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#### Abstract

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[^0]HEWLETT-PACKARD

SERVICE MANUAL

MODEL 64310A

## SOFTWARE PERFORMANCE ANALYZER

## REPAIR NUMBERS

This manual applies directly to models with repair numbers prefixed 2245 A .

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## SAFETY SUMMARY

The following general safety precautions must be observed during all phases of operation, service, and repair of this instrument. Failure to comply with these precautions or with specific warnings elsewhere in, this manual violates safety standards of design, manufacture, and intended use of the instrument. Hewlett-Packard Company assumes no liability for the customer's failure to comply with these requirements.

## GROUND THE INSTRUMENT.

To minimize shock hazard, the instrument chassis and cabinet must be connected to an electrical ground. The instrument is equipped with a three-conductor ac power cable. The power cable must either be plugged into an approved three-contact electrical outlet or used with a three-contact to two-contact adapter with the grounding wire (green) firmly connected to an electrical ground (safety ground) at the power outlet. The power jack and mating plug of the power cable meet International Electrotechnical Commission (IEC) safety standards.

## DO NOT OPERATE IN AN EXPLOSIVE ATMOSPHERE.

Do not operate the instrument in the presence of flammable gases or fumes. Operation of any electrical instrument in such an environment constitutes a definite safety hazard.

## KEEP AWAY FROM LIVE CIRCUITS.

Operating personnel must not remove instrument covers. Component replacement and internal adjustments must be made by qualified maintenance personnel. Do not replace components with power cable connected. Under certain conditions, dangerous voltages may exist even with the power cable removed. To avoid injuries, always disconnect power and discharge circuits before touching them.

## DO NOT SERVICE OR ADJUST ALONE.

Do not attempt internal service or adjustment unless another person, capable of rendering first aid and resuscitation, is present.

## DO NOT SUBSTITUTE PARTS OR MODIFY INSTRUMENT.

Because of the danger of introducing additional hazards, do not install substitute parts or perform any unauthorized modification of the instrument. Return the instrument to a Hewlett-Packard Sales and Service Office for service and repair to ensure that safety features are maintained.

## DANGEROUS PROCEDURE WARNINGS.

Warnings, such as the example below, precede potentially dangerous procedures throughout this manual. Instructions contained in the warnings must be followed.

## WARNING

Dangerous voltages, capable of causing death, are present in this instrument. Use extreme caution when handling, testing, and adjusting.

# QUICK REFERENCE GUIDE - 64310A SOFTWARE PERFORMANCE ANALYZER. 

## OPERATION.

The sof tware performance analyzer is used with Hewlett-Packard 64000 series emulator subsystems. It is installed in the emulator subsystem like a model 64300A or 64302A logic analyzer, but does not replace them. Rather, it provides additional capabilities for monitoring the emulation bus. Unlike the logic analyzers, which operate only as a part of the emulation mode software, the software performance analyzer has its own separate mode of operation.

## ON-BOARD MICROPROCESSOR.

The 64310A has its own on-board microprocessor that communicates with the host development station via an asynchronous interface. The development station initializes the 64310A by sending a signal to the ansynchronous interface to reset the microprocessor. After receiving the signal, the microprocessor runs a reset routine that is resident in on-board ROM. When a failure prevents the host station from correctly communicating with the 64310A, most of the performance verification test results are not valid.

## PERFORMANCE VERIFICATION.

When the software performance analyzer is selected under <option_test> PV, the following tests are displayed.

PERFORMANCE ANALYZER RESET. Checks the microcontroller composed of a 68 B 09 microprocessor, ROM, and RAM.

MAINFRAME/ANALYZER INTERFACE. Checks interface, and RAM addressing capablility.
DATA ACQUISITION. Checks trigger and run latch and measurement context circuitry.
TIME, EVENT, AND SEQUENCE COUNTER. Checks programmable time, event and sequence counters.

STATISTICS. Checks the statistics circuitry composed of the time, event, and sequence counters, flip-flops, and interrupt controller. The statistics test may require removal of the emulation bus cables. A prompt indicates when this is necessary.

INTER-MODULE BUS. Checks the IMB interface between the 64310A and another option board with IMB capabilities. This test requires an IMB cable be connected between the 64310 A and the option board used as the IMB stimulus. When there is no other option board with IMB capabilities present, the inter-module bus test does not appear.

# QUICK REFERENCE GUIDE - 64310A SOFTWARE PERFORMANCE ANALYZER 

When the emulator connected to the 64310A is selected under <option_test> PV, the analyzer stimulus test is one of the tests displayed.

ANALYZER STIMULUS. Checks the 24 bit analyzer address bus, even though the emulator may have only a 16 bit address bus. For these emulators, the upper 8 bits may be tied high or low during testing. See Performance Analyzer Stimulus Test paragraphs in Section IV Performance Tests.

## BE AWARE OF THE FOLLOWING.

Under normal operating conditions, comparator chips U27-32 and U42-47 run hot, about 45 degrees centigrade.

There is a test switch on the board. When incorrectly set, the analyzer will not operate or selftest properly. See Basic Microcontroller Failure paragraphs in Section IV Performance Tests.

When using a 16 -bit-address emulator, the analyzer stimulus test may display 'Can count address $=$ FFxxxxH'. This occurs because the analyzer emulation address bus is 24 bits wide and some emulators tie the unused upper 8 bits high during testing.

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## SECTION I

## GENERAL INFORMATION

## 1-1. INTRODUCTION.

1-2. This service manual explains how to install, test, and service the Hewlett-Packard Model 64310A Software Performance Analyzer. Detailed operating instructions are provided in a separate operating manual supplied with the instrument.

Service information contained in this manual allows the user to isolate functional problems to the board or component level. Board level troubleshooting is in support of the Hewlett-Packard Bluestripe board exchange program.

1-3. Described in this section are instruments covered, the general features of the software performance analyzer, power supply loads, and its use with Hewlett-Packard emulators. Also included are conventions used in the manual.

1-4. Shown on the title page is a microfiche part number. This number can be used to order 4 x 6 inch microfilm transparencies of the manual. Each microfiche contains up to 96 photoduplicates of the manual pages.


Figure 1-1. Mode ${ }^{1}$ 64310A Software Performance Analyzer

## 1-5. RELATED SERVICE MANUALS.

1-6. Service manuals for the models listed below provide additional information that may be useful in servicing the analyzer.
a. Development station models 64100A and 64110A.
b. Internal analyzer models 64300 A and 64302A.

## 1-7. INSTRUMENTS COVERED BY THIS MANUAL.

1-8. Attached to the Model 64310A Software Performance Analyzer is a repair number tag. The repair number is in the form 0000A 00000 . It is in two parts; the first four digits and the letter are the prefix and the last five digits are the suffix. The prefix is the same for identical 64310A Software Performance Analyzers; but the suffix is different and uniquely identifies each analyzer manufactured. This manual applies to all 64310A Software Performance Analyzers with a repair prefix that is listed on the title page.

1-9. A model 64310A manufactured after the printing of this manual may have repair number not listed on the title page. The manual for the newer analyzer is accompanied by a yellow manual change supplement. The supplement explains how to adapt the manual to the analyzer.

1-10. In addition to change information, the supplement may contain information for correcting errors in the manual. To keep this manual as current and accurate as possible, Hewlett-Packard recommends that you periodically request the latest manual changes supplement. The supplement is identified by the manual print date and part number, both of which appear on the manual title page. Copies are available at the Hewlett-Packard sales/service of fices listed in the back of this manual.

## 1-11. DESCRIPTION.

1-12. The model 64310A Software Performance Analyzer consists of a single board and associated software. It is a 64000 series internal analyzer that connects to Hewlett-Packard emulators via emulation bus cables. The analyzer monitors only the emulator address and status buses. Using the inter-module bus (IMB), the analyzer can trigger, or be triggered by other option modules in the card cage.

1-13. The purpose of the software performance analyzer is to make measurements of software activity in the connected emulator. Basically, the analyzer can make six different types of measurements, perform statistical analysis of the measurements, and store the results on-board for access by the development station. Results of the measurements are expressed numerically and in bar graph form on the development station display.

## 1-14. ACCESSORIES SUPPLIED.

1-15. No accessories are supplied with the analyzer.

1-16. ADDITIONAL EQUIPMENT REQUIRED.
1-17. The Model 64310A Software Performance Analyzer must be connected to a Hewlett-Packard emulator controller that is installed in a Hewlett-Packard 64000 series development station.

## 1-18. POWER REQUIREMENTS.

1-19. Power requirements of the sof tware performance analyzer are shown in table 1-1.

Table 1-1. +5 Volt Power Supply Load
+5 volt supply; current $=5 \mathrm{amps}$ maximum

## 1-20. LEVEL OF SERVICE.

1-21. This is a final component-level service manual. It contains performance verification (PV) and signature analysis (SA) test information for component level service of the software performance analyzer. Detailed schematics and parts lists are provided to assist in the servicing of the board.

## 1-22. CONVENTIONS.

$1-23$. The following conventions are used in the text and schematics.
a. Abbreviations, see table 6-1.
b. Mnemonics (signal names); see table 8-2.

The letters to the left of the slash (/) indicate the electrical status of the signal. The letters to the right of the slash show the signal function. For example, L/STB is low/strobe. Typical status indicators are:

L=low, or latched, $\mathrm{H}=$ high, $\mathrm{B}=$ buffered, $\mathrm{E}=\mathrm{ECL}$
Both TTL- and ECL-level signals are used. The ECL signal menemonics have an E in the electrical status. For example, EL/ANAL is the ECL version of the TTL signal L/ANAL. Mnemonics that do not have electrical status are assumed to be TTL with no predominant active level. For example, POL is a polarity signal.
c. Logic symbols, see table 8-3.
d. Sof tkeys are indicated by arrow brackets, while normal keys are shown in square brackets. For example, <stop> indicates the software labeled stop key, while [RETURN] indicates the keyboard labeled return key.
e. Component designators are assigned according to the upper left to lower right method.
f. Logic levels in volts:

| Input high <br> threshold | Input low <br> threshold | Output high <br> threshold | Output low <br> threshold |  |
| :---: | :---: | :---: | :---: | :---: |
| TTL +2.0 | +0.8 | +2.4 | +0.2 |  |
| ECL | -1.1 | -1.5 | -1.1 | -1.5 |

## SECTION II

INSTALLATION

## 2-1. INTRODUCTION.

2-2. This section contains information necessary to install the Model 64310A Software Performance Analyzer in a 64000 series development station. Also included is information concerning initial inspection, damage claims, environmental considerations, storage and shipment.

## 2-3. INITIAL INSPECTION

2-4. Inspect the shipping container for damage. If the shipping container or cushioning material is damaged, it should be kept until contents have been checked for completeness and the model 64310 A has been checked mechanically and electrically. If the contents are incomplete, if there is mechanical damage or defect, or if the model 64310 A does not pass performance verification, notify the nearest Hewlett-Packard sales/service office. If the shipping container or cushioning material is damaged, notify the carrier as well as the Hewlett-Packard office. Keep the shipping materials for carrier's inspection. The Hewlett-Packard office will arrange for repair or replacement at HP option without waiting for claim settlement.

## 2-5. SERVICE, CARD CAGE CONFIGURATIONS

2-6. When performing service tests, it is best to initially use the actual card cage operating configuration. When a normal operating configuration is not established, one of the configurations shown in figure $2-1$ can be used. Each configuration is designed to optimize cable lengths and positions within the card cage.

| To Pod | To Pod |  |
| :---: | :---: | :---: |
| [ Emulator Controller | ] [ State/Timing Acq | ] ...highest numbered slot |
| [ Internal Analyzer | ] [ State/Timing Ctl | ] |
| [ Soft Perf Analyzer | ] [ Soft Perf Analyzer | ] |
| [ Emulation Memory... | ] [ Internal Analyzer | ] |
| [ | ] [ Emulator Controller | ] |
| [ | ] [ Emulation Memory... | ] |
| Internal-Only | Internal-External |  |

Figure 2-1. Typical Card Cage Configurations

2-7. When connections between the analyzer options and the target system are required, the external-internal configuration is preferable. For example, this configuration is used when the model 64600 S Logic Timing Analyzer, or the 64620 S Logic State Ańalyzer subsystems are present.

2-8. When no external connections are required between analyzer options and the target system, the internal-only configuration is better. For example, this configuration is used when the model 64300A or 64302A Logic Analyzers are the only analyzer options present.

2-9. In either case, complete testing of the software performance analyzer is not possible unless an emulator subsystem and an option card with IMB capabilities are connected to the software performance analyzer via emulation and IMB cables. When an emulator is not present, the analyzer stimulus test cannot be performed. This reduces the number of circuit nodes tested by approximately $22 \%$. When no option board with IMB capablities is present, the software performance analyzer's Inter-Module Bus test is not executed.

## CAUTION

The Model 64310A Software Performance
Analyzer must be installed and removed with
the development station power turned off.

## 2-10. INSTALLATION.

2-11. For detailed installation instructions, refer to the operating manuals for the option boards required in the card cage. For quick reference, the basic steps are presented below

2-12. To install the option boards necessary for complete testing of the software performance analyzer, perform the following steps.
a. Remove the card cage cover. Position the development station so there is clear access to the card cage.
b. Install the emulator control board and the emulator pod.
c. When the emulator requires emulation memory option boards, install the memory controller first, then the memory board(s).
d. Install an option board with inter-module bus capabilities.
e. Install the software performance analyzer.
f. Use two 50 -pin cables to connect the edge connectors on the emulation bus.
g. Use a 20 -pin cable to connect the edge connectors on the inter-module bus.

## 2-13. REMOVAL.

2-14. To remove the software performance analyzer, proceed as follows:
a. Remove the card cage cover. Position the development station so there is clear access to the card cage.
b. Locate the software performance analyzer. The extraction tabs on the analyzer are labeled PERFANL and 64310A.
c. Remove the two 50 -pin emulation cables; and remove the 20 -pin inter-module bus cable.
d. Unseat the analyzer by lifting up the outside edges of the extractor tabs.
e. The software performance analyzer can now be removed by sliding it out of the card cage slot.

## 2-15. OPERATING ENVIRONMENT.

2-16. The Model 64310A Software Performance Analyzer can be operated in environments within the limits shown below. It should be protected from temperature extremes which cause condensation within the instrument.

Temperature .0 to +40 degrees Celsius.
Humidity $\qquad$ 5 to $80 \%$ relative humidity.
Altitude. $4,600 \mathrm{~m}(15,000 \mathrm{ft})$.

## 2-17. STORAGE AND SHIPPING ENVIRONMENT.

2-18. The software performance analyzer can be stored and shipped in environments within the limits given below.

$$
\begin{aligned}
& \text { Temperature.............. }-40 \text { to }+40 \text { degrees Celsius. } \\
& \text { Humidity................................ } 15,240 \mathrm{~m}(50,000 \mathrm{ft}) \text {. }
\end{aligned}
$$

## 2-19. ORIGINAL PACKAGING.

2-20. Containers and packing materials identical to those used in factory packaging are available through Hewlett-Packard sales and service offices.

## 2-21. OTHER PACKAGING.

2-22. The following general instructions should be used for repackaging with commercially available materials.
a. Wrap the Model 64310A Software Performance Analyzer in heavy paper or plastic Use a strong shipping container. A double wall carton made of 350 pound test material is adequate.
b. Use a layer of shock absorbing material 70 to 100 mm ( 3 to 4 inch) thick around all sides of the model 64310 A to provide firm cushioning and prevent movement inside the container
c. Seal shipping container securely.
d. Mark shipping container FRAGILE to request careful handling.
e. In any correspondence, refer to instrument by model number and full repair number.

## SECTION III

## OPERATION

The operation of the Model 64310A Software Performance Analyzer is a function of the 64000 Logic Development System software and is beyond the scope of this service manual. Please refer to the software performance analyzer operator manual.

## SECTION IV

## PERFORMANCE TESTS

## 4-1. INTRODUCTION.

4-2. This section describes the performance verification (PV), and signature analysis techniques, for testing and troubleshooting the sof tware performance analyzer.

Troubleshooting of the analyzer may be carried out to the component level, as described in this section, or to the module level. Although not specifically described in this section, module level repair simply involves replacement of the analyzer board if any of the performance verification tests fail. Module level repair is supported by the Hewlett-Packard Bluestripe exchange program.

## 4-3. SYSTEM CONSIDERATIONS.

4-4. Failure isolation must be performed to eliminate other sections of the logic development system as the source of the failure. It is assumed in this manual that the development station PV has been successfully conducted and that other option cards have also been checked. It is also assumed that the target system being emulated has been disconnected from the emulator pod, thus eliminating it as a possible source of the failure.

## 4-5. PERFORMANCE VERIFICATION TESTS.

4-6. The performance verification for the software performance analyzer is a subsection of the system Option Test Performance Verification. The system level PV tests all option modules that are located in the development station card cage. In addition, the PV can be used as a stimulus for troubleshooting using signature analysis techniques.

## 4-7. REQUIRED EQUIPMENT.

a. Development station with most recent PV software.
b. To test the inter-module bus (IMB), a nother option card with IMB capabilities must be present and connected to the software performance analyzer via an IMB cable. Some products that have this capability are a Model 64302A Wide Logic Analyzer, 64601A Timing Control Board, 64621 A State Control Board, or another software performance analyzer.
c. To test the comparator circuitry and emulation bus latches, an emulator must be connected to the software performance analyzer via emulation bus cables. The emulator performance verification sof tware must be available to run the analyzer stimulus test.
d. To print PV results, a printer must be attached to the system.
e. For troubleshooting, a Hewlett-Packard Model 545A Logic Probe, and 5005A Signature Multimeter, or equivalent equipment, is required.

## 4-8. STARTING PERFORMANCE VERIFICATION.

4-9. To test the sof tware performance analyzer proceed as follows.
a. With the operating system initialized and awaiting a command, figure 4-1, enter:
option__test [RETURN]
b. The PV now displays a directory of the installed option boards and their card slot numbers, figure 4-2. The first step in the PV is to locate the card slot of the Model 64310A Software Performance Analyzer and enter the slot number; for example, if it is in slot 8 of the card cage, enter:

## 8 [RETURN]

c. When the card cage contains no other option cards with Inter Module Bus (IMB) capabilites, the Total PV display appears, and IMB testing is automatically suppressed.
d. When one option card with IMB capabilities is present, the Total PV display appears and IMB testing is automatically activated. Make certain the IMB cable is connected, or the results of the test will be invalid.
e. When two or more option cards with IMB capabilities are present, the display prompts

> Select IMB external stimulus for test.
f. Enter the card slot of the option card to provide the stimulus. The Total PV Display then appears. Once chosen, the stimulus source can not be changed without restarting the software performance analyzer PV. Make certain the IMB bus cable is connected to the external stimulus board, or the results of the test will be invalid.

## 4-10. PERFORMANCE VERIFICATION AND THE MICROCONTROLLER.

4-11. The 64310A performance verification tests operate in a different manner from most other 64000 option cards because the analyzer has an on-board microprocessor, ROM and RAM. The on-board 68B09 microprocessor and associated ROM and RAM circuitry is referred to as the microcontroller. The development station processor does not have direct control over the analyzer microcontroller and must communicate with it via a handshake protocol, passing test data only when both the analyzer microcontroller and the development station are ready.

4-12. There are three 2 K byte RAMs in the microcontroller and one 2 K ROM. ROM U 35 contains all of the performance analyzer reset test code and the first three steps of the mainframe / analyzer interface test. Also in ROM U35 is code to transfer data between the analyzer and the development station. When the analyzer passes the tests contained in ROM U35, it loads PV code from the development station into RAM U38 to perform further tests.


