEARB 3, 2,	INITIALIZE INDEX REGISTERS	4.0
	HRLZI1, - 🕈 D100,	INITIALIZE INDEX COUNTER	2.0
:	MOVE 4, E(3)		4.0
	FAD 4, F(3)		6.0
	FAD 4, G(3)		6.0
	MOVEM 4, D(2),	D=E+F+G	4.2
	MOVE 0, B(1)		4.0
	FAD 0, $\dot{C}(1)$		6.0
	MOVEM 0, A(2)		4.2
	FMP 0, 4		12.3
	MOVEM 0, H(1)		4.2
	ADDI 2, 2,	INCREMENT 2 STEP INDEX	3.0
	ADDI 3, 3,	INCREMENT 3 STEP INDEX	3.0
	AOBJN 1, C1,	INCREMENT 1 STEP INDEX	
		AND COUNT	3.3

Total Time required is 0.062 seconds

C1:

EXPONENTIATION

, FLOATING POINT NUMBER TO A FIXED POINT POWER , COMPUTE X I USING ACCUMULATORS A1, A2, AND T. , STORE THE RESULT IN Y. IF X IS ZERO, RETURN ZERO

FEXP: MOVE A1, X MOVSI T, 201400 SKIPGE A2, I FDVM T, A1 MOVMS A2 JUMPN A1, FEXP2 CLEARB T, A2 FEXP1: FMP A1, A1 LSH A2, -1 FEXP2: TRZE A2, 1 FMP T, A1 JUMPN A2, FEXP1 MOVEM T, Y ;MOVE X TO A1 ;T1 = 1.0 ;MOVE I TO A2, SKIP IF NON-NEGATIVE ;TAKE RECIPROCAL OF X (NEGATIVE POWER) ;TAKE ABSOLUTE VALUE OF I ;GO TO MAIN LOOP (IF NON ZERO BASE) ;ZERO EXPONENT AND RESULT FOR QUICK EXIT ;SQUARE BASE TERM ;SHIFT RIGHT FOR NEXT BIT OF EXPONENT ;IS POWER A FACTOR? TURN OFF BIT ;YES ;MORE FACTORS? ;NO, STORE RESULT

CHARACTER MANIPULATION

- PROBLEM: There is a string of 7 bit ASCII characters beginning at memory location A and ending with a slash. Transfer the characters, excluding the slash to a block beginning at location B. Count the number of characters and leave the result in an index register.
- Assume: 1) The code for a slash is 74₈.

Program	Time in microseconds
MOVE 3, [POINT 7, B] MOVE 2, [POINT 7, A] MOVEI 1, 0 C: LDBI 0, 2 CAIN 0, "/" JRST EXIT DPBI 0, 3 AOJA 1, C	$ \begin{array}{c} 4 \\ 4 \\ 2.0 \\ 5 \\ 2.6 \\ 2.1 \\ 5 \\ 3.4 \\ \end{array} $
	Table Burne in 10 + 17 - Nicolaum

Total time is $18 + 16 \times N$ where N is the number of characters.

	MOVSI A1, CMOVP		2.0
	BLT A1, A1-1,	MOVE TO FAST MEMORY	17.6
	JRST CMOV		3.0
CMOV	/P: PHASE 0		
B1	0		
PTA:	POINT 7, A		
PTB:	POINT 7, B		
CMO	/: LDBI A1, PTB		5.0
	CAIN A1, 74		2.0
	JRST EXIT		2.0
	DPBI A1, PTB		5.0
CM:	AOJA B1, CMOV		2.0
	DEPHASE		
A1 = 0	CM + 1		

The time for this case is $31 + 14 \times N$.