Figure 4-1. System Awaiting Command Display

HP 64000 Option Performance Verification

| Slot \# ID | Module |  |
| :--- | :--- | :--- |
| 5 | $01 F 8 H$ | 128 Kbyte Emul Memory |
| 6 | $0201 H$ | Wide Address Memory Controller |
| 7 | $0101 H$ | Software Perf Analyzer |
| 8 | $0 i 02 H$ | Wide Emulation Analysis |
| 9 | $00 F 0 H$ | General Purpose Controller - -8086 Pod |

STATUS: Awaiting option_test command $\qquad$ 10:10
option_test
$\langle S L O T \#\rangle$ $\qquad$
$\qquad$
$\qquad$
$\qquad$ print

Figure 4-2. Card Cage Directory Display

4-13. When the analyzer microcontroller is not executing code correctly, the development station may never receive the results of the requested test; therefore, the station has a test timeout feature. When a time-out occurs, the screen displays

Test fails because of no response from 64310A Performance Analyzer !
4-14. The time-out error message may appear only on the data acquisition; time, event, and sequence counter; statistics, inter-module, and analyzer stimulus tests.

## 4-15. PERFORMANCE VERIFICATION COMMANDS.

4-16. Each PV display provides prompting for commands that can be executed. These commands are selected by 'softkeys' that are defined in table 4-1.

Table 4-1. Performance Verification Softkeys
<cycle>.......................Starts highlighted test and continues through other tests. When pressed during cycling, it stops the testing.
<disp__test>..............Displays test details. (Use 'display __test' in command files.)
<end>..........................Terminates performance verification and returns to the card cage directory display. It resets all test and failure counters to zero.
<exit__test>..............Stops the test and returns to next higher level display.
<next__test>.............Moves highlight line to following test category.
<print>. $\qquad$ ..Outputs display to attached printer.
<start> $\qquad$ Begins the test. When pressed during testing, it stops the test.

## 4-17. TOTAL PV TEST DISPLAY.

4-18. Purpose. All test categories available for the card cage configuration are shown in this display. When one or more test categories have been executed, the results are displayed. Use the display to choose the test categories to be performed or to review the overall results of the PV.


Figure 4-3. Total PV Test Display

4-19. Running the Total PV. To run all the tests shown on the display, press the <cycle> softkey. Each test category is executed and the results are displayed. A complete cycle requires approximately 15 seconds. To stop the iterations, press the <cycle> sof tkey again.

4-20. Reading the Total PV Results. When the tests are complete, examine the \# Fail column. When all entries are zero, it indicates that $72 \%$ of the circuit nodes have been checked and no errors have been found. Another $22 \%$ of the nodes can be checked by running the emulator Analysis Stimulus Test described at the end of this section.

4-21. A non-zero value represents the number of errors detected in the test category. Determine the exact cause of the error by viewing the failed test category in detail. Do this by positioning the highlight line over the test category and pressing the $<$ disp__test $>$ sof tkey.

## 4-22. OVERALL TROUBLESHOOTING STEPS.

## 4-23. Begin at paragraph 4-8. Starting Performance Verification.

4-24. When the software performance analyzer is in the card cage, but does not appear in the card cage display, troubleshoot the board ID circuit. See schematic 1.

4-25. If the Total PV Display does not appear, the software performance analyzer PV software is not available, and must be loaded.

4-26. Go to paragraph 4-17. Total PV Test Display.
4-27. Cycle through the tests, and look at the mainframe / analyzer interface test, \# Fail column. When there is an interface test failure, go to paragraph 4-70. Mainframe / Analyzer Interface Test Troubleshooting. Do not attempt to troubleshoot any other failures until the interface test executestsuccessfully.

4-28. When the mainframe / analyzer interface test is executing successfully, begin troubleshooting of other failures in the same sequence as the tests appear in the Total PV Display. Go to the paragraphs shown below, as appropriate.
a. 4-106. Data Aquisition Test Troubleshooting
b. 4-120. Time, Event, and Sequence Counter Test Troubleshooting
c. 4-150. Statistics Test Troubleshooting
d. 4-168. Inter-Module Bus Test Troubleshooting
e. 4-187. Analyzer Stimulus Test Troubleshooting




## 4-29. PERFORMANCE ANALYZER RESET TEST DISPLAY.

4-30. Purpose. This test checks microprocessor U33 for its ability to run the reset program stored in ROM U35. RAM U38 is tested for address and data errors, while RAMs U36 and U37 are tested for data errors only.


Figure 4-5. Performance Analyzer Reset Test Display

4-31. Running the Performance Analyzer Reset Test. To view this test display, begin with the Total PV Display (figure 4-3). Position the highlight line over 'Performance Analyzer Reset' and then press the <disp_test> softkey. Next, press the <start> softkey to begin the test. The test continues to run until a sof tkey is pressed. The test takes less than five seconds per iteration.

4-32. Reading the Performance Analyzer Reset Test Results. The \# Fail column always shows the letters ' $\mathrm{N} / \mathrm{A}^{\prime}$ ', meaning 'not available'. This is because approximately every five seconds the development station sends the analyzer a reset. The reset causes the microcontroller to execute the reset test stored in ROM U35, but no test results are transferred back to the development station.

4-33. Errors can be identified on the LED lights at the top edge of the analyzer board. Details on decoding these errors are given in the following paragraphs.

4-34. How. The test resets the analyzer to run code from ROM U35. This routine is run every time the analyzer is configured; thus, each PV test includes execution of this reset code at least once.

4-35. There are eight steps within the reset test. At the start of the test, the status lights at the top of the analyzer board are initialized. As each step begins, the lights are updated. When a test fails, microprocessor U33 executes an endless loop; thus, the lights are locked-up and indicate the test step that failed. There is no accumulation of errors and the development station cannot communicate with the analyzer at this point in the testing.

4-36. Results. The test results are interpreted by reading lights abcdefg at the top of the board. Between each iteration of the reset test there is a pause, and the light pattern is momentarily static. Note the exact pattern at this point; when it matches the last pattern shown below (code 11), all steps of the reset test are executing correctly. When there is a different pattern, decode the specific test that is failing. Light o should be illuminated in all steps, except the very first.



Figure 4-6. Status Light Decoding

4-37. When the reset test is successfully completed, the analyzer signals the development station that it is ready to transfer data. At this point the station can request the remaining PV tests be performed. As these tests are executed, the status lights continue to be updated. However, the lights cannot be decoded to identify an error, because the microcontroller does not lock up when an error is detected. The table below indicates the nature of the status light activity.

| Light | 7 Bit |  |
| :---: | :---: | :---: |
| Pattern | Code | Test in Progress |
| o abc defg |  |  |
|  |  | MAINFRAME / ANALYZER INTERFACE TEST |
| $x$ 00x 0000 | 10 | Enable interrupts \& stacking in RAM |
| x 00x 000x | 11 | Opcode output to performance analyzer |
| $x$ 00x 00xo | 12 | Data input from performance analyzer |
| x oox ooxx | 13 | Data output to performance analyzer |
| $x$ oox oxoo | 14 | RAM address line check (U36) |
| $x$ oox oxox | 15 | RAM address line check (U37) |
|  |  | DATA ACQUISITION TEST |
| $x 0 \times 00000$ | 20 | Trigger and run latch control |
| $x$ oxo 000x | 21 | Comparator bus |
| $x$ oxo 00xo | 22 | Status qualifier RAM data |
| x oxo 00xx | 23 | Status qualifier RAM address |
| x 0 oxx 0000 | 30 | Context state register reset |
| x oxx ooxo | 32 | Context FPLA 1 checksum |
| x 0xx 00xx | 33 | Context FPLA 2 checksum |
| x oxx $0 \times 00$ | 34 | U57 check, using FPLA 1 sum |
|  |  | TIME, EVENT, AND SEQUENCE COUNTER TEST |
| x x 000000 | 40 | Time, event, and sequence counter reset |
| x x 00000 x | 41 | Time, counter walking 1,0 and decrement |
| x xoo ooxo | 42 | Event counter walking 1,0 and decrement |
| x xoo 00xx | 43 | Sequence counter walking 1,0 and decrement |
|  |  | STATISTICS TEST |
| x xox 0000 | 50 | Interrupt controller reset and response |
| $x$ xox 000x | 51 | Time counter response |
| x xox 00xo | 52 | Event counter control |
| x xox 00xx | 53 | Time sequence counter |
| x xox $0 \times 00$ | 54 | Event sequence counter |
| x xox oxox | 55 | Counter error response |
|  |  | INTER-MODULE BUS TEST |
| x xxo 0000 | 60 | EL/ME drive |
| x xxo 000x | 61 | EL/TE drive |
| x xxo 00xo | 62 | $E H / T R$ drive |
| x xxo 00xx | 63 | EL/ME and EL/TE receive |
| $\mathrm{x} \times \mathrm{xO} 0 \times 00$ | 64 | EL/ME, EL/TE, and EH/TR enable line test |

Figure 4-7. Status Light Activity

4-38. PERFORMANCE ANALYZER RESET TROUBLESHOOTING.

4-39. Use these troubleshooting instructions to determine the nature of the failure found in the mainframe / analyzer interface test. The performance analyzer reset test must be running during this troubleshooting.

4-40. THERE IS STATUS LIGHT ACTIVITY.

4-41. When there is some status light activity, decode the light pattern using paragraph 4-36. Results. Determine which of the following status light test conditions exists.

All reset tests pass (code 11) or A reset test has failed.
Note the status light test condition, and if pertinent, note the failing test, and suspected component. Return to the mainframe / analyzer interface test troubleshooting for signature analysis LOOP B instructions.

## 4-42. THERE IS NO STATUS LIGHT ACTIVITY.

4-43. Verify that the reset test is running by watching the \# Test indicator. Each time the \# Test counter increments, the eight status lights should show some activity.

4-44. When there is no activity, use a logic probe or signature analyzer etc., and check microprocessor U33, pin 37 RESET. When it is not pulsing, there is an interface problem; use signature analysis Loop A instructions below. When it is pulsing, go to the paragraphs on basic microcontroller failure below.

## 4-45. SIGNATURE ANALYSIS - LOOP A.

4-46. Connect the signature analyzer as directed for SA Loop A, in Appendix A. The performance analyzer reset test provides the stimulus and must be running when signatures are taken. Reference schematics 1 and 2 in Section VIII. Check the components that process the reset signal, and check the basic microprocessor power and control.

Schematic 1, check: U89, U91. Schematic 2, check: U33.

## 4-47. BASIC MICROCONTROLLER FAILURE.

4-48. If RESET is pulsing, the software performance analyzer is receiving the reset signal from the development station. The microprocessor is not executing code correctly; thus, there is probably something wrong in the basic microcontroller. Possible problem areas are:

Microprocessor U33. ROM U35. Control or power supply line.
Address or data line shorted or open. Test switch SU 34 set incorrectly.
Status light circuits

4-49. At this point, signature analysis is not possible; therefore, test switch SU34 is used. To test microprocessor U33, perform the steps shown below. When the switch is set to the test position, a one-byte opcode is jammed onto the data bus. This causes the microprocessor to continually fetch this opcode; therefore, the address lines should be pulsing. While in the test position, probe each pin on microprocessor U33 to verify a high, low, or pulsing condition.
a. Turn off the development station power.
b. Remove the software performance analyzer from the development station. If necessary, see removal instructions in Section II.
c. Install the software performance analyzer on a service extender board.
d. Locate test switch SU34, and set to the test position. After testing, DO NOT FORGET to reset the switch to the normal operating position.

| Normal | Test |
| :--- | :--- |
|  |  |
| open | closed |
| open | closed |
| closed | open |
| closed | open |
| closed | open |
| closed | open |
| closed | open |
| closed | open |
| closed | open |
| closed | open |

Figure 4-8. SU34 Test Switch Positions
e. Place the analyzer and extender back into the development station.
f. Turn on the power and start the software performance analyzer PV.
g. SELECT the performance analyzer reset test and start it running.
h. Using a logic probe, signature analyzer, etc., test each pin on microprocessor U33. See table 4-2 for expected pin status; and refer to schematic 2 in Section VIII.

1) Are pin 7 Vcc and pin 1 ground valid?
2) Is pin 38 EXTAL pulsing ?
3) Is pin 37 RESET going from an active low to a high ?
4) Is pin 34 E pulsing ?
5) Is pin 32 READ/WRITE high, indicating a read operation?
6) Is the microprocessor status correct; pin 6 BA low, and pin 5 BS pulsing?
7) Is the microprocessor data bus correct;

LHLHHHHH on pins 31 thru 24 ? L=low, H=high.
8) Are all the microprocessor address lines pulsing; pins 8 thru 23?
9) Are all the buffered address lines pulsing; U48 and U49?
i. When all of the pins checkout, the interface between the microprocessor and ROM U35 is suspect. In this case check the ROM output enable pin $\mathrm{U} 35-20$; it should be low. Check the ROM chip select pin U35-18; it should be pulsing. It is possible that ROM U35 is faulty.
j. DO NOT FORGET to return the test switch to the normal operating position when the test of microprocessor U33 is completed.
k. If all pins checkout, it may be necessary to use an ohmmeter and check the continuity of the microcontroller circuitry shown on schematic 2.

4-50. After troubleshooting the failure, return to the mainframe / analyzer interface test paragraphs and re-run the test to see that the problem is corrected.

Table 4-2. Reset Test, Microprocessor U33 Troubleshooting

| Pin | Status | Pin | Status | Pin | Status | Pin | Status |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 1 | low | 11 | pulsing | 21 | pulsing | 31 | high |
| 2 | high | 12 | pulsing | 22 | pulsing | 32 | high |
| 3 | low | 13 | pulsing | 23 | pulsing | 33 | high |
| 4 | pulsing | 14 | pulsing | 24 | low | 34 | pulsing |
| 5 | pulsing | 15 | pulsing | 25 | high | 35 | pulsing |
| 6 | low | 16 | pulsing | 26 | low | 36 | pulsing |
| 7 | high | 17 | pulsing | 27 | high | 37 | pulsing |
| 8 | pulsing | 18 | pulsing | 28 | high | 38 | pulsing |
| 9 | pulsing | 19 | pulsing | 29 | high | 39 | low |
| 10 | pulsing | 20 | pulsing | 30 | high | 40 | high |

## 4-51. MAINFRAME / ANALYZER INTERFACE TEST DISPLAY.

4-52. Purpose. The first three tests shown on this display check the ability of analyzer to receive and send selected information to the development station. The last two tests check the analyzer microprocessor's ability to address RAMs U36 and U37.


Figure 4-9. Mainframe / Analyzer Interface Test Display

4-53. Running the Mainframe / Analyzer Interface Test. To view this test display, begin with the Total PV Display (figure 4-3). Position the highlight line over 'Mainframe / Analyzer Interface' and then press the <disp_test> softkey. Next, press the <start> softkey to begin the test. The test continues to run until a softkey is pressed. Each iteration takes less than 8 seconds, if there are no failures. Failures may lengthen the execution time.

4-54. Reading the Mainframe / Analyzer Interface Test Results. The \# Failures column shows the total number of errors detected during the test. Each error code in the result column represents a single failure encountered during the last iteration.

## 4-55. OPCODE OUTPUT TO PERFORMANCE ANALYZER.

4-56. How. After successful completion of the performance analyzer reset test, the analyzer signals the development station that it is ready to receive information. The station then sends the opcode sequence 0 through 20 H . After each opcode is sent, the station briefly waits for the analyzer to signal that it is ready to receive the next opcode. When the station does not receive a signal from the analyzer in the allotted time, a failure is recorded.

4-57. Results. When a failure is detected, the result column shows the next opcode that would have been sent to the analyzer. Thus, if the analyzer never sends a ready signal, the results are 00 H .

Op Code Output to Performance Analyzer......xxH

## 4-58. DATA OUTPUT TO PERFORMANCE ANALYZER.

4-59. How. When the opcode output test is successfully completed, the development station sends the data sequence 0 through FFH. After each data word is sent, the station briefly waits for the analyzer to signal that it is ready to receive data. When the station does not receive a signal from the analyzer in the allotted time, a failure is recorded.

4-60. Results. When a failure is detected, the result column shows next data word that would have been sent to the analyzer.

Data Output to Performance Analyzer........xxH

## 4-61. DATA INPUT FROM PERFORMANCE ANALYZER.

4-62. How. Upon successful completion of the data input test, the analyzer sends the development station the data sequence 0 through FFH. The station compares the data received with expected values; any discrepancies are recorded as failures.

4-63. Results. When an error is detected, the result column shows the exclusive OR product of data-sent with data-expected. If the two previous tests have not passed, the results of this test are probably invalid.

Data Input from Performance Analyzer.......xxH

## 4-64. RAM ADDRESS LINE CHECK (U36).

4-65. How. Each address bit is tested by writing zero to the lowest address in RAM U36. At this location all address lines are low. In sequence, each address line is brought high, and that location is loaded with FFH. The lowest address is read; it should contain zero. Any discrepancies from expected values is noted as an address bit error.

4-66. Results. The hexadecimal error word is decoded as follows.

RAM address line check (U36) $\times x x H=$

| Binary | Signal in Error |  |
| :---: | :---: | :---: |
| 000000000000 | None |  |
| -1 | L/ADR0 | U36-8 |
| ---1- | L/ADR 1 | U36-7 |
| -1-- | L/ADR 2 | U36-6 |
| -------- 1--- | L/ADR 3 | U36-5 |
| -------1 ---- | L/ADR 4 | U36-4 |
| 1----- | L/ADR 5 | U36-3 |
| -- | L/ADR6 | U36-2 |
| -- | L/ADR 7 | U36-1 |
| -1-------- | L/ADR 8 | U36-23 |
| - | L/ADR 9 | U36-22 |
| - | L/ADR 10 | U36-19 |
| - | na |  |

4-67. RAM ADDRESS LINE CHECK (U37).
4-68. How. Each address bit is tested by writing zero to the lowest address in RAM U37. At this location all address lines are low. In sequence, each address line is brought high, and that location is loaded with FFH. The lowest address is read; it should contain zero. Any discrepancies from expected values is noted as an address bit error.

4-69. Results. The hexadecimal error word is decoded as follows.

RAM address line check (U37) $x x x H=$

| Binary | Signal in Error |  |
| :---: | :---: | :---: |
| 000000000000 | None |  |
| ----1 | L/ADR0 | U37-8 |
| ---- --1- | L/ADR 1 | U37-7 |
| ------1-- | L/ADR 2 | U37-6 |
| - | L/ADR 3 | U37-5 |
| $1-$ | L/ADR 4 | U37-4 |
| -1----- | L/ADR 5 | U37-3 |
| -1------ | L/ADR6 | U37-2 |
| 1--- ---- | L/ADR 7 | U37-1 |
| -1-------- | L/ADR 8 | U37-23 |
| --1--------- | L/ADR 9 | U37-22 |
| -1---------- | L/ADR 10 | U37-19 |
| --------- | na |  |

## 4-70. MAINFRAME / ANALYZER INTERFACE TEST TROUBLESHOOTING.

## 4-71. ANY OF THE FIRST THREE SUBTESTS FAIL

4-72. When one or more of the first three subtests fail, the microcontroller has a malfunction. Go to paragraph 4-38. Performance Analyzer Reset Troubleshooting and determine the nature of the problem. If directed, return here to the signature analysis LOOP B paragraphs.

## 4-73. SIGNATURE ANALYSIS - LOOP B.

4-74. Connect the signature analyzer as directed for SA Loop B, in Appendix B. The mainframe / analyzer interface test provides the stimulus and must be running when signatures are taken. Reference schematic 2 in Section VIII.

4-75. When one of the status light tests fails, the microcontroller is executing code, but part of the microcontroller circuit is failing. Check the basic microcontroller circuitry: the microprocessor, ROM, RAM, data bus transceiver, address bus buffers, I/O decoder, wait-state shift register, and miscellaneous gates and inverters.

Schematic 2 , check: U33, U35, U36, U37, U38, U39, U48, U49, U50, U51, U52, U53, U65, U66.

4-76. When all of the status light tests pass (code 11), the microcontroller is executing code correctly, but is unable to transfer data to the development station correctly. Check the address and data interface with the development station.

Schematic 1, check: U86, U87, U88, U92, U93.

4-77. THE FIRST THREE SUBTESTS PASS, BUT A RAM TEST FAILS.
4-78. When this happens, troubleshoot the failing RAM test. Test results can be decoded using the information in Results paragraphs for the interface test.

4-79. SIGNATURE ANALYSIS - LOOP B.

4-80. Connect the signature analyzer as directed for SA Loop B, in Appendix B. The mainframe / analyzer interface test provides the stimulus and must be running when signatures are taken. Reference schematic 2 in Section VIII. Check the failing RAM.

Schematic 2, check: U36, U37, U38.

## 4-81. DATA ACQUISITION TEST DISPLAY.

4-82. Purpose. The seven tests shown on this display check the trigger and run latch and measurement context circuitry.


Figure 4-10. Data Acquisition Test Display

4-83. Running the Data Acquisition Test. To view this test display, begin with the Total PV Display (figure 4-3). Position the highlight line over 'Data Acquisition Test' and then press the <disp_test> sof tkey. Next, press the <start> softkey to begin the test. The test continues to run until a sof tkey is pressed. Each iteration takes less than 2 seconds.

4-84. Reading the Data Acquisition Test Results. The \# Failures column shows the total number of errors detected during the test. Each error code in the present column represents a single failure encountered during the last iteration. The cumulative error code represents the sum of all errors detected during the test. Cumulative error codes that differ from error codes in the results column indicate multiple, or intermittent errors. When the error codes are the same, the errors are systematic.

## 4-85. TRIGGER AND RUN LATCH CONTROL.

4-86. How. Six test steps are performed in the sequence described below. The reset command is H/HALT, U24-7.

1. Flip-flop U23 is reset; signal H/TRIGGER is read. It should be low.
2. Flip-flop U23 is set. Signal H/TRIGGER is read; it should be high.
3. Flip-flop U23 is reset again; H/TRIGGER should be low.
4. Signal $H / R U N$ is read, it should be low.
5. Flip-flop U22 is clocked; $H / R U N$ should be high.
6. Finally, flip-flop U22 is reset; H/RUN should be low.

4-87. Results. The error bits are decoded as follows.

Trigger and Run Latch Control...xxxxxx =

| Bits | Test Step in Error |
| :---: | :---: |
| 000000 | None |
| ---1 | H/TRIGGER U23-9 |
| ---1- | 2 H/TRIGGER U23-9 |
| --1-- | $3 \mathrm{H} /$ TRIGGER U23-9 |
| -1--- | 4 H/RUN U22-5 |
| -1---- | 5 H/RUN U22-5 |
| 1---- | 6 H/RUN U22-5 |

4-88. COMPARATOR BUS DATA.
4-89. How. Input latch U73 is enabled and drives output latch U75. Latch U73 is loaded in sequence with the decimal values 0 through 63. After each load, output latch U75 is read and compared with the loaded value.

4-90. Results. The hexadecimal error word is decoded as follows.

Comparator Bus Data......xxH $=$

| Binary | Signal in Error |  |  |
| :---: | :---: | :---: | :---: |
| 00000000 | None |  |  |
| ---1 | BH/COMOUT1 | U73-2 | U75-2 |
| ---1- | BH/COMOUT2 | U73-19 | U75-17 |
| --1-- | BH/COMOUT3 | U73-5 | U75-4 |
| $1-$ | BH/COMOUT4 | U73-16 | U75-15 |
| -1 | BH/COMOUT 5 | U73-6 | U75-6 |
| 1----- | BH/COMOUT6 | U73-15 | U75-13 |
|  | na |  |  |
|  | na |  |  |

## 4-91. STATUS QUALIFIER RAM DATA.

4-92. How. All 256 locations of emulator status RAM U11 are loaded in sequence with the data 0 through 3. After each load, the data is read back via output latch U75. The data read should match the loaded value. Note that only two of the four bits of RAM data are used.

4-93. Results. The error bits are decoded as follows.

Status Qualifier RAM Data.......xx =

| Bits | Signal in Error |  |
| :---: | :--- | :--- |
|  |  |  |
| 00 | None |  |
| -1 | H/QUAL 1 | U11-12 |
| $1-$ | H/QUAL 2 | U11-10 |

## 4-94. STATUS QUALIFIER RAM ADDRESS.

4-95. How. The first location in emulator status RAM U11 is 4000 H to microprocessor U33; and, at this address, all the status qualifier RAM address lines are low. The location is loaded, via latch U10, with zero. In sequence, each address line is brought high and OFH is loaded into the addressed location. After each load, location 4000 H is read. It should still contain 0 . If it does not, the last address bit brought high is displayed as a failure.

4-96. Results. The hexadecimal error word is decoded as follows.

Status Qualifier RAM address...xx =

| Binary | Signal in Error |  |  |
| :---: | :---: | :---: | :---: |
| 00000000 | None |  |  |
| --1 | L/ADR 0 | U10-9 | U11-4 |
| ---1- | L/ADR 1 | U10-6 | U11-3 |
| -1-- | L/ADR 2 | U10-5 | U11-2 |
|  | L/ADR 3 | U10-2 | U11-1 |
| -1---- | L/ADR 4 | U10-19 | U11-21 |
|  | L/ADR 5 | U10-16 | U11-5 |
|  | L/ADR6 | U10-15 | U11-6 |
| 1------- | L/ADR 7 | U10-12 | U11-7 |

4-97. CONTEXT STATE REGISTER RESET.

4-98. How. The context state flip-flops U56 and U68 are reset via decoder U69-12. The flipflops are then read via buffer U74. All bits should be zero.

4-99. Results. The hexadecimal error word is decoded as follows.

## Context State Register Reset...xxH =

Binary Signal in Error

| 00000000 | None |  |  |
| :---: | :---: | :---: | :---: |
| -1 | H/CONERR | U56-2 | U74-2 |
| -1- | L/CONEND | U56-15 | U74-17 |
| -1-- | H/GATE B | U56-10 | U74-4 |
| 1--- | H/GATE A | U56-7 | U74-15 |
| -1 ---- | H/STATE 1 | U68-2 | U74-6 |
|  | H/STATE 2 | U68-15 | U74-13 |
|  | H/STATE 3 | U68-10 | U74-8 |
|  | H/STATE 4 | U68-7 | U74-11 |

## 4-100. CONTEXT FPLA 1 CHECKSUM.

4-101. How. Logic array U76, measurement context 1 , is tested by doing a checksum. The outputs for each unique input condition to the array are added together. Input lines to the array come from mode latch U72, test latch U73, and emulator status RAM U11.

4-102. Results. The right hand bit indicates an error in performing the checksum when flipflop US7, pin 1 is held low. The left hand bit indicates an error in performing the checksum when flip-flop U57 pin 1 is held high.

Context FPLA 1 Check Sum........xx

## 4-103. CONTEXT FPLA 2 CHECKSUM.

4-104. How. Logic array U58, measurement context 2 , is tested by doing a checksum. The outputs for each unique input condition to the array are added together. Input lines to the array come from mode latch U72, test latch U73, and emulator status RAM U11. Flip-flop U57 pin 1 is held low.

4-105. Results. The results of this test are not decoded. A failure indicates an incorrect checksum.

4-106. DATA ACQUISITION TEST TROUBLESHOOTING.
4-107. Do not attempt to troubleshoot the data acquisition test until the mainframe / analyzer interface test has been successfully completed. Instructions in the preceding Results paragraphs provide information on how to determine which component is suspect.

4-108. SIGNATURE ANALYSIS - LOOP C.
4-109. Connect the signature analyzer as directed for SA Loop C, in Appendix C. The data acquisition test provides the stimulus and must be running when signatures are taken. Reference schematics 2, 5 and 7 in Section VIII. Check the components in the measurement context circuits, and the trigger and run control circuits.

Schematic 2 , check: U65.
Schematic 5, check: U58, U68, U69, U72, U73, U74, U75, U76, U77.
Schematic 7 , check: U5, U6, U7.

## 4-110. TIME, EVENT, AND SEQUENCE COUNTER TEST DISPLAY.

4-111. Purpose. The test shown on this display checks the programmable event counter U60, time counter U61 and sequence counter U62. It also tests the bidirectional data bus transceiver U70 and the statistics I/O decoder U85. The microcontroller sends commands to the programmable counters and reads back counter responses via the microcontroller data bus.


Figure 4-11. Time, Event, and Sequence Counter Test Display

4-112. Running the Time, Event, and Sequence Counter Test. To view this test display, begin with the Total PV Display (figure 4-3). Position the highlight line over 'Time, Event, and Sequence Counter' and then press the <disp_test> softkey. Next, press the <start> softkey to begin the test. The test continues to run until a sof tkey is pressed. Each iteration takes less than 3 seconds.

4-113. Reading the Time, Event, and Sequence Test Results. The \# Failures column shows the the total number of errors detected during the test. Each error code in the display represents a single failure encountered during the last iteration.

Sof tware Performance Analuzer verification
Performance Analuzer in carct siot $\# 7$
Time, Event, and Sequence Counter Test ……) \# Fail o \# Test o
 FFFF FFFF FFFF FFFF FFFF: FFFF FFFF FFFF FFFF FFFF: FFFF FFFF FFFF FFFF FFFF Master Mode $=$ FFFF; Master Mode $=$ FFFF; Master Mode $=$ FFFF Counter Register Walking One/Zero
FFFF FFFF FFFF FFFF FFFF: FFFF FFFF FFFF FFFF FFFF: FFFF FFFF FFFF FFFF FFFF FFFF FFFF FFFF FFFF FFFF: FFFF FFFF FFFF FFFF FFFF: FFFF FFFF FFFF GFFF FFFE FFFF FFFF FFFF FFFF FFFF: FFFF FFFF FFFF FFFF FFFF: FFFF FFFF FFFF FFFF FFFF
$80008000800080008000: 8000$ Counter Decrement $8000800080008000: 80008000800080008000$
STATUS: Awaiting option..test command
$\qquad$
$\qquad$
$\qquad$

Figure 4-12 a. Sample Transceiver or Decoder Failure


Figure 4-12 b. Sample Counter Failure

4-114. How. First, microprocessor U33 sends a reset command to programmable event counter U60, time counter U61, and sequence counter U62. The counters' internal hold and master mode registers are read and displayed; all bits should be zero after the reset.

4-115. Second, the counters' internal load and mode registers are loaded and read back with the sequence $1,2,4,8,16,32,64$, and 128 . Any discrepancy between the data written and read back is displayed as an error.

4-116. Third, all counters are loaded with OFFFFH and configured to count down in binary. The counters are then issued 0FFFDH step commands. The internal hold registers are read and should contain 0002 H . Any discrepancy is noted as an error in the display.

4-117. Results. Each character is a hexadecimal digit. Don't be intimidated by all the characters in the display; it is not necessary to decode each one. Look for general patterns. When all characters are zero, there are no test failures.

4-118. When there are non-zero characters in the display, a failure has been detected. Look at the distribution of the characters. When the non-zero characters appear under more than one counter heading, the bidirectional bus transceiver, or the statistics I/O decoder is failing the test. See figure 4-12a for an example.

4-119. When the non-zero characters appear under one counter heading, only the counter is failing the test. See figure 4-12b for an example.

## 4-120. TIME, EVENT, AND SEQUENCE COUNTER TEST TROUBLESHOOTING.

4-121. Do not attempt to troubleshoot the time, event, and sequence counter test until the mainframe / analyzer interface test and the data acquisition test have been successfully completed. Instructions in the preceding Results paragraphs provide information on how to determine which component is suspect.

## 4-122. SIGNATURE ANALYSIS - LOOP D.

4-123. Connect the signature analyzer as directed for SA Loop D, in Appendix $\mathbf{D}$. The data acquisition test provides the stimulus and must be running when signatures are taken. Reference schematic 6 in Section VIII. Check the event counter, time counter, sequence counter, data bus transceiver, and statistics I/O decoder.

Schematic 6, check: U60, U61, U62, U70, U85.

## 4-124. STATISTICS TEST DISPLAY.

4-125. Purpose. The seven tests shown on this display check the statistics interrupt controller U63 and the programmable event counter U60, time counter U61, and sequence counter U62. Each counter has several SOURCE and GATE inputs, and several OUT outputs.

4-126. Under software control, the counters are initialized, and configured to count transitions on a SOURCE input and produce an active OUT after a specified count. The context state flipflop U56 sends count enable signals to the counters. The active OUT results in an interrupt to interrupt controller U63, which, in turn, sends an IRQ interrupt to the microcontroller.


Figure 4-13. Statistics Test Display

4-127. Running the Statistics Test. To view this test display, begin with the Total PV Display (figure 4-3). Position the highlight line over 'Statistics' and then press the <disp_test> softkey. Next, press the <start> softkey to begin the test. The test continues to run until a softkey is pressed. Each iteration takes less than 1 second.

4-128. Reading the Statistics Test Results. The \# Failures column shows the total number of errors detected during the test. Each error code in the present column represents a single failure encountered during the last iteration. The cumulative error code represents the sum of all errors detected during the test. Cumulative error codes that differ from error codes in the results column indicate multiple, or intermittent errors. When the error codes are the same, the errors are systematic.

## 4-129. INTERRUPT CONTROLLER RESET.

4-130. How. Three test steps are performed in the sequence described below.

1. After interrupt controller U63 is initialized, the internal interrupt register is read; it should be zero.
2. Signal $H / C O N E R R$ is brought high and the interrupt request register is read; H/DATA6 should be high.
3. On the same read of the interrupt request register, H/TOOFAST is checked; H/DATA7 should be low.

4-131. Results. The error bits are decoded as follows.

Interrrupt Controller Reset........xxx $=$
Bits Test Step in Error
000 None
$--1 \quad 1$
-1- 2
1-- 3

## 4-132. INTERRUPT RESPONSE.

4-133. How. Two test steps are performed in the sequence described below.

1. Processor U33-3 IRQ interrupt is enabled and an IR6 interrupt is sent to controller U63. An IRQ interrupt service routine should be executed by processor U33.
2. All interrupts coming into interrupt controller U63 are masked out. Processor U33-3 IRQ interrupts are enabled and an IR6 interrupt is sent to the controller. An IRQ interrupt routine should not be executed.

4-134. Results. The error bits are decoded as follows.

Interrrupt Response. $\mathrm{xx}=$

| Bits | Test Step in Error |
| :---: | :--- |
|  |  |
| 00 | None |
| -1 | 1 |
| $1-$ | 2 |

## 4-135. TIME COUNTER CONTROL.

4-136. How. Eleven test steps are performed on time counter U61, in the sequence described below. In each test step, 25 MHz is the counting source.

1. Count SOURCE 1 with no gating; H/RUN held high. Causes active OUT 3 and interrupt IR 4.
2. Count SOURCE 1 with no gating; H/RUN held high. Causes active OUT 5 and interrupt IR 5 .
3. Count SOURCE 1 with no gating; H/RUN is held low. The result is an inactive OUT 5 and no interrrupt IR 5 .
4. Count SOURCE 1 , with gating on GATE 3 ; GATE 3 is held low; H/RUN is held high. The result is an inactive OUT 3 and no interrupt IR 4.
5. Count SOURCE 1, with gating on GATE 3; GATE 3 is held high; H/RUN is held high. The result is an active OUT__ 3 and interrupt IR4.
6. Count SOURCE 2, with no gating; H/RUN and H/GATE B are held high. Causes active OUT 5 and interrupt IR 5 .
7. Count SOURCE 2, with no gating; H/RUN is held high; H/GATE B is held low. The result is an inactive OUT 5 and no interrupt IR 5 .
8. Count SOURCE 3, with no gating; H/RUN and H/GATE B are held high. Causes an active OUT 5 and interrupt IR 5 .
9. Count SOURCE 4, with no gating; H/RUN and H/GATE A are held high. Produces an active OUT 5 and interrupt IR 5 .
10. Count SOURCE 4, with no gating; H/RUN is held high; H/GATE A is held low. Causes an inactive OUT_ 5 and no interrupt IR6.
11. Count SOURCE 5 with no gating; H/RUN and H/GATE A are held high. Produces an active OUT 5 and interrupt IR 6.

4-137. Results. The error bits are decoded as follows.

Time Counter Control.....xxxxxxxxxxx =

| Bits | Test Step in Error |
| :---: | :---: |
| 00000000000 | None |
| ----------1 | 1 |
| ---------1- | 2 |
| --------1-- | 3 |
| -------1--- | 4 |
| ----1---- | 5 |
| ---1----- | 6 |
| ----1------ | 7 |
| ---1------- | 8 |
| --1-------- | 9 |
| -1--------- | 10 |
| 1---------- | 11 |

## 4-138. EVENT COUNTER CONTROL.

4-139. How. Nine test steps are performed on event counter U 60 , in the sequence described below. In each test step H/PHASE 5 is the counting source.

1. Count SOURCE 1, with no gating. Produces an active OUT 3 and an interrupt IR 2.
2. Count SOURCE 1, with no gating. Produces an active OUT 5 and an interrupt IR 3.
3. Count SOURCE 1, with high GATE_3. Produces an active OUT 3 and an interrupt IR 2.
4. Count SOURCE 2, with no gating; H/GATE B is held high. Produces an active OUT 5 and an interrupt IR3.
5. Count SOURCE 2, with no gating; H/GATE B is held low. Produces inactive OUT 5 and no interrupt IR3.
6. Count SOURCE 3, with no gating; H/GATE B is held high. Produces an active OUT 5 and an interrupt IR 3.
7. Count SOURCE 4, with no gating. Produces an active OUT 5 and an IR 3. GATE_A should be high.
8. Count SOURCE 4 with no gating and low GATE_A. Produces inactive OUT 5 and no IR 3.
9. Count SOURCE 5 with no gating; H/GATE A is held high. Produces an active OUT 5 and an interrupt IR3.

4-140. Results. The error bits are decoded as follows.

Event Counter Control.......xxxxxxxx $=$

| Bits | Test Step in Error |
| :---: | :---: |
| 000000000 | None |
| --------1 | 1 |
| -------1- | 2 |
| ------1-- | 3 |
| -----1--- | 4 |
| ----1---- | 5 |
| ---1----- | 6 |
| --1------ | 7 |
| -1------- | 8 |
| 1-------- | 9 |

## 4-141. TIME SEQUENCE CONTROL.

4-142. How. Eleven test steps are performed on sequence counter (SC) U62, in the order described below. All test steps are performed with time counter U61 counting SOURCE 1; and SC U62 using time-counter OUT 1 as the counting source. Signal H/RUN is held high in all test steps.

1. With no gating; yields an active SC OUT 1 and interrupt IR 1.
2. With no gating, yields an active SC OUT 2 and interrupt IR0.
3. With no gating, yields an active SC OUT 3 and interrupt IR 3 .
4. With no gating, yields an active SC OUT 4 and interrupt IR 4.
5. With no gating, yields an active SC OUT 5 and interrupt IR 5 .
6. Starting SC counting on negative edge of GATE 1. No edge is sent, producing an inactive OUT 1 and no interrupt IR 1.
7. Starting SC counting on negative edge of GATE 1. An edge is sent, producing an active OUT 1 and interrupt IR1.
8. Starting SC counting on a high GATE 2. A low on GATE 2 produces an inactive OUT 2 and interrupt IR 0 .
9. Starting SC counting on a high GATE 2. A high on GATE 2 produces an active OUT 2 and interrupt IR 0 .
10. Starting SC counting on a high GATE 3. A low on GATE 3 produces an inactive OUT 3 and interrupt IR 3.
11. Starting SC counting on a high GATE 3. A high on GATE 3 produces an active OUT 3 and interrupt IR 3.