CHARACTER TRANSLATION

- Assume: 1) That the number in accumulator A is a 6-bit code read from the card reader. The program must translate the card code into the equivalent 7-bit ASCII code. A translation table begins at location TAB consisting of 7-bit ASCII characters packed five to a word.
 - 2) The characters in this table are in order of their appearance in the card code. Because characters are packed five to a word, the quotient of the card code divided by 5 gives the word in which the ASCII character is found. The remainder gives the character position. An auxilliary table of five byte pointers, one pointing to each character position, allows retrieval of the proper ASCII with a single LDB instruction.
- TRANSL: IDIVI A,5 LDB A, BTAB (A+1) JRST EXIT BTAB: POINT 7, TAB (A), 6 7, TAB (A),13 POINT 7, TAB (A), 20 POINT 7, TAB (A), 27 POINT 7, TAB (A), 34 POINT TAB: **.**←1234**.** ASCII ASCII .56789. ASCII .Ø=@↑'. ASCII .\ /ST. .UVWXY. ASCII ASCII •Z;,(". •#%-JK• ASCII .LMNOP. ASCII ASCII .QR:\$*. .[>&+A. ASCII .BCDEF. ASCII ASCII /GHI?./

ASCII

.)]<!.

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CHARACTER ADDITION

PROBLEM: Add two 5 digit numbers expressed at 7-bit ASCII characters.

Calling Sequence: JSP AC3, ASCIAD

, ASCIAD:	A ROUTINE TO ADD OR SUBTRACT FIVE DIGIT ASCII NUMBERS (7 BIT CHARACTERS).
; ; ; ; ; ; ; ; ; ; ; ; ; ; ;	 CHARACTERS MUST BE RIGHT JUSTIFIED TO ENTER ROUTINE: MOVE ACO, (ADDEND) MOVE AC1, (AUGEND)/ MOVN AC1, (SUBTRAHEND) JSP AC3, ASCIAD ON RETURN THE SUM OR DIFFERENCE IS IN AC2 AND THE CONTENTS OF ACO AND AC1 ARE UNCHANGED THE ROUTINE IS A RING COUNTER; FOR EXAMPLE 99999+2=00001 and 3-6=99997 NOTE THAT TWO NEGATIVE NUMBERS CANNOT BE COMBINED AND THAT IF ONE IS NEGATIVE IT MUST APPEAR IN AC1 ON ENTRY.
; ; ;	
ASCIAD:	AND AC0, M2 IOR AC1, M4 TLZN AC1, 400000 ADD AC1, M1 ADD AC0, AC1 AND AC0, M3 MOVE AC2, M4 AND AC2, -3 SUBM AC0, AC2 IOR AC2, M4 JRST (AC3)
M1: M2: M3: M4:	BYTE (1) (7) 6, 6, 6, 6, 6 BYTE (1) (7) 17, 17, 17, 17 BYTE (1) (7) 77, 77, 77, 77, 77 BYTE (1) (7) 60, 60, 60, 60 AC0=0 AC1=1 AC2=2 AC3=3 END

FIFTEENTH DEGREE POLYNOMIAL

Assume: 1) P denotes a block of memory containing the 16 coefficients; \overline{X} is a memory location containing the argument; the answer is stored in location Z.

Time in microseconds

RADIX 10,	SET ASSEMBLER RADIX TO 10	
MOVE 3, X,	MOVE ARG TO FAST MEMORY	4.0
MOVEL2, 15	INITIALIZE INDEX COUNTER	2.0
MOVE 0, P + 15,	INITIALIZE VALUE	4.0
IMUL 0, 3,	MULTIPLY BY ARGUMENT	13.2
ADD 0, P-1 (2)	ADD NEXT LOWER COEFFICIENT	4.0
SOJGE 2,2,	INCREMENT AND COUNT	2.8
MOVEM 0, Z,	STORE ANSWER	4.0

Total time required is 314 microseconds

EVALUATION OF COMPLEX POLYNOMIAL

 $Y = P_o + P_1 X^1 + P_2 X^2 + \dots P_n X^n$ WHERE Y, X, and P are complex numbers.

The real parts of the coefficients, P, are stored in an array, the first location labeled P. The imaginary parts are stored in another array, PI. The argument is X (real part) and XI (imaginary part), the answer is placed in Y and YI, and the order is in N.