4-143. Results. The error bits are decoded as follows.

Time Sequence Control....xxxxxxxxxxx $=$

| Bits | Test Step in Error |
| :---: | :---: |
| 00000000000 | None |
| ---------1 | 1 |
| --------1- | 2 |
| -------1-- | 3 |
| ------1--- | 4 |
| -----1---- | 5 |
| ---1----- | 6 |
| ---1------ | 7 |
| --1------- | 8 |
| --1-------- | 9 |
| -1--------- | 10 |
| 1---------- | 11 |

## 4-144. EVENT SEQUENCE COUNTER.

4-145. How. Five test steps are performed on sequence counter (SC) U62, in the order described below. All test steps are performed with the event U60 counting SOURCE_1 and SC U62 counting event-counter OUT_1. Signal H/PHASE 5 is the counting source in all tests.

1. With no gating, yields an active SC OUT 2 and no interrupt IR1.
2. Starting SC counting on active high GATE 4. A low GATE 4 produces an inactive OUT 4 and no interrupt IR4.
3. Starting SC counting on active high GATE 4. A high GATE 4 produces an active OUT 4 and interrupt IR 4.
4. Starting SC counting on active high GATE 5 . A low GATE 5 produces an inactive OUT 5 and no interrupt IR 5.
5. Starting SC counting on active high GATE 5. A high GATE 5 produces an active OUT 5 and interrupt IR 5.

4-146. Results. The error bits are decoded as follows

Event Sequence Counter.........xxxxx =

| Bits | Test Step in Error |
| :--- | :--- |
| 00000 | None |
| ----1 | 1 |
| $--1-$ | 2 |
| $--1--$ | 3 |
| $-1---$ | 4 |
| $1---$ | 5 |

## 4-147. COUNTER ERROR RESPONSE.

4-148. How. Four test steps are performed in the order described below.

1. Signal H/OVERFLOW (U7-5) is brought low and the H/TRIGGER flag is reset. H/TRIGGER (U23-9) is read and should be low.
2. The H/TRIGGER flag is set via decoder U24-12. H/TRIGGER is read and should be high.
3. The H/TRIGGER flag is reset via decoder U24-10. The H/TRIGGER flag is then clocked via NOR gate U8-3. H/TRIGGER is read and should be high.
4. Signal H/OVERFLOW is brought low, the H/RUN flag is set, and the H/TRIGGER flag is reset. Then H/OVERFLOW is brought high, clocking the H/TRIGGER flag. H/TRIGGER is read and should be high.

4-149. Results. The error bits are decoded as follows.

Counter Error Response $\qquad$
Bits Test Step in Error

| 0000 | None |
| :--- | :--- |
| ---1 | 1 |
| $--1-$ | 2 |
| $-1--$ | 3 |
| $1---$ | 4 |

4-150. STATISTICS TEST TROUBLESHOOTING.
4-151. Do not attempt to troubleshoot the statistics test until the mainframe / a alyzer interface test, the data acquisition test; and time, event, and sequence counter test have been successfully completed. Instructions in the preceding Results paragraphs provide information on how to determine which component is suspect.

## 4-152. SIGNATURE ANALYSIS - LOOP E.

4-153. Connect the signature analyzer as directed for SA Loop E, in Appendix E. The data acquisition test provides the stimulus and must be running when signatures are taken. Reference schematics 6 and 7 in Section VIII. Check the components in the event, time, and sequence counter circuitry, and the toofast and trigger control logic.

Schematic 6, check: U60, U61, U62, U63, U64, U70, U78, U79, U80, U81, U82, U83, U84, U85.

Schematic 7, check: U5, U8, U19, U23.

## 4-154. INTER-MODULE BUS TEST DISPLAY.

4-155. Purpose. The test shown on this display checks the analyzer status latch U7, TTL-to-ECL converter U1, active terminator $U 2$, and the ECL-to-TTL converter $U 3$. When no card with IMB capabilites is present in the card cage, this test does not appear.


Figure 4-14. Inter-Module Bus Test Display

4-156. Running the Inter-Module Bus Test. To view this test display, begin with the Total PV Display (figure 4-3). Position the highlight line over 'Inter-Module Bus' and then press the <disp__test> softkey. Next, press the <start> sof tkey to begin the test. The test continues to run until a softkey is pressed. Each iteration takes less than 1 seconds.

4-157. Reading the Inter-Module Bus Test Results. The \# Failures column shows the total number of errors detected during the test. Each error code in the present column represents a single failure encountered during the last iteration. The cumulative error code represents the sum of all errors detected during the test. Cumulative error codes that differ from error codes in the results column indicate multiple, or intermittent errors. When the error codes are the same, the errors are systematic.

4-158. Test results are invalid, unless the software performance analyzer inter-module bus is connected by an IMB cable to the option card selected for IMB stimulus.

## 4-1 59. IMB MASTER ENABLE.

4-160. How. Two test steps are performed in the sequence described below.

1. The analyzer is configured to drive EL/ME high and the external module reads EL/ME; it should be high. The analyzer is then configured to drive EL/ME low and the external module reads EL/ME (U1-3); it should be low.
2. The analyzer is put into the IMB default mode and the external module reads EL/ME; it should be high.

4-161. Results. The error bits are decoded as follows.

IMB Master Enable $\qquad$ $\mathrm{xx}=$

| Bits | Test Step in Error |
| :---: | :--- |
| 00 | None |
| -1 | 1 |
| $1-$ | 2 |

## 4-162. IMB TRIGGER ENABLE.

4-163. How. Two test steps are performed in the sequence described below.

1. The analyzer is configured to drive EL/TE high and the external module reads EL/TE; it should be high. The analyzer is then configured to drive EL/TE low and the external module reads EL/TE (U1-12); it should be low.
2. The analyzer is put into the IMB default mode and the external module reads EL/TE; it should be high.

4-164. Results. The error bits are decoded as follows.

IMB Trigger Enable $\qquad$ $\mathrm{xx}=$

| Bits | Test Step in Error |
| :--- | :--- |
| 00 | None |
| -1 | 1 |
| $1-$ | 2 |

## 4-165. IMB TRIGGER.

4-166. How. Two test steps are performed in the sequence described below.

1. The analyzer is configured to drive $\mathrm{EH} / \mathrm{TR}$ high and the external module reads EH/TR; it should be high. The analyzer is then configured to drive EH/TR low and the external module reads EH/TR (U1-14); it should be low.
2. The analyzer is put into the IMB default mode and the external module reads EH/TR; it should be high.

4-167. Results. The error bits are decoded as follows.

IMB Trigger $\qquad$ $\mathrm{xx}=$

| Bits | Test Step in Error |
| :---: | :--- |
|  |  |
| 00 | None |
| -1 | 1 |
| $1-$ | 2 |

## 4-168. INTER-MODULE BUS TEST TROUBLESHOOTING.

4-169. Do not attempt to troubleshoot the inter-module bus test until the mainframe / analyzer interface test, the data acquisition test; the time, event, and sequence counter test; and the statistics test have been sucessfully completed. Instructions in the preceding Results paragraphs provide information on how to determine which component is suspect.

4-170. SIGNATURE ANALYSIS - LOOP F.
4-171. Connect the signature analyzer as directed for SA Loop F, in Appendix F. The data acquisition test provides the stimulus and must be running when signatures are taken. Reference schematic 7 in Section VIII. Check the flip- flops, gates, and TTL/ECL converters in the IMB and control circuits.

Schematic 7 , check: U1, U3, U5, U7, U8, U17, U18, U20, U22, U23.

## 4-172. SOFTWARE PERFORMANCE ANALYZER STIMULUS TEST.

4-173. The software performance analyzer stimulus test is not part of the software performance analyzer PV and cannot be run or viewed while the analyzer PV is running. The analyzer stimulus test is part of emulation software and an emulator must be installed before the test can be executed. Perform all other emulator tests before executing the analyzer stimulus test, or the stimulus test results may be invalid.

## NOTE

Do not proceed until all software performance analyzer PV tests have been successfully run. When any of the tests fail, results of the analyzer stimulus test may be invalid.

When running emulation PV, different emulators may display different names for this test, such as analysis test, analyzer stimulus, etc. Test procedures are the same regardless of name.

4-174. To execute the analyzer stimulus test proceed as follows.
a. Exit the software performance analyzer PV.
b. Make certain an emulator is installed. If necessary, refer to the emulator manual for installation instructions.
c. With the operating system initialized and awaiting a command, enter:
option_test [RETURN]
d. The PV now displays a directory of the installed option boards and their card slot numbers. Locate the card slot of the emulator and enter the slot number. For example, if the emulator controller is in slot 9 of the card cage, enter:

## 9 [RETURN]

e. When the software performance analyzer is the only analysis option in the card cage, the next display shows the emulation tests that can be performed. Position the highlight line over the analyzer stimulus test and press the <disp__test> sof they.
f. When the software performance analyzer is not the only analysis option in the card cage, the display prompts

## Select analyzer for test

Enter the card slot of the software performance analyzer; the next display shows the emulator tests that can be performed. Position the highlight line over analyzer stimulus test, and press the <disp__test> softkey.

4-175. ANALYZER STIMULUS TEST DISPLAY.

4-176. Purpose. The tests shown on this display check the emulation bus address latches U12-14, and address range comparators U27-32 and U42-47. The comparator selection circuitry U40,54, 55, 67 and comparator decoding circuitry U26 and U41 are checked. Also tested are the emulation status bus latch U 49 and part of the arming circuit U 7 and U 20 .


Figure 4-15. Analyzer Stimulus Test Display

4-177. Running the Analyzer Stimulus Test. Begin the emulator PV as directed on the previous page. To view this test display, position the highlight line over 'Analyzer Stimulus' and then press the <disp__test> softkey. Next, press the <start> softkey to begin the test. The test continues to run until a softkey is pressed. Each iteration takes approximately 5 seconds, depending upon the emulator used.

4-178. Reading the Analyzer Stimulus Test Results. The \# Failures column shows the total number of errors detected during the test. Each error code in the present column represents a single failure encountered during the last iteration. The cumulative error code represents the sum of all errors detected during the test. Cumulative error codes that differ from error codes in the results column indicate multiple, or intermittent errors. When the error codes are the same, the errors are systematic.

4-179. How. The emulator calls a program that toggles all bits on the emulation bus. Two lists are passed to the analyzer software; one, a list of memory addresses used in the program, and two, a list of status codes generated during the program. Analyzer comparators 1 and 2 are configured to count the memory address occurrences and the emulator is released to loop continuously through the program. When both comparators successfully count occurrences of the expected addresses, the analyzer checks to see that all expected status codes are received. Components tested are shown below.

4-1 80. PERFORMANCE ANALYSIS.
4-181. Results. This display line is a summary of the emulator address bus test, the status bus test, and some individual tests. Each comparator is tested separately. When both fail, it is likely that the emulator is not operating correctly, or signal L/ANAL is not toggling correctly. The error bits are decoded as follows.

Performance Analysis xxxxxxxxxxx =

| Bits | Error |
| :---: | :---: |
| 00000000000 | None |
| $\begin{aligned} & -----00 \\ & --------10 \end{aligned}$ | Comparator 1, address test summary OK no addresses counted. some addresses counted, but not all. only invalid addresses counted. |
| $\begin{aligned} & -00-- \\ & -01-- \\ & -10-- \\ & -11-- \end{aligned}$ | Comparator 2 , address test summary OK no addresses counted. some addresses counted, but not all. only invalid addresses counted. |
| $\begin{aligned} & -00---- \\ & -1-1---- \end{aligned}$ | Decoder test, comparators 1 and 2 OK . U26 pin 1 or 10 or 13 held high. U41 pin 1 or 4 or 10 held high. |
|  | Pull-up resistor test, OK. one of U27 through U32 pin 1 held low. one of U42 through U47 pin 1 held low. |
|  | Arming test, U7 and U20 OK. U20 pin 6 high, or U7 pin 12 low. U20 pin 8 high, or U7 pin 9 low. |
| - | Status qualifier test OK. Status qualifier test failed. |

## 4-182. EMULATION ADDRESS BUS.

4-183. Results. Correct operation is indicated by an OK message. Incorrect operation can produce two different error messages. Each comparator is tested separately; thus, when both fail, it is likely that the emulator is not operating correctly, or signal L/ANAL is not toggling correctly. The error messages are as follows.
a. Cannot count any address !

Comparator circuitry is unable to count any of the expected addresses.
b. Cannot count address $=000032 \mathrm{H}$ !

Can count address $=000004 \mathrm{H}$

In this example, the list of expected addresses is checked and 32 H is the first address not found. Location $4 \mathbf{H}$ is the first address which was found.

## 4-184. EMULATION STATUS BUS.

4-185. How. When both comparators are successfully tested, the emulation status bus L/ESO-7 is tested. This is done by checking simultaneously for an expected address and its associated emulator processor status code. When both the address and status code cannot be identified, an error is recorded.

4-186. Results.
a. Status qualifier faulty!

The expected address has been found but the status code associated with the address is not the expected code.
b. Not tested because of Emulation Address Bus Failure!

The emulation address bus test has failed. No status bus test has been performed.

## 4-1 87. ANALYZER STIMULUS TEST TROUBLESHOOTING.

4-188. Do not attempt to troubleshoot the analyzer stimulus test until all the software performance analyzer PV tests have been successfully completed. Instructions in the preceding Results paragraphs provide information on how to determine which component is suspect.

4-189. When the message shown below appears, there is complete failure of both comparator circuits. Check the cabling first, then check for an active L/ANAL. See schematic 3. Check U21-13; it should be toggling. See schematic 7 .

Cannot count any address !

4-190. SIGNATURE ANALYSIS - LOOP G. Connect the signature analyzer as directed for SA Loop G, in Appendix G. Reference schematics 3, 4 and 7 in Section VIII. Check the components in the comparator circuits.

Schematic 3, check: U27, U28, U29, U30, U31, U32.
4-191. The signatures are valid whether or not the emulation bus cables are connected. This is because the signature stimulus is provided by the microcontroller, and only control bit signatures are checked. Address lines are stimulated by the emulator, which runs asynchronously to the analyzer.

## NOTE

In normal operation, comparators U27-U32, and U42-U47 run hot.

## SECTION V

## ADJUSTMENTS

There are no adjustments on the Model 64310A Software Performance Analyzer.

## SECTION VI

## REPLACEABLE PARTS

## 6-1. INTRODUCTION.

6-2. This section contains information for ordering parts for the Model 64310A Software Performance Analyzer. Table 6-1 lists abbreviations used in the parts list and throughout the manual. Table 6-2 lists all replaceable parts in reference designator order. Table 6-3 contains the names and addresses that correspond to the manufacturers' five digit code numbers.

## 6-3. ABBREVIATIONS.

6-4. Table 6-1 lists abbreviations used in the parts list, the schematics and throughout the manual. In some cases, two forms of the abbreviation are used: one, all in capital letters, and one partial or no capitals. This occurs because the abbreviations in the parts list are always capitals. However, in the schematics and other parts of the manual, other abbreviation forms are used with both lowercase and uppercase letters.

## 6-5. REPLACEABLE PARTS.

6-6. Table 6-2, the replaceable parts list, is organized as follows:
a. Chassis mounted parts in alphanumerical order by reference designator.
b. Electrical assemblies and their components in alphanumerical order by reference designator.
c. Miscellaneous parts.

6-7. The total quantity for each part is given only once, at the first appearance of the part number in the list. The information given for each part consists of the following.
a. The Hewlett-Packard part number and the check digit.
b. The total quantity (Qty) in the instrument.
c. The description of the part.
d. A five digit code that indicates the manufacturer.
e. The manufacturer's part number.

## 6-8. ORDERING INFORMATION.

6-9. To order a part listed in the replaceable parts table, quote the Hewlett-Packard part number and check digit, indicate the quantity required, and address the order to the nearest Hewlett-Packard office.

6-10. To order a part that is not listed in the replaceable parts table, include the instrument model number, instrument repair number, the description and function of the part, and the number of parts required. Address the order to the nearest Hewlett-Packard office.

## 6-11. DIRECT MAIL ORDER SYSTEM.

6-12. Within the USA, Hewlett-Packard can supply parts through a direct mail order system. Advantages of using the system are as follows:
a. Direct ordering and shipment from the HP parts center in Mountain View, California.
b. No maximum or minimum on any mail order. There is a minimum order amount for parts ordered through a local HP of fice when the orders require billing and invoicing.
c. Prepaid transportation. There is a small handling charge on each order.
d. No invoices - to provide these advantages, a check or money order must accompany each order.

6-13. Mail order forms and specific ordering information are available through your local HP office. Addresses and phone numbers are located at the back of this manual.

6-14. EXCHANGE ASSEMBLIES

6-15. Exchange assemblies are available from the HP Corporate Parts center on a trade in basis. These exchange assemblies, are listed in Table 6-2.


Figure 6-1. Component Locator

Table 6-1. Reference Designators and Abbreviations

| REFERENCE DESIGNATORS |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| A | = assembly | F | = fuse | MP | $=$ mechanical part | u | = integrated circuit |
| B | = motor | FL | = filter | P | $=$ plug | $v$ | = vacuum, tube, neon |
| BT | = battery | IC | = integrated circuit | Q | = transistor |  | bulb, photocell, etc |
| c | = capacitor | J | = jack | R | = resistor | VR | $=$ voltage regulator |
| CP | = coupler | K | = relay | RT | $=$ thermistor | w | = cable |
| CR | = diode | L | = inductor | s | = switch | x | = socket |
| DL | = delay line | LS | = loud speaker | T | = transformer | Y | = crystal |
| DS | $=$ device signaling (lamp) | M | = meter | TB | = terminal board | z | = tuned cavity network |
| E | $=$ misc electronic part | MK | $=$ microphone | TP | $=$ test point |  |  |
| Abbreviations |  |  |  |  |  |  |  |
| A | = amperes | H | $=$ henries | N/O | = normally open | RMO | = rack mount only |
| AFC | $\begin{aligned} & =\text { automatic frequency } \\ & \text { control } \end{aligned}$ | HDW | = hardware | NOM | = nominal | RMS | = root-mean square |
| AMPL | = amplifier | $\begin{aligned} & \text { HEX } \\ & \text { HG } \end{aligned}$ | = hexagonal <br> = mercury | NPO | = negative positive zero (zero temperature | RWV | = reverse working voltage |
| BFO | = beat frequency oscillator | HR | = hour (s) |  | coefficient) |  |  |
| BE CU | = beryllium copper | HZ | $=$ hertz | NPN | $=$ negative-positive- | S-B | = slow-blow |
| BH | = binder head |  |  |  | negative | SCR | = screw |
| BP | = bandpass |  |  | NRFR | = not recommended for | SE | = selenium |
| BRS | = brass | IF | = intermediate freq |  | field replacement | SECT | = section(s) |
| Bwo | = backward wave oscillator | IMPG INCD | $=$ impregnated <br> = incandescent | NSR | $=$ not separately replaceable | SEMICON | = semiconductor <br> = silicon |
| CCW | = counter-clockwise | INCL | $=$ include(s) |  |  | SIL | = silver |
| CER | = ceramic | INS | = insulation(ed) | OBD | = order by description | SL | = slide |
| смо | = cabinet mount only | INT | = internal | OH | = oval head | SPG | = spring |
| COEF | = coeficient |  |  | ox | = oxide | SPL | = special |
| COM | = common | K | = $\mathrm{kilo}=1000$ |  |  | SST | = stainless steel |
| COMP | = composition |  |  |  |  | SR | = split ring |
| COMPL | = complete | LH | $=$ left hand | P | = peak | STL | = steel |
| CONN | = connector | LIN | = linear taper | PC | $=$ printed circuit |  |  |
| CP | = cadmium plate | LK WASH | = lock washer | PF | $=$ picofarads $=10-12$ | TA | = tantalum |
| CRT | = cathode-ray tube | LOG | = logarithmic taper |  | farads | TD | $=$ time delay |
| CW | = clockwise | LPF | = low pass filter | PH BRZ | $=$ phosphor bronze | TGL | $=$ toggle |
|  |  |  |  | PHL | = phillips | THD | = thread |
| DEPC | = deposited carbon | M | $=$ milli $=10^{-3}$ | PIV | = peak inverse voltage | TI | = titanium |
| DR | = drive | MEG | $=\mathrm{meg}=106$ | PNP | $=$ positive-negative- | TOL | = tolerance |
|  |  | MET FLM | = metal film |  | positive | TRIM | $=$ trimmer |
| ELECT | = electrolytic | MET OX | $=$ metallic oxide | P/O | = part of | TWT | $=$ traveling wave tube |
| ENCAP | = encapsulated | MFR | = manufacturer | POLY | = polystyrene |  |  |
| EXT | = external | MHZ | $=$ mega hertz | PORC | = porcelain | U | $=$ micro $=10-6$ |
|  |  | MINAT | $=$ miniature | POS | $=$ position(s) |  |  |
| F | = farads | MOM | = momentary | POT | $=$ potentiometer | VAR | = variable |
| FH | = flat head | mos | $=$ metal oxide substrate | PP | = peak-to-peak | vDCw | = dc working volts |
| FIL H | = fillister head | MTG | = mounting | PT | $=$ point |  |  |
| FXD | = fixed | MY | = "mylar" | PWV | $=$ peak working voltage | $\begin{aligned} & \mathbf{w} / \\ & \mathbf{w} \end{aligned}$ | $\begin{aligned} & =\text { with } \\ & =\text { watts } \end{aligned}$ |
| G | $=$ giga (109) | N | $=$ nano (10-9) | RECT | $=$ rectifier | wiv | = working inverse |
| GE | = germanium | N/C | = normally closed | RF |  |  | voltage |
| GL | = glass | NE | = neon | RH | $=$ round head or | ww | = wirewound |
| GRD | = ground(ed) | NI PL | = nickel plate |  | right hand | w/o | $=$ without |

Table 6-2. Replaceable Parts List

| Reference Designation | HP Part Number | $\begin{aligned} & c \\ & d \end{aligned}$ | Oty | Description | Mfr Code | Mfr Part Number |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $\begin{gathered} \mathrm{c} 1 \\ \mathrm{c}, 2 \\ \mathrm{c} 3 \\ \mathrm{c} 4 \\ \mathrm{c} 5 \\ \mathrm{c} 5 \end{gathered}$ | 64310 A $64310-66501$ <br> 64310-66501 <br> 0160-5298 <br> $0160-5298$ $0160-5298$ <br> 0160-5298 |  | $\begin{array}{r} 1 \\ 1 \\ 1 \\ 83 \end{array}$ | SOF TWARE PERFORMANCE ANALYZER BOARD ASSEMBLY-STATIC MODULE-NEW <br> BOARD ASSEMBLY-STATIC MODULE-NEW <br> CAPACITOR FXD CER .OUVF IDOUDC <br> CAPACTTOR FXD CER , O1UF 100 UDC <br> CAPACITOR FXD CER , O1UF 100 UDC CAPACTTOR FXD CER $01 u F ~ 100 U D C$ | $\begin{aligned} & 28480 \\ & 28480 \\ & 28480 \\ & 28480 \\ & 28480 \\ & 28480 \\ & 28480 \\ & 28480 \end{aligned}$ |  |
| $\begin{aligned} & \mathrm{c} 8 \\ & \mathrm{c} 7 \\ & \mathrm{c} 7 \\ & \mathrm{c} 8 \\ & \mathrm{cos} \end{aligned}$ | $0160-5298$ $0160-5988$ $0160-5298$ $0160-5298$ 0160-5298 |  |  | CAPACITTOR FXD CER.01uF 100uvd <br>  <br>  | 28480 28480 28480 23480 $\qquad$ | 0160-5298 0160-5298 0160-529 |
|  | $0160-5298$ $0160-5298$ 0 0160-5298 0160-5298 | 8 |  |  |  |  |
|  |  |  |  |  |  |  |
|  |  |  |  |  |  |  |
| $\begin{aligned} & \mathrm{c} 26 \\ & \mathrm{cab} \\ & \mathrm{c} 2 \mathrm{ar} \\ & \mathrm{c} 290 \\ & \mathrm{Can} \end{aligned}$ |  |  |  |  | 28480 2480 2480 24880 28880 28480 |  |
|  |  |  |  |  |  |  |
|  | $0160-5298$ $010-5298$ $0160-5298$ $0.160-5298$ $0160-5298$ <br> 0160-529 | 俍 |  |  |  |  |
|  |  |  |  |  |  |  |
|  |  | 俍 |  |  |  |  |
|  |  | 8 8 8 8 8 8 8 |  |  |  |  |
|  |  |  |  |  |  |  |
| $\begin{aligned} & c_{66}^{662} \\ & C_{6}^{685} \\ & c_{64}^{645} \end{aligned}$ |  |  |  |  | 23480 28480 28480 28480 28480 284 |  |
| $\begin{aligned} & c_{66}^{66} \\ & c_{6}^{68} \\ & c_{6}^{69} \\ & \hline 70 \end{aligned}$ |  |  |  | CAPACITTR FXD CER .OTUF 100 UDC NOT LOADED NOT NOADED <br>  capacitior fX | 28480 <br> 2848028480 <br> 28480 23480 28480 |  |
|  |  | (1) |  |  | 28480 28480 28480 28480 |  |

See introduction to this section for ordering information

Table 6-2. Replaceable Parts List (Cont'd)

| Reference Designation | HP Part <br> Number | C | Qty | Description | Mfr Code | Mfr Part Number |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 676 | 0160-5298 | 8 |  | CAPACITOR FXD CEE . OIJF $100 \cup \mathrm{DC}$ | 23480 | 0160-5298 |
| C.77 | 0160-5298 | 8 |  | CAPACITOR FXD CER . 01 UF $100 \cup \mathrm{DC}$ | 28480 | $0160-5298$ |
| c78 | 0160-5298 | B |  | CAPACJTOR FXD CEE , O1UF 100UDC | 28480 | 0160-5298 |
| c79 | 0160-5298 | 8 |  | CAPACITOR FXD CER . 014 L (100UDC | 28480 | 0160-5298 |
| C80 | 0160-5298 | 8 |  | CAPACITOR FXD CER . O1UF $100 \cup D C$ | 28480 | 0160-5298 |
| $\mathrm{c}_{61} 8$ | 0160-5298 | 8 |  | CAPACITOR FXD CER , 01UF 100 UDC | 28480 | 0160-5298 |
| c8e | 0160-5298 | 8 |  | CAPACTTOR FXD CER . O1UF 100VDC | 28480 | 0160-5298 |
| ${ }_{C 8}^{\text {C83 }}$ | 0160-5298 | 8 |  | CAPACITOR FXD CER , OLUF 100 UDC, | 28480 | 0160-5298 |
| C84 $\mathrm{C85}$ | $0160-5298$ $0160-5298$ | 8 |  | CAPACITOR FXD CER , O1UF 100UDC | 23480 | 0160-5298 |
| C85 | 0160-5298 | $\varepsilon$ |  | CAPACTTOR FXD CER . 01 LIF 100 UDC. | 28480 | 0160-5298 |
| C86 | 0160-5298 | 8 |  | CAPACTTOR FXD CER , 01UF 100 UDC, | 28480 | 0160-5298 |
| C87 | 0160-5298 | 8 |  | CAPACITOR FXD CER , OIUF $100 \cup \mathrm{DC}$ | 28480 | 0160-5298 |
| C88 | 0160-5298 | 8 |  | CAPACITOR FXD CER , O1UF $100 \cup D C$ | 28480 | 0160-5298 |
| C89 690 | $\begin{aligned} & 0180-0229 \\ & 0160-5298 \end{aligned}$ | 7 | 2 | CAPACITOR-FXD $330 F+-10 \%$ 10UDC TA | 56.289 | 15003369901082 |
| 69 | 0160-5298 | 8 |  | CAPACTTOR FXD CER , O1UF 100 UDC | 28480 | 0160-5298 |
| c.9 1 | 0180-0229 | 7 |  | CAPACITOR-FXD 33 UF $+-10 \%$ 10UDC TA | 56289 | $150 \mathrm{D} 336 \times 901082$ |
| C92 | 0160-5298 | 8 |  | CAPACITOR FXD CER . OILF 100 ODDC | 28480 | 0160-5298 |
| CR 1 | 1990-0652 | 8 | 3 | LED-LAMP ARRAY LUM-INT $=200 \cup \mathrm{CLD}$ IF $=5 \mathrm{SM}$ - MAX | 28480 | 1990-0652 |
| CR2 | 1990-0652 | 8 |  | LED-LAMP ARRAY LUM-TNT $=200 \cup U C D$ TF $=5 \mathrm{MA}-\mathrm{MAX}$ | 28480 | $1990-0652$ |
| CR3 | 1990-0652 | 8 |  | LEED-LAMP ARRAY LUM-INT=200UCD IF $=$ SMA - MAX | 28480 | 1990-0652 |
| MP1 | 64310-85001 | 4 | 1 | EXTRACTOR,' $64.310 A^{\prime}$ | 28480 | 64:310-85001 |
| MP2 | 64310-85002 | 5 | 1 | EXTRACTOR,'SU--PERF' | 28480 | 64310-85002 |
| MP3 MP4 | $1480 \cdots 0116$ $1480 \cdots 0116$ | 8 8 8 | 2 |  | 28480 | 1480-0116 |
| MP MP5 | $1480 \cdots 0116$ $7124 \cdots 0271$ | 8 | 1 |  | 28480 | 1480-0116 |
|  |  |  | 1 | L.ABEL."- ${ }^{\text {ORANGE }}$ DOT | 85480 | QD25 TAPE E- $810-\mathrm{DR}$ |
| R1 | 0757.-0280 | 3 | 3 | RESISTOR $1 \mathrm{~K} 1 \% .125 \mathrm{~W}$ F TC= $0+-100$ | 24546 | C4-1/8-T0-1001-F |
| R2 | 0757-0230 | 3 |  | RESTSTOR $1 \mathrm{~K} 1 \%$. 125 SW F TC $=0+\cdots 100$ | 24546 | C.4-1/8 - T0-1001-F |
| R3 | 0"57-0280 | 3 |  | RESTSTOR $1 \mathrm{~K} 1 \% .125 \mathrm{WF}$ TC $=0+-100$ | 24546 | C4-1/8-T0 - 1001-F |
| RP1 | $1810-0280$ | 8 | 8 | NETWORK--RES 10-STP10.0K DHM $\times 9$ | 01121 | 2104103 |
| RP2 | $1810-0280$ | 8 |  | NETWORK-RES 10 --STP10.OK OHM $\times 9$ | 01121 | 2104103 |
| RP3 | 1810-0280 | 8 |  | NETWORK - -RES $10-$ SIP 10.0 K DHM $\times 9$ | 01121 | 210 A103 |
| RP4 | 1810-0280 | 8 |  | NETWORK-RES 10 -SIP 10.0 K OHM $\times 9$ | 01121 | 2104103 |
| RP5 | 1810-0280 | 8 |  | NETWORK-RES $10-$ SIP 10.0 K DHM $\times 9$ | 01121 | 2104103 |
| RP6 | 1810-0280 | 8 |  | NETWORK-RES 10 -STP 10.0 K OHM $\times 9$ | 01121 | 2104103 |
| RP7 | 1810-0230 | 8 |  | NETWORK--RES 10 -SIP 10.0 K OHM $\times 9$ | 01121 | 2104103 |
| RP88 | 1810-0280 | 8 |  | NETWORK-RES 10-STP10.0K OHM $\times 9$ | 01121 | 210 A103 |
| 51534 | 3101-2102 | 6 | 1 | dTP ROCKER SWItch | 28480 | 3101-2102 |
| TP1 | 0360-0.0535 | 0 | 11 | TERMINAL TEST POINT PCB | 00000 | ORDER BY DESCRIPTION |
| TP2 | 0360-0535 | , |  | TERMINAL TEST POINT PCB | 00000 | ORDER BY DESCRIPTION |
| TP3 | 0360-0535 | 0 |  | TERMINAL TEST POINT PCB | 00000 | ORDER bY desccription |
| TP4 | 0360-0535 | 0 |  | TERMINAL TEST POINT PCB | 00000 | ORDEER BY DEGSCRIPTTON |
| TPS | 03600-0535 | 0 |  | TERMINAL TEST POINT PGE | 00000 | ORDER BY description |
| TPG | 0360-0535 | 0 |  | TERMINAL TEST POINT PCB | 00000 | ORDER BY DESCCRTPTITON |
| TP7 | 0360.0.0535 | 0 |  | TERMINAL TEST POINT PCE | 00000 | ORDER BY DESCRTPTION |
| TP8 TP9 | $0360-0535$ $0360 \cdots 0535$ | 0 |  | TERMINAL TEST POINT PCE | 00000 | ORDER BY DEGCRIPTION |
| TP10 | $0.360 \cdots 0.35$ $0360-0535$ | 0 |  | TERMINAL. TEST POINT PCE | 00000 | ORDER EY DESCRTPTION |
| TP10 | 0.360-0535 | 0 |  | TERMINAL TEST POINT PCEB | 00000 | ORDER BY DESCRIPTION |
| TP 11 | 0360-0535 | 0 |  | TERMINAL TEST POINT PCB | 00000 | ORDER BY dFscription |
| U1 | 1820-1173 | 1 | 1 | IC XLTr ECL TTL--TO-ECL RUAD 2 -Inp | 04713 | MC10124L |
| U1 | 1820-2359 | 7 | 1 | IC MTSC ECL 14-INP | 07263 | F10014PC |
| U3 | 1820-1052 | 5 | 1 | IC XITR ECL ECL--TO-TTL QUAD 2-INP | 04713 | MC10125L |
| 14 | 1813-0193 | 8 | 1 | DEL LTNE 200NS | 07393 | TTI. DM-200 |
| U5 | 1820-1917 | 1 | 4 | IC BFR TTL L..s l.tine drur octl. | 01295 | SN74LSS240N |
| U6 | 1820-1997 | 7 | 12 | IC FF TTL LSS D-TYPE POS-EDGE-TRTG PRI.-IN | 01295 | SN741.5374N |
| 1.17 | 1820-1997 | 7 |  | TC FF TTL LS D TYPE POS-EDGE--TRIG PRL-IN | 01295 | SN74LS374N |
| 48 49 | $1820-2684$ $1820-1997$ | 1 | 3 | IC GATE TTI. F NAND QUAD 2 INP | 07263 | 74F00PC |
| U10 | $1820-2102$ | 8 | 1 | IC FH THL L S D-TYPE POS-EDGE-TRTG PRL-TN | 01295 | SN7 4LS374N SN74L.LS |
| 411 | 1816-1308 | 5 | 1 | IC--931.422 PC | 07263 | 931.422PC |
| 412 | 1820-1997 | 7 |  | IC FFF TTL LS D-TYPE POS-EDGE-TRTG PRI-IN | 01295 | SN74LS374N |
| 413 | 1820-1997 | 7 |  |  | 01295 | SN74LS374N |
| 414 | 1820-1997 | 7 |  | IC FF TTL LS D - TYPE POS-EDGE-TRIG PRL-IN | 01295 | SN74L.S374N |
| 415 | 1820-2686 | 3 | 2 | IC GATE TTL F AND QUAD 2 -TNP | 07263 | $74 \mathrm{F08PC}$ |
| 416 417 | $1820-2686$ $1820-0682$ | 3 5 |  | IC GATE TTL F AND QUAD $2 \cdots$ INP | 07263 | 74 F 08 PC |
| 417 418 | $1820-0682$ $1820-2689$ | 5 | 2 | IC GATE TTL S NAND QUAD 2-INP | 01295 | SN74S03N |
| 418 419 | $1820-2689$ $1820-1203$ | 6 8 8 | 1 | IC GATE TTL. F NAND DUAL 4-INP | 07263 01295 | 74F20PC SN74LS11N |
| บ20 | 1820-2684 | 1 |  | IC GATE TTLL F NAND QUAD 2-INP | 07263 | 74F00PC |
| U21 | 1820-2685 | 2 | 5 | IC GATE TTL F NOR QUAD 2-J.Np | 07263 | 74F02PC |
| U22 | 1820-0629 | 0 | 5 | IC FF TTL S J-K NEG-EDGE-TRIG | 01295 | SN74S112N |
| 1423 | 1820-0629 | 0 |  | IC FF TTL $S$ J-K NEG--EDGE-TRIG | 01295 | SNTAS 112 N |
| U24 | 1820-1240 | 3 | 7 | IC DCDR TTL S 3-TO-8-LINE 3-INP | 01295 | SN74S138N |
| 1325 | 1820-1624 | 7 | 1 | IC BFR TTL S OCTL. 1-INP | 01295 | SN74S2.41N |