DATA STRUCTURE

P: BLOCK 14,	REAL COEFFICIENT PARTS
PI: BLOCK 14,	IMAGINARY COEFFICIENT PART
X: 0	REAL PART OF ARGUMENT
XI:0	IMAG. PART OF ARGUMENT
Y: 0	REAL PART OF ANSWER
YI:0	IMAG. PART OF ANSWER
N: 0	ORDER OF POLYNOMIAL
	т

Time in microseconds

MOVEI 4, N, MOVE 0, P (4), MOVE 1, PI(4), MOVE 2, X, MOVE 3, XI,	INITIALIZE INDEX COUNTER INITIALIZE ANSWER MOVE ARGUMENT TO FAST MEMORY	2.0 4.0 4.0 4.0 4.0
P13: MOVE 5, 1 FMP 5, 3, MOVE 6, 0 FMP 6, 3, FMP 0, 2, FSB 0, 5, FMP 1, 2, FAD 1, 6,	PI * XI P * XI P * X P * X - PI * XI = REAL PART PI * X P * XI + PI * X = IMAGINARY PART	2.4 12.2 2.4 12.2 12.2 5.6 12.2 5.4
FAD 0, P–1 (4), FAD 1, PI–1 (4) SOJGE 4, P13	ADD NEXT LOWER COEFFICIENT	6.0 6.2 4.0
MOVEM 0, Y, MOVEM 1, YI	STORE ANSWER	4.0 4.0

 $TIME = 28 + 80.8N \mu sec.$

Example: A 13th Degree Polynomial Requires 1.04 milliseconds.

MATRIX INVERSION

PROBLEM: To invert an NxM matrix, stored row-wise in sequential locations beginning with A.

,CALLING SEQUENCE:

,CALL: JSP 17, INVER

- , EXPA
- , JRST ERROR

, THE ORDER OF THE MATRIX IS IN A, WITH THE NUMBER OF ROWS IN THE LEFT HALF, , AND THE NUMBER OF COLUMNS IN THE RIGHT HALF. THE ELEMENTS ARE STORED , ROW-WISE BEGINNING IN A+1

, IF THE INVERSION WAS SUCCESSFUL IT WILL RETURN TO CALL +3, AND IF A ZERO , PIVOT ELEMENT OR OVERFLOW OCCURRED , IT WILL RETURN TO CALL +2

, ACCUMULATOR ASSIGNMENTS

- T=15 , PIVOT ELEMENT
- J=14 , COLUMN SUBSCRIPT
- K=13 , ROW SUBSCRIPT
- P=12 , INDEX POINTING TO PIVOT ELEMENT
- PT=11 , MULTIPLIER
- LC=10 , STOP COUNTER
- LCS=7 , ROW COUNTER
- INVERT: HRRZ @ (17) MOVEM, ROWS[#] HLRZ @ (17) MOVEM, COLS[#] MOVE [XWD ROWPRG, ROW] BLT ROWL;

HRR ROW, (17)

;GET COLUMN COUNT

;GET ROW COUNT ;MOVE ROW SUBROUTINE INTO FAST MEMORY

;SET UP PROGRAM ADDRESSES

ADDI ROW, 1 HRR ROW+2, (17) HRR ROW+3, ROW ADDI ROW+2, 2 HRRM ROW, INZ1+1 HRRM ROW, DIV+2 HRRM ROW, DIV+6 HRRM ROW, INZROW+1 HRRM ROW+2, DIV

MOVEI P, 0 MOVN T, COLS MOVE T, 1 (T) HRRM T, INZ1

INZSTP:	MOVELK, 0 MOVE LCS, ROWS MOVE J, P	;INITIALIZE INVERSION STEP
INZ1:	HRLI J, O SKIPN T, A(P) JRST 1 (17)	;GET PIVOT ELEMENT ;IF IT IS ZERO, EXIT AS ERROR
DIV:	MOVE A+1 (J) FDV T MOVEM A(J)	;DIVIDE PIVOT ROW THROUGH BY ;PIVOT ELEMENT
	AOBJN J, DIV MOVSI 1.0B53 FDV T MOVEM A(J)	;LAST ELEMENT OF PIVOT ROW
INZROW:	MOVE J, P MOVE PT, A(K)	;INITIALIZE TO PROCESS A ROW
	CAMN K, P JRST ROWSKP	;IF THE ROW IS THE PIVOT ROW, ;SKIP IT
ROWOUT:	JRST ROW MOVN@ ROW FMP PT MOVEM@ROW+2	;GO TO PROGRAM IN FAST MEMORY ;HANDLE FINAL ELEMENT OF THE ROW
CTX:	SOJN LCS, INZROW ADD P, COLS	;IS STEP FINISHED?
	SOJN LC, INZSTP	;IS JOB FINISHED?
	JRST 2(17)	;RETURN
ROWSKP:	ADD K, COLS JRST CTX	;SKIP PIVOT ROW DURING ;INVERSION STEP
, THIS PROG		EMENTS IN A ROW IS MOVED INTO FAST MEMORY
ROWPRG: PHASE 1		
ROW:	MOVN A(J) FMP PT FAD A+1 (K) MOVEM A(K) ADDI J, 1 AOBJN K, ROW	
ROWL: DEPHASE END	JRST ROWOUT	