Table 6-2. Replaceable Parts List (Cont'd)

| Reference Designation | HP Part Number | C | Oty | Description | Mfr Code | Mfr Part Number |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| U26 | 1820-2685 | 2 |  | IC GATE TTL F NOR QUAD 2-TNP | 07263 | 74 FOPP |
| U27 | 1820-2899 | 0 | 12 | IC-74AS885 | 28480 | 1820-2899 |
| U28 | 1820-2899 | 0 |  | TC-74AS885 | 29480 | 1820-2899 |
| U29 | $1820-2899$ | 0 |  | TC-74AS885 | 28480 | $1820-2899$ |
| 430 | 1820-2897 | 0 |  | TC-74AS885 | 28480 | 1820-2899 |
| 431 | 1820-..2899 | 0 |  | IC--74AS885 | 23480 | 1820-2899 |
| 432 | 1820-2899 | 0 |  | IC-74AEB85 | 28480 | 1820-2899 |
| 433 | 1820 - 2770 | 6 | 1 | IC--UP 68E09L | 28480 | 1820--2770 |
| 1435 | 64310-80000 | 3 | 1 | EFROM, BOOT | 28480 | 64310-80000 |
| U36 | 1818-1611 | 7 | 3 | IC. HM6116P-3 | 54013 | HME: 16 P --3 |
| 437 | 1818-1611 | 7 |  | IC HM6.116P-3 | 54013 | HM6116P-3 |
| 438 | 1818-1611 | 7 |  | IC HME116P-3 | 54013 | HM6\%16P 3 |
| U39 | 1820-2206 | 3 | 2 | IC MISC TTL LS | 01295 | SN74LS640N |
| 440 | 1820-0683 | 6 | 2 | IC INU TTL S HEX 1-INP | 01295 | SNTASO4N |
| 1441 | 1820-2685 | 2 |  | IC GATE TTL F NOR QUAD 2-.t.np | 07263 | $74 F 02 P C$ |
| 442 | 1820--2899 | 0 |  | IC--74AS885 | 28480 | 1820-2899 |
| 143 | 1820-2899 | 0 |  | It. - $74 \mathrm{ASB85}$ | 28480 | 1820-2399 |
| 444 | 1820-2899 | 0 |  | IC.-74AS885 | 28490 | 1820-2899 |
| 1455 | $1820-2898$ | 0 |  | TC-74AS885 | 28480 | 1820-2899 |
| 446 | 1820-2899 | 0 |  | IC-74AS885 | 28480 | 1920-2899 |
| 447 | 1820--2899 | 0 |  | IC--74AS日85 | 28480 | 1820-2399 |
| 448 | 1820-1633 | 8 | 2 | IC EFR TTL. S INU OCTL I- TNP | 01295 | SNTHSE40N |
| 449 | 1820-1633 | 8 |  | TC BER TTL 5 INU OCTL 1-TNP | 01295 | SN74S240N |
| U50 | 1820 $\cdots 1416$ | 5 | 2 | IC SCHMITT-TRTG TTL LS INU HEX 1-TNP | 01295 | SN741.S14N |
| U51 | 1820-1240 | 3 |  | IC DCDR TTL 5 3-TO-B-LINE 3-TNP | 01295 | SN745138N |
| 452 | 1820-2685 | 2 |  | IC GATE TTL F NOR QUAD 2 INP | 07263 | 74502 PC |
| U53 | 1820-1276 | 5 | 1 | IC. SHFwRGTR TTL LS R--S PRL - IN PRL--0UT | 01295 | SN74L.S194AN |
| 454 | 1820-1240 | 3 |  | IC DCDR TTL S 3 TO-8-LTNE 3-INP | 01295 | SN'74S138N |
| $1 \mathrm{US5}$ | 1820-0683 | $\stackrel{6}{5}$ |  | IC TNU TTL S HEX 1-TNP | 01295 | SN74S04N |
| U56 | 1820--2696 | 5 | 2 | IC FF TTI F D-TYPE POS-EDGE-TRTG COM CLK | 07263 | 74F175PC |
| 457 | 1820-1112 | 8 | 4 | IC. FF TTL LS D-TYPE POS-EDSE-TRTG | 01295 | SN74LS74AN |
| 458 | $64310-80003$ | 6 | 1 | LOGIE ARRAY, MEASUREMENT CONTEXT2 | 28480 | $64310-80003$ |
| 459 | 1820-1997 | 7 |  | TC FF TTL LS D-TYPE POSEDGE-TRIG PRL--TN | 01295 | SN'74L. S374N |
| 460 | 1820--2604 | 5 | 3 | JC, NMOS 16--ETT | 34335 | AM9513CC |
| 1061 | 1820-2604 | 5 |  | TC NMOS 16-bIT | 34335 | AM9513CC |
| 462 | 1820--2604 | 5 |  | IC: NmOS 16 -mit | 343:35 | AM9513CC |
| 163 | $1820-2601$ | 2 | 1 | IC-8259A | 28480 | $1820-2601$ |
| 1164 | $1820-2654$ | 5 | 1 | IC. MUXR/DATA SEL TTL F 2 - TO-1-LTNE QUAD | 07263 | 74 F 157 PC |
| 165 | 1820-1197 | 9 | 2 | IC GATE TTL L.S NAND QUAD 2 - ${ }^{\text {INP }}$ | 01295 | SN7 4LSOON |
| 066 | 1820-1197 | 9 |  | IC GATE TTL LS NAND QUAD $2-$ TNP | 01295 | SN741.500N |
| 1467 | 1820-1240 | 3 |  | IC DCDR TTL S 3-TO-8-LINE 3-TNP | 01295 | SN74S138N |
| 168 | 1820-2696 | 5 |  | TC FF TTL F D-TYPE POS EDCEETRTG COM CLK | 07263 | $745175 P \mathrm{C}$ |
| 169 470 | $1820-1240$ $1820-2206$ | 3 |  | IC DCDR TTL S 3-TO-8-LTNE 3-TNP | 01295 | SN74S138N |
| 470 | 1920--2206 | 3 |  | IC MTSC TTI LG NOT LOADED | 01295 | SN74L S640N |
| U72 | 1820-1997 | 7 |  | IC FF: TTL LS D--TYPE POS-EDGE-TRIG PRL--IN | 01295 | SN741.5374N |
| 473 | 1820-1997 | 7 |  | IC FF TTL LS D-TYPE POS EDEE- TRIG PRI...IN | 01295 | SN741. 5374N |
| 4174 | 1820-1917 | 1 |  | IC, EFR TTL LS LTNE DRUR OCTL | 01295 | SN'74LS240N |
| 1475 | 1820-1917 | 1 |  | TC EFR TTL LS LINE DRUR OCTL | 01295 | SN'74LS240N |
| 476 | 64310-80002 | 5 | 1 | LOGTC ARRAY, MEASUREMENT CONTEXT1 | 28480 | 64310-80002 |
| 477 | 1820-1416 | 5 |  | tc schmitt-trtg trl lis tnv hex 1 - Tnp | 01295 | SN゙T4L.514N |
| 478 | 1820 ${ }^{101112}$ | 8 |  | IC FF TTL LS D TYPE POS-EDGE-TRTG | 01295 | SN74L.S74AN |
| 479 | 1820-1112 | 8 |  | IC FF TTL IS D-TYPE PDSEEDCE TRTG | 01295 | SN74LS74AN |
| U80 481 | $1820-0629$ $1820-0629$ | 0 0 |  | IC FF TTL S IC FF TTL S J-K | 01295 | SN749112N |
| U81 | 1820-0629 | , |  | IC FF TTL 6 J-K NEGEDCE TRJG | 01295 | SN74S112N |
| 482 | 1820-0629 | 0 |  | IC FF TTL S J K NEG EDGE TRTG | 01295 | SNTMSI12N |
| 1883 | 1820-2684 | 1 |  | IC GATE TTL F NAND QUAD 2-TNP | 07263 | 74 FOOPC |
| 1884 1885 | $1820-2685$ $1820-1240$ | $\frac{2}{3}$ |  | IC GATE TTL F NOR QUAD $2 \cdots$ TNP | 07263 | $74 F 02 P C$ GNFASI |
| 1885 1486 | $1820-1240$ $1820 \cdots 1997$ | 3 7 |  | IC DCDR TTL S 3-TO G-LINE 3-INP IC FF TTL LS DTYPE POS-EDGE-TRTG PRI-IN | 01295 | SN74S138N SN74I. 374 N |
| 487 | 1820-1997 | 7 |  | IC FF TTL LS D--TYPE POS EDDEE-TRTG PRL-TN | 01295 | SN74LS374N |
| 488 | 1820-1997 | 7 |  | IC FFF TTL LS D--TYPE POS-EDGE-TRTG PRL-IN | 01295 | SN741. S374N |
| 489 | 1820-1917 | 1 |  | TC EFR TTL ILS LINE DRUR OCTL | 01295 | SN74LSE40N |
| 490 | 1820-1240 | 3 |  | IC DCDR TTL S 3-TO-8-LINE: 3-INP | 01295 | SN74S138N |
| 491 | 64310-80001 | 4 | 1 | LOGIC ARRAY, MAINFRAME CONTROL. | 28480 | 64310-80001 |
| 492 | 1820-1112 | 8 |  | IC FFF TTL LS D-TYPE POS-EDCE-TRIG | 01295 | SN741.574AN |
| 193 | 1820-0682 | 5 |  | IC. GATE TTL 5 NAND QUAD $2-$-TNP | 01295 | SN74S03N |
| $\times 133$ | 1200-0654 |  | 4 | SOCKET-IC 40-CONT DIP DTP-SLDR | 29480 | 1200-0654 |
| XU35 | 1200-0541 | 1 | 4 | SOCKET-TC 24 CONT DIP DIPP-.SLDR | 28480 | 1200-0541 |
| $\times 1136$ $\times 1037$ | 1200-0541 | 1 |  | SOCKET-IC, 24-CONT DIP DTP - SLDR | 29480 | 1200-0541 |
| $\times 1137$ $\times 103$ | 1200-0541 | 1 |  | SOCKET-TC E4-CONT DIP DIP-GLDR | 28480 | 1200-0541 |
| $\times 1138$ | 1200-0541 | 1 |  | SOCKET-IC. 24-CONT DTP DTP-GLDR | 23480 | 1200-0541 |
| xuse | 1200-0553 | 5 | 4 | SOCKET-TC 2B-CONT DTP--SIDR | 23480 | 1200-0553 |
| $\times 1660$ $\times 1161$ | 1200-0654 | 7 |  | SOCKET-IC, 40-CONT DTP DTP SLDR | 23480 | 1200-0654 |
| $\times 1161$ | 1200-0654 | 7 |  | SOCKET-TC 40-CONT DIP DTP-.5LDR | 28480 | 1200-0654 |
| $\times 1162$ | $1200-0654$ | 7 |  | SOCKET-IC 40-ECONT DIP DTP-SLDR | 28480 | 1200-0654 |
| $\times 1563$ | 1200-0553 | 5 |  | GOCKET-IC 2B-CONT DTP-SLDR | 28480 | 1200-0553 |

Table 6-2. Replaceable Parts List (Cont'd)


Table 6-3. List of Manufacturers' Codes

| Mfr <br> No. | Manufacturer Name | Address |  | Zip <br> Code |
| :---: | :---: | :---: | :---: | :---: |
| 54013 00000 | HITACHI <br> ANY SATISFACTORY SUPPLIER | TOKYO | JP |  |
| 01121 | ALLEN - bradley co | milwaukee | WT | 53204 |
| 01295 | TEXAS INSTR INC SEMICOND CMPNT DIU | DALLLAS | TX | 75222 |
| 04713 | MOTOROLA SEMICONDUCTOR PRODUCTS | PHOENIX | AZ | 85008 |
| 07263 | FAIRCHILD SEMICONDUCTOR DIU | MOUNTAIN UTEW | ${ }_{\text {c }}^{\text {ca }}$ | 94042 |
| 07393 | COLSON CORP THE | JONESERORO | AR | 72401 |
| 24546 28480 | CORNING GLASS WORKS (BRADFORD) | ERADFORD PALO ALTO | PA | 16701 94304 |
| 34335 | ADUANCED MICRO DEVICES INC | SUNNYUALE | CA | 94086 |
| 56289 | Sprague electric co | NORTH ADAMS | MA | 01247 |
| 85480 | ERADY W H CO | milwalkee | WT | 53209 |

## SECTION VII

## MANUAL CHANGES

This section normally contains backdating information for models with repair numbers prior to the one shown on the title page. Because this edition includes only the first repair number, there is no backdating material.

## SECTION VIII

## SER VICE

## 8-1. INTRODUCTION.

$8-2$. This section contains reference information for servicing the Model 64310A Software Performance Analyzer. For convenience, the schematics, component locator, and other service information are provided on foldout service sheets.

8-3. The following functional blocks implement the operation of the analyzer.
Block ..... Schematic
Development Station Interface ..... 1
Microcontroller. ..... 2
Address Recognition ..... 3, 4
Context Recognition ..... 5
Statistics ..... 6
Control and Timing ..... 7

## 8-4. GENERAL THEORY.

8-5. Software performance analyzer operation is directed by the microcontroller circuit. The microcontroller consists of a 68 B 09 microprocessor operated at $8 \mathrm{MHz}, 6 \mathrm{~K}$ bytes of RAM , and 2 K bytes of ROM. Software is loaded into the RAM by the development station. The only routines in the ROM are the bootstrap loading, and initial performance verification test.

8-6. The 68B09 microprocessor drives a fourteen bit address bus via a set of buffers. Most of the address lines are used only within the microcontroller circuitry for RAM/ROM addressing. The lowest four address bits and the eight bit data bus also go to other parts of the board. These four address bits and the data bus connect all functional blocks of the board and allows direct I/O to hardware registers by way of decoders. The I/O is memory mapped.

8-7. Address recognition, context recognition, and statistics are done in real-time hardware to measure emulator instruction rates of up to 5 MHz . The address recognition circuit indicates if an address on the emulation bus falls within a specified range. It consists of two circuits that compare the twenty-four bit address with the upper and lower bound of a user specified range. Each comparator circuit produces the signals shown below, for a total of six comparator output bits.

Equal to upper bound. In range. Equal to lower bound.

8-8. The context recognition circuit latches eight emulation status bits. The status bits are checked with a recognition RAM and generate two qualifier bits. The qualifiers distinguish memory access types as shown below and have different bit assignments for different emulators.

8-9. The two qualifier bits, six comparator output bits, and measurement mode bits all go into the context recognition state machine which does all of the triggering for the operator specified address ranges, event and trace start and stop, sequences, etc. Programmable logic arrays provide the majority of the circuitry in the state machine.

8-10. Statistical analysis of emulation address states is performed by three AMD9513 programable counters, one for events, one for time, and one for sequence. The programable counters are gated on and of by the context recognition state machine and can collect statistics up to a maximum rate of 7 MHz . This means collection of statistics is as fast as memory cycles on the emulation bus. Time resolution is 160 ns . The time reference comes from the development station 25 MHz back plane clock, and is synchronized and divided by four prior to feeding into the time counter.

8-11. The counters are continually building one bar on the occurrence histogram, and one bar on the time histogram. An entire histogram is built by having the 68B09 microprocessor dynamically reprogram the address recognition comparators and accumulate each bar in turn.

8-12. The IMB and control section interfaces the analysis clock L/ANAL and inter-module bus to the 64310A internal control signals. High speed strobe signals, H/PHASE 4 AND H/PHASE 5 , cause the various acquisition registers to fire in the proper pipelined fashion. This pipelining allows a new measurement to come in while an old measurement is still being accumulated, thereby giving a 5 MHz acquistion rate, although an entire measurement cycle takes about 350 ns.

8-13. Performance verification circuitry is built-in to allow the 68 B 09 microprocessor to read/write the six comparator output bits, read the context recognition outputs, and read/write the programable counter registers. This allows the performance verification software to do extensive testing of the board.

## 8-14. DEVELOPMENT STATION INTERFACE, SCHEMATIC 1.

8-15. All communication between the development station and the analyzer is accomplished via a handshake method using the development station data bit 15 . Whenever the development station wants to transfer data to or from the analyzer, it first checks bit 15 . When bit L/D15 is clear, the development station reads or writes data from the analyzer interface latches U86, U87, and U 88 .

8-16. This process sets the H/BPCREQ interrupt to the microcontroller. The microcontroller then recognizes the interrupt and clears it. When the microcontroller is ready for the transfer, it writes its data to the output latch U88. The process of writing the data to the development station clears bit L/D15. When the microcontroller is reading data from the development station latch U87, a dummy write is done to the output latch to clear the handshake bit.

8-17. All of the arbitration for this communication is contained in logic array U91. Synchronization is handled by flip-flop U92 and prevents changing of the handshake bit while the development station is checking status. The development station interface handles any hard resets of the microcontroller via the L/RESET line. This line is always set true at power-up by L/POP and can be set/reset by the development station.

## 8-18. MICROCONTROLLER, SCHEMATIC 2.

8-19. The heart of the microcontroller is a 68 B 09 microprocessor with an 8 MHz clock, 6 K bytes of RAM, and 2 K bytes of ROM. The microcontroller drives a negative true address bus, a positive true data bus to memory, and a negative true data bus to I/O and control. Primary address decoding is handled by decoder U51 and primary data bus driving and inversion is handled by transceiver U39.

8-20. The main purpose of the microcontroller is to handle the hardware configuration for measurements and to accumulate measurement data. All data for a current measurment is maintained by the microcontroller. In this way, the analyzer is able to run and acquire measurement data independent of the development station. The microcontroller recognizes two interrupts, one from the development station for data transfers, and one from the statistics section for measurement end, start, or error. The microcontroller software recognizes the source of the interrupt and acts accordingly.
$8-21$. Four-bit shift register U 53 is a wait-state generator. It is enabled whenever ROM or statistics is addressed by the microprocessor. The wait-state generator is disabled whenever L/RESET is true to allow proper startup of the 68B09 from powerup. Switch SU34 is used for service, and forces an LDA instruction onto the data bus. This causes a constant toggling of the address bits, thus providing a constant stimulus for SA.

## 8-22. ADDRESS RECOGNITION, SCHEMATICS 3 AND 4.

8-23. The analyzer has the ability to simultaneously recognize two different, twenty-four bit emulation addresses. This is accomplished in two address range comparator circuits. Each circuit consits of six TI AS885 eight-bit comparator chips, organized in two banks of three chips. One bank is programmed for the address range upper bound, and one for the lower bound. By processing the outputs of each bank with NOR gates $\mathbf{U} 26$ and U41, the comparator output bits shown below are obtained.
a. H/COMOUT1, 4 ; emulation address equals upper bound.
b. H/COMOUT2, 5; emulation address is in range.
c. H/COMOUT3, 6; emulation address equals lower bound.

8-24. The range comparators are programmed on a byte-by-byte basis by the microcontroller. Address decoding is handled by decoders U67 and U54. The upper seven bits and the least significant bit can be placed into a don't care condition when the microcontroller writes a pattern to latch U59. The outputs of this latch enable/disable AND gates U15 and U16. This places the inputs of the range comparator into a known state. The microcontroller knows the don't care pattern and handles the addresses accordingly.

## 8-25. CONTEXT RECOGNITION, SCHEMATIC 5 .

8-26. The context recognition section performs all real-time measurement operations. It consists of a context state machine, mode latch, emulation status bits qualifier, and data buffers.

8-27. The heart of this section is the context recognition state machine which consists of logic arrays U76 and U58, state feedback register U68, and state output latch U56. The state machine's registers are cleared whenever the microcontroller programs mode latch U72. The microcontroller addresses the various elements of this section through decoder U69.

8-28. The state machine monitors the L/COMOUT1-6 bits, the two status qualifier bits and mode latch U72. The mode latch is programmed with the measurment request code and logic array select bit. In this way, different sets of equations are selected for the requested measurement. Each logic array holds forty-eight, sixteen-term equations.

8-29. Flip-flop U57 monitors L/COMOUT 4 from comparator 2 to 'memorize' an event occurrence. This is needed for disable conditions because the state machine clock is paused during reprogramming of range comparator 1 for certain types of measurements. This flip-flop is enabled, disabled, and cleared by the microcontroller.

8-30. The state machine outputs are connected to the statistics section, and based on emulation address and status, start, stop, retrigger, and interrupt statistics accumulation.

8-31. The status qualifier consists of RAM U11 which recognizes patterns on the status bus. Only two of the RAM outputs, H/QUAL1,2 are used by the state machine. The RAM is programmed by the microcontroller for the type of measurement requested. The RAM occupies a 256 byte block of write address space in the microcontroller memory.

8-32. Three buffers and one latch are provided in this section for performance verification. Buffer U25, and latch U73 are used to provide microcontroller stimulation of the six comparator output bits. Buffer U25 disables the address recognition section from the comparator output bits. Buffer U75 allows monitoring of the comparator output bits and the status RAM outputs by the microcontroller to check operation of the state machine and its feedback register.

## 8-33. STATISTICS, SCHEMATIC 6.

8-34. The statistics section handles the real-time data reduction. Depending on the measurement requested, time data, event data, or both are collected. Time data is recorded as counts of 160 ns on counter U61. Events are counted as occurrences of emulation addresses on counter U60. Counter U62 functions as a sequence counter. Each counter is an AMD9513 which contains five 16 -bit counters. The counters are configured by the microcontroller to record the statistics as thirty-two bit words.

8-35. The microcontroller addresses the statistics section via decoder U85. The statistics section also has its own bus driver to reduce loading and to invert the data bus. The time reference is supplied by the 25 MHz backplane source and is divided by four to produce the 160 ns clock. Flip-flops U80, U81, U82 are used for the division, and also provide synchronization with the state machine. The timers are also gated on and of with the L/BKG signal from the emulator to assure they are not running when the emulator is in background.

8-36. The statistics section also contains an interrupt controller that is operated in a polled fashion. The active interrupt is determined by the requested measurement and programmed by the microcontroller. The interrupt acknowledge signal is generated by a software strobed line. Four of the inputs to the interrupt controller are multiplexed by two-to-one selector U64 to allow different measurements to select the interrupts they require.

8-37. Time boundary flip-flops U78 and U79 are connected to the outputs of the time and event counters. They are used when the analyzer is making duration measurements. One flipflop is set when the lower time boundary is crossed. The outputs are clocked into sequence counter U62 on the rising edge of H/CONEND. By taking the difference between the counts, the period of time the counters were in the programmed range can be determined.

## 8-38. IMB AND CONTROL, SCHEMATIC 7.

8-39. The IMB and control section generates the pipeline timing and handles all IMB functions. The timing generator produces H/PHASE 4 and H/PHASE 5 signals from the rising edge of L/ANAL. Each phase is a positive going pulse of 80 to 90 ns duration. Signal H/PHASE 4 has a 160 ns period and clocks the context recognition state machine. Signal H/PHASE 5 has a 200 ns period and clocks the event counter.
$8-40$. The timing generator is turned on and off by the microcontroller. The microcontroller is synchronized to the timing generator by run and go flip- flop $\mathrm{U}-22$. When a run command is issued, U22-5 H/RUN is set high. Signal H/RUN is then gated with IMB signals by NOR gate U18. When all signals are true, then the input on go flip-flop U22-11 is high. On the next rising edge of L/ANAL, U22-9 H/GO goes high. This signal is then inverted by U21 and passed to the delay chip U4.

8-41. Delay chip U4 then generates H/PHASE 4 and H/PHASE 5. The $40 \%$ tap on U4, L/GOCLR, is sent back, to reset go flip-flop U22. This clears the flip-flop after a delay of 80 ns .

8-42. The IMB functions are limited to the receiving and driving trigger enable, EL/TE. When the analyzer is receiving EL/TE, it is simply used to gate H/RUN on and off. When the analyzer is driving EL/TE, the state of EL/TE is determined by the microcontroller software.

8-43. Signals L/BRK, E/DTR, and EH/TR are never driven, even though there is hardware to do so. Signals H/OVTIME and H/OVCOUNT are always disabled.

## NOTE

When an external module is windowing the analyzer, only the occurrence counters are disabled; the timers continue to run.

8-44. There is one latch, half of a buffer, and one gate used for performance verification in this section. Buffer U5 allows the microcontroller to monitor the status of flip-flops U23 and U22, trigger and run signals. Latch U6 is used to drive the analyzer status light array. This latch is directly written to by the microcontroller.


Table 8-1. Connector Signals

| Connector P1 |  | Connector I 1 | Connector J2 | Connector J3 |
| :---: | :---: | :---: | :---: | :---: |
| Schematic 1 |  | Schematic 7 | Schematic 5 | Schematic 3 |
| Pin |  | Pin | Pin | Pin |
| 1 gnd | 51 L/D 14 | 1 E/GMC | 1 L/BRK | 1 L/EA 0 |
| 2 gnd | 52 L/D15 | 2 gnd | 2 not used | 2 gnd |
| $3+5 v$ | 53 gnd | 3 not used | 3 gnd | 3 L/EA 1 |
| $4+5 \mathrm{y}$ | 54 gnd | 4 gnd | 4 gnd | 4 gnd |
| $5-5.2 \mathrm{v}$ | 55 L/HSYN | 5 not used | 5 L/EDO | 5 L/EA 2 |
| $6-5.2 v$ | 56 L/VSYN | 6 gnd | 6 L/ED 1 | 6 gnd |
| $7-5.5 v$ | 57 L/VID | 7 not used | 7 L/ED2 | 7 L/EA 3 |
| $8-5.2 v$ | 58 L/IVIDT | 8 gnd | 8 L/ED3 | 8 gnd |
| $9-3.2 v$ | 59 gnd | $9 \mathrm{E} / \mathrm{DTR}$ | 9 L/ED 4 | 9 L/EA 4 |
| $10-3.2 \mathrm{v}$ | 60 gnd | 10 gnd | 10 L/ED5 | 10 gnd |
| $11-12 \mathrm{v}$ | 61 L/BYTE | 11 not used | 11 L/ED6 | 11 L/EA5 |
| $12-12 v$ | $62 \mathrm{~L} / \mathrm{UPB}$ | 12 gnd | 12 L/ED7 | 12 gnd |
| $13+12 v$ | 63 L/STM | 13 EL/ME | 13 gnd | 13 L/EA 6 |
| $14+12 v$ | 64 L/STB | 14 gnd | 14 gnd | 14 gnd |
| $15+17 v$-ret | $65 \mathrm{~L} / \mathrm{WRT}$ | $15 \mathrm{EL} / \mathrm{TE}$ | 15 L/ED8 | 15 L/EA 7 |
| $16+17 v$ | 66 L/MSYN | 16 gnd | 16 L/ED9 | 16 gnd |
| $17+40 v$ | 67 L/ID | 17 EL/SE | 17 L/ED 10 | 17 L/EA 8 |
| 18 not used | 68 L/MAP 1 | 18 gnd | 18 L/ED 11 | 18 gnd |
| 19 L/A0 | 69 L/MAP2 | $19 \mathrm{EH} / \mathrm{TR}$ | 19 L/ED12 | 19 L/EA9 |
| $20 \mathrm{~L} / \mathrm{A} 1$ | 70 L/MAP3 | 20 gnd | 20 L/ED 13 | 20 gnd |
| $21 \mathrm{~L} / \mathrm{A} 2$ | 71 L/IR 1 |  | 21 L/ED14 | 21 L/EA10 |
| 22 L/A 3 | 72 L/SEL | To Other | 22 L/ED15 | 22 gnd |
| $23 \mathrm{~L} / \mathrm{A} 4$ | 73 BNC4 | Option Cards | 23 gnd | 23 L/EA11 |
|  |  |  | 24 gnd | 24 gnd |
| $25 \mathrm{~L} / \mathrm{A} 6$ | 75 BNC3 |  | 25 L/EBYT | 25 L/EA 12 |
| 26 L/A 7 | 76 L/POP |  | 26 gnd | 26 gnd |
|  | 77 BNC2 |  | 27 L/EBUP | 27 L/EA 13 |
| 28 L/A9 | 78 BNC 1 |  | 28 gnd | 28 gnd |
| 29 L/A10 | 79 gnd |  | 29 L/REFRE | 29 L/EA14 |
| $30 \mathrm{~L} / \mathrm{A} 11$ | 80 gnd |  | 30 gnd | 30 gnd |
| 31 L/A12 | 8125 MHz |  | $31 \mathrm{H} /$ REFAK | 31 L/EA15 |
| 32 L/A 13 | 82 not used |  | 32 gnd | 32 gnd |
| $33 \mathrm{~L} / \mathrm{A} 14$ | $83+5 v$ |  | 33 L/MBRKS | 33 L/EA16 |
| 34 L/A15 | $84+5 v$ |  | 34 gnd | 34 L/EA 20 |
| 35 gnd | 85 gnd |  | 35 L/BKG | 35 L/EA 17 |
| 36 gnd | 86 gnd |  | 36 gnd | 36 L/EA21 |
| 37 L/D0 |  |  | 37 not used | 37 L/EA 18 |
| $38 \mathrm{~L} / \mathrm{D} 1$ | To |  | 38 gnd | 38 L/EA22 |
| 39 L/D2 | Development |  | 39 L/ANAL | 39 L/EA 19 |
| $40 \mathrm{~L} / \mathrm{D} 3$ | Station |  |  | $40 \mathrm{~L} / \mathrm{EA} 23$ |
| 41 L/D 4 |  |  | 41 L/ES0 | $41 \mathrm{H} / \mathrm{MAV}$ |
| 42 L/D5 |  |  | $42 \mathrm{~L} / \mathrm{ES} 1$ | 42 gnd |
| 43 L/D6 |  |  | 43 L/ES2 | $43 \mathrm{H} / \mathrm{READY}$ |
| 44 L/D7 |  |  | $44 \mathrm{~L} / \mathrm{ES} 3$ | 44 gnd |
| $45 \mathrm{~L} / \mathrm{D} 8$ |  |  | $45 \mathrm{~L} / \mathrm{ES} 4$ | $45 \mathrm{~L} / \mathrm{EWRT}$ |
| $46 \mathrm{~L} / \mathrm{D} 9$ |  |  | $46 \mathrm{~L} / \mathrm{ESS}$ | 46 gnd |
| 47 L/D 10 |  |  | 47 L/ES6 | 47 L/WDV |
| 48 L/D 11 |  |  | 48 L/ES 7 | 48 gnd |
| $\begin{aligned} & 49 \text { L/D } 12 \\ & 50 \text { L/D } 13 \end{aligned}$ |  |  | 49 gnd | 49 H/USER |
|  |  |  | 50 gnd | 50 gnd |
|  |  |  | To Other Option Cards | To Other Option Cards |

Table 8-2. Mnemonics

Mnemonic Description
$25 \mathrm{MHz} \quad 25 \mathrm{MHz}$ CLOCK. The time reference for the time-counter circuitry in the statistics section. It is the inverted version of $\mathrm{L} / 25 \mathrm{MHz}$. Schematics $1^{*}$, 6 .

BH/COMOUT1-6 BUFFERED HIGH COMPARATOR OUTPUT BUS. The buffered version of H/COMOUT1-6. The buffered bus allows the comparators to be disconnected from the context recognition circuitry during PV testing. Schematic 5.

EH/DTR ECL HIGH DRIVE TRIGGER. Not Used. Schematic 7.
EH/TR ECL HIGH TRIGGER. Not used in normal operation. Driven in PV testing. Schematic 7.

EL/ME ECL LOW MASTER ENABLE. Not used in normal operation. Driven in PV testing. Schematic 7.

EL/TE ECL LOW TRIGGER ENABLE. Inter-module bus (IMB) signal that is both driven and received by the analyzer. When driven, it enables another module to look for its trigger. When received, the analyzer is enabled to look for its trigger. Schematic 7.

H/ACQREQ HIGH ACQUISITION REQUEST. An signal generated by interrupt controller U63 that causes an interrupt of microprocessor U33. Schematics $2,6 *$.

H/ARM

H/BPCREQ
HIGH ARM. Input to the H/GO flip-flop that indicates the analyzer is ready to begin data acquisition. Schematic 7

HIGH BPC REQUEST. Indicates the development station is requesting a data transfer with the analyzer. It is derived from development station control signals by logic array chip U91. Schematics 1*, 2.

H/BREAK HIGH BREAK. Emulator control bit. Not used. Schematic 7.

Table 8-2. Mnemonics (Cont'd)

| Mnemonic | Description |
| :---: | :---: |
| H/COMOUT 1-3 | HIGH COMPARATOR OUTPUT BUS 1-3. Address range 1 comparator output. Bit one idicates the emulator address is equal to the upper bound of the specified range. Bit two means the emulator address is within the range, and bit three indicates the address is equal to the lower bound. Schematics $3^{*}, 5$. |
| H/COMOUT4-6 | HIGH COMPARATOR OUTPUT BUS 4-6. Address range 2 comparator output. Bit one idicates the emulator address is equal to the upper bound of the specified range. Bit two means the emulator address is within the range, and bit three indicates the address is equal to the lower bound. Schematics $4^{\star}, 5$. |
| H/CONERR | HIGH CONTEXT ERROR. Indicates the context recognition circuitry has detected an error. Schematics $5^{*}, 6$. |
| H/DATA 0-7 | HIGH DATA BUS 0-7. Microcontroller data bus 0-7. When inverted, becomes L/DATA0-7. Schematics $2^{\star}, 6^{*}$. |
| H/GATEA | HIGH GATE A. Output from the context recognition circuit that is a counting source for event counter U60. Schematics $5 *, 6$. |
| H/GATEB | HIGH GATE B. Output from the context recognition circuit that is a counting source for event counter U60. Schematics $5 *, 6$. |
| H/GO | HIGH GO. Indicates the analyzer is in the measurement mode. Schematic 7. |
| H/ID | HIGH IDENTIFICATION. Output from logic array U91. Places board ID on the development station L/D0-7 data bus. Schematic 1. |
| H/INCLK | HIGH DATA-IN CLOCK. Output from logic array U91. Clocks data-in latch $\mathbf{U} 87$ when the development station is sending data to the analyzer. Schematic 1. |
| H/OUTCLK | HIGH DATA-OUT CLOCK. Output from the interface I/O decoder U90. Clocks data-out latch $\mathbf{U} 88$ when the analyzer is getting ready to send data to the development station. Schematic 1 . |
| H/OVERFLOW | HIGH OVERFLOW. Control bit output from analyzer status latch U7 that clears the trigger flip-flop. Schematic 7. |

Table 8-2. Mnemonics (Cont'd)
Mnemonic Description

H/PHASE4

H/PHASE 5

H/PVTEST

H/QUAL1-2

H/RUN

H/SERRDY

H/SERVICE

H/STATE1-4

H/TOOFAST

H/TRIGGER

L/ACQ

L/ACQCLR

L/ADR 0-12

HIGH PHASE 4. Output of delay line U4 that clocks the context state flip-flop. Schematics 5, 7*.

HIGH PHASE 5. Output of delay line U4 that controls the source input of the even counter. Schematics 6, 7*.

HIGH PERFORMANCE VERIFICATION TEST. Output from mode latch U72 that enables various latches and buffer during performance verification testing. Schematic 5 .

HIGH STATUS QUALIFIER BITS. Each bit indicates that the emulator status matches the specified condition. Bit one is for comparator range 1 , and bit two is for comparator range 2 . Schematic 5.

HIGH RUN. Indicates the analyzer is running. Schematics 6, 7*.

HIGH SERVICE READY. Indicates the analyzer is ready to transfer data with the development station. Schematic 1.

HIGH SERVICE. Indicates the development station is requesting a data transfer. Schematic 1.

HIGH CONTEXT STATE BITS. Feedback bits in the context recognition circuit state machine. Schematic 5.

HIGH TOO FAST. Indicates the emulator is running too fast for software analysis. Schematics 6, 7*.

HIGH TRIGGER. Output of flip-flop U23 that controls the trigger signals on the inter-module bus (IMB). Schematic 7 .

LOW ACQUISITION. Output from the master I/O decoder U 51 that enables the comparator and context recognition I/O decoders. Schematics $2^{\star}, 3,4,5$.

LOW ACQUISITION CLEAR. Output from the context I/O decoder U69 that clears the time and event counter flip-flops. Schematics $5^{\star}, 6$.

LOW ADDRESS BUS 0-12. Microcontroller address bus. Uses negative logic: high $=0$, low $=1$. Schematics $1,2 *, 3,4,5,6$.

Table 8-2. Mnemonics (Cont'd)

| Mnemonic | Description |
| :---: | :---: |
| L/ANAL | LOW ANALYSIS. Signals the analyzer that the emulation bus contains a valid emulation state. It is driven by the emulator. Schematics 3, 5*, 7 . |
| L/BPC | LOW BPC. Output from master I/O decoder U51 that enables the interface I/O decoder for data transfer with the development station. Schematics $1,2 *$. |
| L/CONEND | LOW CONTEXT END. Output from the context recognition circuitry that gates operation of the time, event and sequence counters. Schematics $5^{*}, 6$. |
| L/CTL | LOW CONTROL. Output from the master I/O decoder U51 that enables the IMB and control decoder U24. Schematics $2^{\star}, 7$. |
| L/DATA-IN | LOW DATA-IN. Enables the data-in latch U87 when the development station is sending data to the analyzer. Schematic 1. |
| L/DATA-OUT | LOW DATA-OUT. Enables the data-out latch U88 when the analyzer is sending data to the development station. Schematic 1. |
| L/DATA0-7 | LOW DATA BUS 0-7. Microcontroller data bus. <br> Uses negative logic: high $=0$, low $=1$. <br> Schematics $1^{\star}, 2^{\star}, 3,4,5^{\star}, 6^{\star}, 7^{\star}$. |
| L/EA0-23 | LOW EMULATOR ADDRESS BUS 0-23. Emulator address bus that is monitored by the analyzer. Uses negative logic: high $=0$, low $=1$. Schematic 3 . |
| L/EN 1-6 | LOW ENABLE COMPARATOR BITS 1-6. Enables the six comparators in address range 1 . Schematic 3. |
| L/EN7-12 | LOW ENABLE COMPARATOR BITS 7-12. Enables the six comparators in address range 2 . Schematic 4. |
| L/ESO-7 | LOW EMULATOR STATUS BUS 0-7. Emulator status bus that is monitored by the analyzer. Uses negative logic: high $=0$, low $=1$. Schematic 5 . |
| L/GATEA | LOW GATE A. Output from the context recognition circcit that is a counting source for time counter U60. Schematics $5^{*}, 6$. |

Table 8-2. Mnemonics (Cont'd)
Mnemonic Description

L/GATEB LOW GATE B. Output from the context recognition circuit that is a counting source for time counter U60. Schematics $5 *, 6$.

L/GOCLR LOW GO CLEAR. Output from delay chip U4 that clears the go flip-flop. Schematic 7.

L/INTACK LOW INTERRUPT ACKNOWLEDGE. Output from the IMB and control decoder U24 that indicates to the interrupt controller U63 that the microprocessor is ready to service the interrupt. Schematics 6, 7*

LOW INTERRUPT CLEAR. Output from the interface I/O decoder U90 that indicates the development station interrupt to transfer data is complete. Schematic 1.

L/MBRKS

L/MODE1-6

L/MODE4

L/MODECLK

L/MSTCLK

L/OPR

L/OVCOUNT

L/OVTIME

LOW MEMORY BREAK STATUS. Emulation bus bit driven by the analyzer that controls emulation memory breaks. Schematic 5, 7*.

LOW MODE BITS 1-6. Output from mode latch U72 that controls the context logic arrays. Schematic 5.

LOW MODE BIT 4. Output from mode latch U72 that controls the sequence count flip-flops. Schematics $5 \star$, 6 .

LOW MODE CLOCK. Output from the context I/O decoder U69 that clocks the mode latch and clears the context state flipflops. Schematic 5 .

LOW MASTER CLOCK. A clock signal derived from the microprocessor internal clock. It is used to enable the comparator I/O decoders. Schematics $2 *, 3,4$.

LOW OPERATION. Output from the interface I/O decoder U90 that enables the operation latch when the development station is sending an operation instruction to the analyzer. Schematic 1.

LOW OVER COUNT. Not used. Schematics 6*, 7.
LOW OVER TIME. Not used. Schematics 6*, 7.