TWO-BIT TESTING AND DEPOSITING OF DATA

PROBLEM: Consider four tables with 500 registers a table. The entries of the first table contain a 2-bit item, ITEM zeros, in bits 13 and 14. The entries of the second table contain ITEM ones in bits 1-6; the third table contains ITEM twos in bits 1-9; and the fourth table contains ITEM threes in bits 1-10.

For n = 1, 500

- If ITEM $0_n = 0$ Set: ITEM $1_n = 10_8$ ITEM $2_{n} = 100_{8}$ ITEM $3_{n} = 300_{8}$ Set: ITEM $1_n = 20_8$ If ITEM $0_p = 1$ ITEM $2_{n} = 200_{8}$ ITEM $3_{n} = 400_{8}$ If ITEM $0_n = 2$ ITEM $1_{n} = 30_{8}$ Set: ITEM $2_n = 300_8$ ITEM $3_{n} = 500_{8}$ If ITEM $0_n = 3$ ITEM $1_n = 40_8$ Set: ITEM $2_{n} = 400_{8}$ ITEM $3_{n} = 600_{8}$
- Program: For 500 cases, moving the program to fast memory results in a time saving of approximately 5000 microseconds.
 - HRLZIO, A BLTO, 17 JRST2

A:

0

XWD D-500,0 LDB 0, 14 ROT 0, 3 ADDI 0, 10 DPB 0, 15 ROT 0, 3

TWO-BIT TESTING AND DEPOSITING OF DATA (continued)

DPB 0, 16 ADDI 0, 200 DPB 0, 17 AOBJN 1, 2 JRST EXIT POINT 2, TAB0 (1), 14 POINT 6, TAB1 (1), 6 POINT 9, TAB2 (1), 9 POINT 10, TAB3 (1), 10

ANY RADIX PRINT

PROBLEM	:	To Print out a signed number in	an arbitrary radix.	
Assume: 1)		TOUT is the first location of an I/O Routine which exits by POPJ P,0. The argument to tout is in accumulator B.		
	2)	The output radix is stored in the this example is R.	address part of RADIX. The output radix in	
	3)	Place the number to be converte RADPT.This routine suppresses la	ed in accumulator A and call RADPT with PUSHJ P, eading zeros.	
RADPT:	M¢ PU	MPGE B, RADIX DVEI B, "-" ISHJ P, TOUT DVNS A	;IS NUMBER NEGATIVE? ;YES, GET ASCII MINUS SIGN ;OUTPUT THE MINUS SIGN ;TAKE ABSOLUTE VALUE OF ARGUMENT	
RADIX:	ID Hr	IVI A, R LM A+1, (P)	;QUOTIENT GOES TO A, REMAINDER TO A+1 ;SAVE REMAINDER IN LEFT SIDE OF LAST ;ITEM ON PUSH DOWN LIST ;IS QUOTIENT = 0?	
RADPT1 :	HL AC	ISHJ P, RADIX RZ B, (P) DDI B, 260 ST TOUT	;NO, GO BACK FOR ANOTHER DIGIT ;GET THE DIGIT OFF THE PUSHDOWN LIST ;CONVERT THE DIGIT TO ASCII ;GO TO THE I/O ROUTINE. TOUT EXECUTES ;A POPJ P, BACK TO RADPT1 OR (FINALLY) ;TO THE PLACE WHERE RADPT WAS CALLED.	

20-8/64