Table 8-2. Mnemonics (Cont'd)

| Mnemonic | Description |
| :---: | :---: |
| L/PVTEST | LOW PERFORMANCE VERIFICATION TEST. An inverted version of H/PVTEST that enables various latches and buffers during performance verification testing. Schematic 5 . |
| L/PVTEST1 | LOW PERFORMANCE VERIFICATION TEST 1. Output from context I/O decoder U69 that enables buffer U5 to place control bits on the L/DATA bus. Schematics $5 *, 7$. |
| L/PVTEST2 | LOW PERFORMANCE VERIFICATION TEST 2. Output from context I/O decoder U69 that enables buffer U75 to place comparator output, and status qualifier bits on the L/DATA bus. Schematic 5. |
| L/PVTEST3 | LOW PERFORMANCE VERIFICATION TEST 3. Output from context I/O decoder U69 that enables buffer U74 to place context state bits on the L/DATA bus. Schematic 5 . |
| L/RAM1-3 | LOW RAM BITS 1-3. Output from master I/O decoder U51 that enables RAMs U38, U37, and U36. Schematic 2. |
| L/RESET | LOW RESET. Output from logic array U91 that resets the analyzer. Schematics $1^{*}, 2,7$. |
| L/ROM | LOW ROM. Output from master I/O decoder U51 that enables ROM U35. Schematic 2. |
| L/RUN | LOW RUN. Not used. Schematic 6. |
| L/STATCLK | LOW STATUS BUFFER CLOCK. Output derived from the microprocessor internal timing and address lines that clocks status RAM buffer U10. Schematics $2^{*}, 5$. |
| L/STATIO1-8 | LOW STATISTICS INPUT-OUTPUT BITS $1-8$. Output bits from the statistics I/O decoder U85 that control the read and writer operations of the time, even, and sequence counter and the interrupt controller. Schematic 6. |

Table 8-2. Mnemonics (Cont'd)

| Mnemonic | Description |
| :---: | :---: |
| L/STATS | LOW STATISTICS. Output from the master I/O decoder U51 that enables the data bus transceiver U70, and statistics I/O decoder U85. Schematics $2 *, 6$. |
| L/STATWRT | LOW STATISTICS WRITE. Output derived from the microprocessor internal timing and address lines that enables read and write operations on status RAM U11. Schematics $2 \star$, 5 . |
| L/STEP | LOW STEP. Output from the IMB and control decoder U24 that controls the time event, and sequence counters, during 'step' mode operation. Schematics 6,7 *. |
| L/WRITE | LOW WRITE. Output derived from the microprocessor internal timing and read/write lines that enables most $I / O$ sections. Schematics 1, 2*, 5, 6, 7. |
| L/WRTCLK | LOW WRITE CLOCK. Output derived from the microprocessor internal timing and read/write lines that clocks RAMs U36, U37, and U38. Schematic 2. |
| LL/DATA0-7 | LATCHED, LOW DATA BUS 0-7. Latched version of the microcontroller L/DATA bus. It is used to set emulator address 'don't care' bits. Schematic 3. |
| LL/EA0-23 | LATCHED, LOW EMULATOR ADDRESS BUS 0-23. Latched version of the emulator address bus; it is the input to the address comparators. Schematics $3^{\star}, 4$. |
| LL/ES0-7 | LATCHED, LOW EMULATOR STATUS BUS 0-7. Latched version of the emulator status bus; it is the input to the emulator status RAM U1i. Schematic 5 . |

Table 8-3. Logic Symbols

## GENERAL

All signals flow from left to right, relative to the symbol's orientation with inputs on the left side of the symbol, and outputs on the right side of the symbol (the symbol may be reversed if the dependency notation is a single term.)

All dependency notation is read from left to right (relative to the symbol's orientation).
An external state is the state of an input or output outside the logic symbol.
An internal state is the state of an input or output inside the logic symbol. All internal states are True $=$ High.

## SYMBOL CONSTRUCTION

Some symbols consist of an outline or combination of outlines together with one or more qualifying symbols, and the representation of input and output lines.


Some have a common Control Block with an array of elements:


CONTROL BLOCK - All inputs and dependency notation affect the array elements directly. Common outputs are located in the control block. (Control blocks may be above or below the array elements.)

ARRAY ELEMENTS -All array elements are controlled by the control block as a function of the dependency notation. Any array element is independent of all other array elements. Unless indicated, the least significant element is always closest to the control block. The array elements are arranged by binary weight. The weights are indicated by powers of 2 (shown in [ ]).

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Table 8-3. Logic Symbols (Cont'd)
INPUTS - Inputs are located on the left side of the symbol and are affected by their dependency notation.
Common control inputs are located in the control block and control the inputs/outputs to the array elements according to the dependency notation.

Inputs to the array elements are located with the corresponding array element with the least significant element closest to the control block.

OUTPUTS - Outputs are located on the right side of the symbol and are effected by their dependency notation.
Common control outputs are located in the control block.
Outputs of array elements are located in the corresponding array element with the least significant bit closest to the control block.

CHIP FUNCTION - The labels for chip functions are defined, i.e., CTR - counter, MUX - multiplexer.

## DEPENDENCY NOTATION

Dependency notation is always read from left to right relative to the symbol's orientation.
Dependency notation indicates the relationship between inputs, outputs, or inputs and outputs. Signals having a common relationship will have a common number, i.e., C7 and 7D....C7 controls D. Dependency notation $2,3,5,6+/ 1, C 7$ is read as when 2 and 3 and 5 and 6 are true, the input will cause the counter to increment by one count....or (/) the input (C7) will control the loading of the input value (7D) into the $D$ flip-flops.

The following types of dependencies are defined:
a. AND (G), OR (V), and Negate (N) denote Boolean relationship between inputs and outputs in any combination.
b. Interconnection $(Z)$ indicates connections inside the symbol.
c. Control (C) identifies a timing input or a clock input of a sequential element and indicates which inputs are controlled by it.
d. Set (S) and Reset (R) specify the internal logic states (outputs) of an RS bistable element when the R or S input stands at its internal 1 state.
e. Enable (EN) identifies an enable input and indicates which inputs and outputs are controlled by it (which outputs can be in their high impedance state).
f. Mode (M) identifies an input that selects the mode of operation of an element and indicates the inputs and outputs depending on that mode.
g. Address (A) identifies the address inputs.
h. Transmission (X) identifies bi-directional inputs and outputs that are connected together when the transmission input is true.

## DEPENDENCY NOTATION SYMBOLS

| A | Address (selects inputs/outputs) (indicates binary range) | N | Negate (compliments state) |
| :--- | :--- | :--- | :--- |
| C | Control (permits action) | R | Reset Input |
| EN | Enable (permits action) | S | Set Input |
| G | AND (permits action) | V | OR (permits action) |
| M | Mode (selects action) | Z | Interconnection |
|  |  | $X$ | Transmission |

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Table 8-3. Logic Symbols (Cont'd)

## OTHER SYMBOLS



| BG | Borrow Generate | CO | Carry Output | J | J Input |
| :--- | :--- | :--- | :--- | :--- | :--- |
| BI | Borrow Input | CP | Carry Propagate | K | K Input |
| BO | Borrow Output | CT | Content | P | Operand |
| BP | Borrow Propagate | D | Data Input | T | Transition |
| CG | Carry Generate | E | Extension (input or output) | + | Count Up |
| CI | Carry Input | F | Function | - | Count Down |

## MATH FUNCTIONS

| I. | Adder |
| :--- | :--- |
| ALU | Arithmetic Logic Unit |
| COMP | Comparator |
| DIV | Divide By |
| $=$ | Equal To |


| $>$ | Greater Than |
| :--- | :--- |
| $<$ | Less Than |
| CPG | Look Ahead Carry Generstor |
| $\pi$ | Multiplier |
| P-Q | Subtractor |

## CHIP FUNCTIONS

| BCD | Binary Coded Decimal |
| :--- | :--- |
| BIN | Binary |
| BUF | Buffer |
| CTR | Counter |
| DEC | Decimal |


| DIR | Directional | RAM | Random Access Memory |
| :--- | :--- | :--- | :--- |
| DMUX | Demultiplexer | RCVR | Line Receiver |
| FF | Flip-Flop | ROM | Read Only Memory |
| MUX | Multiplexer | SEG | Segment |
| OCT | Octal | SRG | Shift Register |

## DELAY and MULTIVIBRATORS

| $\Omega \square$ | Astable |
| :--- | :--- |
| 100 ns | Delay |
| $\square$ | Nonretriggerable Monostable |
| NV | Nonvolatile |
| $\square$ | Retriggerable Monostable |

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Table 8-4. Schematic Diagram Notes

REAR-PANEL MARKING
MANUAL CONTROL
IVIVER ADJUSTMENT
ELECTRICAL TEST POINT TP (WITH NUMBER)
WIRE COLORS ARE GIVEN BY NUMBERS IN PARENTHESES USING THE RESISTOR COLOR CODE

| $\left[\begin{array}{ll}\text { (925) IS WHT-RED-GRN }\end{array}\right.$ |  |
| :--- | :--- |
| 0-BLACK | 5-GREEN |
| 1-BROWN | $6-$ BLUE |
| 2-RED | $7-$ VIOLET |
| 3- ORANGE | 8-GRAY |
| 4- YELLOW | 9-WHITE |

* OPTIMUM VALUE SELECTED AT FACTORY, TYPICAL VALUE SHOWN; PART MAY HAVE BEEN OMITTED.
UNLESS OTHERWISE INDICATED: RESISTANCE IN OHMS CAPACITANCE IN PICOFARADS INDUCTANCE IN MICROHENRIES
$\mu \mathrm{P}=$ MICROPROCESSOR
P/O = PART OF

```
(925)
(925)
NUMBERED WAVEFORM NUMBER CORRESPONDS TO ELECTRICAL TEST POINT NO.
LETTERED TEST POINT NO MEASUREMENT AID PROVIDED
COMMON CONNECTIONS. ALL LIKE-DESIGNATED POINTS ARE CONNECTED.
NUMBER ON WHITE BACKGROUND = OFF-PAGE CONNECTION. LARGE NUMBER ADJACENT = SERVICE SHEET NUMBER FOR OFF-PAGE CONNECTION.
CIRCLED LETTER = OFF-PAGE CONNECTION BETWEEN PAGES OF SAME SERVICE SHEET.

INDICATES SINGLE SIGNAL LINE

NUMBER OF LINES ON A BUS


Table 8-5. IC to Schematic Cross-Reference
\begin{tabular}{|c|c|c|}
\hline IC Schematic & IC Schematic & IC Schematic \\
\hline U1 7 & U40 4 & U80 6 \\
\hline U2 7 & U41 4, 5 & U81 6 \\
\hline U3 7 & U42 4 & U82 6 \\
\hline U4 7 & U43 4 & U83 6 \\
\hline U5 7 & U44 4 & U84 1,6 \\
\hline U6 7 & U45 4 & U85 6 \\
\hline U7 7 & U46 4 & U86 1 \\
\hline U8 7 & U47 4 & U87 1 \\
\hline \multirow[t]{2}{*}{U9 5} & U48 2 & U88 1 \\
\hline & U49 2 & U89 1 \\
\hline U10 5 & & \\
\hline U11 5 & & U90 1 \\
\hline U12 3 & U50 2, 5 & U911 \\
\hline U13 3 & U51 2 & U92 1 \\
\hline U14 3 & U52 2 & U93 1 \\
\hline U15 3 & U53 2 & \\
\hline U16 3 & U54 4 & Y1 2 \\
\hline U17 7 & U55 3 & \\
\hline U18 7 & US6 5 & \\
\hline \multirow[t]{2}{*}{U19 7} & U57 5 & \\
\hline & U58 5 & \\
\hline U20 7 & U59 3 & \\
\hline U21 7 & & \\
\hline U22 7 & U60 6 & \\
\hline U23 7 & U61 6 & \\
\hline U24 7 & U62 6 & \\
\hline U25 5 & U63 6 & \\
\hline U26 3 & U64 6 & \\
\hline U27 3 & U65 2 & \\
\hline U28 3 & U66 2 & \\
\hline \multirow[t]{2}{*}{U29 3} & U67 3 & \\
\hline & U68 5 & \\
\hline U30 3 & U69 5 & \\
\hline U31 3 & & \\
\hline U32 3 & U70 6 & \\
\hline U33 2 & U71 NA & \\
\hline SU34 2 & U72 5 & \\
\hline U35 2 & U73 5 & \\
\hline U36 2 & U74 5 & \\
\hline U37 2 & U75 5 & \\
\hline U38 2 & U76 5 & \\
\hline \multirow[t]{3}{*}{U39 2} & U77 2, 5 & \\
\hline & U78 6 & \\
\hline & U79 6 & \\
\hline
\end{tabular}

\section*{NOTES}


Component Locator

\begin{tabular}{|c|c|c|}
\hline REF HP PART & \begin{tabular}{l}
mfG PART \\
NUMBER
\end{tabular} & \[
+5 \mathrm{GND}
\] \\
\hline U84 1820-2685 & 74F02PC & \\
\hline U86 1820-1997 & SN74LS374N & \\
\hline U87 1820-1997 & SN74LS374N & 2010 \\
\hline U88 1820-1997 & SN74L5374N & \\
\hline U8180-191 & SN/4L240N & \\
\hline U90 1820-1240 & SN4151380 & 168 \\
\hline U92 1820-1112 & SN74LS74AN & \\
\hline U93 1820-0682 & SN74503N & \\
\hline
\end{tabular}

PARTS ON SChematic 1
\begin{tabular}{|ll|}
\hline \begin{tabular}{ll} 
C1-66, C69-92. & CR3. \\
TP1 \(2,2,3,4,8,9,10,11\).
\end{tabular} \\
\hline
\end{tabular}


Component Locator

\begin{tabular}{|c} 
Figure \(8-3.3\) shematic 2 \\
Microcontritoler \\
\(8-25\)
\end{tabular}


Component Locator



Component Locator



Component Locator



Component Locator



Component Locator


\section*{SIGNATURE TABLE LOOP A}

LOOP A signatures are valid while running the Performance Analyzer Reset Test.
Start = Positive edge of TP2 on the 64100 A mainframe I/O board, or TP 6 on the 64110 A mainframe CPU/IO board.
Stop \(=\) Negative edge of TP2 on the 64100 A mainframe I/O board, or TP6 on the 64110 A mainframe CPU/IO board.
Clock = Negative edge of U89, pin 3 on the software performance analyzer.
Clock Qualifier = A high on U89, pin 9 on the software performance analyzer Qualified signatures require a 5005 A Signature Multimeter.
Ground = Use a ground lead from the probe to a ground point on the software performance analyzer.
high \(=\) a solid HIGH on the node under test.
low = a solid LOW on the node under test.
All logic is positive logic.
\(\mathrm{Vh}=0007\)

NODE SIG
Microprocessor
Schematic 2
U 33-1 low
U 33-2 high
U 33-4 0003
U 33-7 high
U 33-37 0005

NODE SIG
Control Bit Buffer/Receiver Schematic 2

U 89-1 low
U 89-2 0007
U 89-3 0007
U89-4 0004
U 89-5 0002
\begin{tabular}{l} 
U 89-6 high \\
U 89-7 \\
\hline
\end{tabular}
U89-7 0007
U 89-8 high
U 89-9 000
U89-10 low
U 89-11 0000
U 89-12 low
U 89-13 0000
U89-13 0000
U 89-14 low
U \(89-15\) 000
\(\begin{array}{ll}\text { U 89-15 } & 0005 \\ \text { U 89-16 } & 0003\end{array}\)
\(\begin{array}{r}\text { U 89-16 } \\ \text { U 89-17 } \\ \text { U } \\ \hline\end{array}\)
\(\begin{array}{r}\text { U 89-17 } \\ \text { U 89-18 } \\ \text { U } \\ \hline\end{array}\)
U 89-18 0007
U 89-19
U 89-20 high

NODE SIG
Mainframe Control
Logic Array
Schematic 2
U 91-2 0004
U 91-3 high
U 91-8 0005
U 91-9 0002
U 91-10 0004
U 91-10 0004
U 91-12 0004
U 91-13 high
U91-13 low
U91-14 low
U 91-15 low

U 91-17 0005
U 91-18 000
U 91-19 low
U 91-20
\(91-21\)
low
U 91-21 0007
\(\begin{array}{lll}\text { U 91-22 } & \text { low } \\ \text { U 91-23 } & 0007\end{array}\)
U 91-23 0007
U 91-24 0003
U 91-25 0002
U 91-26 0007
U 91-27 000

\section*{SIGNATURE TABLE LOOP B.}

LOOP B signatures are valid while running the Mainframe / Analyzer Interface Test.

Start \(=\) Positive edge of TP11 on the sof tware performance analyzer
Stop = Positive edge of TP 10 on the sof tware performance analyzer.
Clock = Positive edge of TP7 on the sof tware performance analyzer.
Clock Qualifier = No qualified clocks are necessary.
Ground = Use a ground lead from the probe to a ground point on the sof tware performance analyzer.
high \(=\) a solid HIGH on the node under test.
low \(=\) a solid LOW on the node under test.
All logic is positive logic.
\(\mathrm{Vh}=\mathrm{CF} 44\)
\begin{tabular}{|c|c|c|c|}
\hline NODE SIG & NODE SIG & NODE SIG & NODE SIG \\
\hline \multirow[t]{3}{*}{Microprocessor Schematic 2} & U 33-34 CF44 & RAMs & Data Bus \\
\hline & U 33-35 0000 & \multirow[t]{2}{*}{Schematic 2} & \multirow[t]{2}{*}{Transceiver Schematic 2} \\
\hline & U 33-36 1478 & & \\
\hline U 33-1 low & U 33-37 CF44 & U 36-12 low & \\
\hline U 33-2 high & U 33-38 0000 & U 36-18 CF44 & U 39-1 6A03 \\
\hline U 33-3 high & U 33-39 low & U 36-19 1478 & U 39-2 10PU \\
\hline U 33-4 CF44 & U 33-40 high & U 36-20 low & U 39-4 0146 \\
\hline U 33-5 0000 & & U 36-21 6A03 & U 39-6 CH32 \\
\hline U 33-6 low & & U 36-24 high & U 39-8 03U4 \\
\hline U 33-7 high & ROM & & U 39-19 6A03 \\
\hline U 33-8 FAPF & Schematic 2 & U 37-12 low & \\
\hline U 33-9 H62A & & U 37-18 CF44 & \\
\hline U 33-10 F04P & U 35-12 low & U 37-19 1478 & \\
\hline U 33-11 F519 & U 35-18 H647 & U 37-20 low & \\
\hline U 33-12 36PF & U 35-19 1478 & U 37-21 6A03 & \\
\hline U 33-13 2353 & U 35-20 low & U 37-24 high & \\
\hline U 33-14 A83F & U 35-21 high & & \\
\hline U 33-15 6A03 & U 35-24 high & U 38-12 low & \\
\hline U 33-16 A83F & & U 38-18 CF44 & \\
\hline U 33-17 A83F & & U 38-19 1478 & \\
\hline U 33-18 A83F & & U 38-20 low & \\
\hline U 33-19 6A02 & & U 38-21 6A03 & \\
\hline U 33-20 6A03 & & U 38-24 high & \\
\hline U 33-21 6A03 & & & \\
\hline U 33-22 A83F & & & \\
\hline U 33-23 A83F & & & \\
\hline U 33-32 6A03 & & & \\
\hline U 33-33 high & & & \\
\hline
\end{tabular}

Appendix B - Model 64310A
\begin{tabular}{|c|c|c|c|}
\hline NODE SIG & NODE SIG & NODE SIG & NODE SIG \\
\hline Address Bus & Master I/O & Misc Gates & Interface Address \\
\hline Buffers & Decoder & Schematic 2 & Latch \\
\hline Schematic 2 & Schematic 2 & & Schematic 1 \\
\hline & & U 65-1 H647 & \\
\hline U 48-2 H647 & U 51-1 H646 & U 65-2 A83F & U 86-1 pulsing \\
\hline U 48-3 H647 & U 51-2 H647 & U 65-3 CF44 & U 86-11 pulsing \\
\hline U 48-4 A83F & U 51-3 6A03 & U65-8 6A03 & \\
\hline U 48-5 1478 & U 51-4 low & U 65-9 high & Data-In Latch \\
\hline U 48-6 A83F & U 51-5 0000 & U 65-10 H647 & Schematic 1 \\
\hline U 48-7 H646 & U 51-6 CF44 & & \\
\hline U 48-8 A83F & U 51-7 CF44 & U 66-4 CF 44 & U 87-1 pulsing \\
\hline U 48-9 H647 & U 51-9 CF44 & U66-S 6A03 & U 87-11 pulsing \\
\hline U 48-11 6A03 & U 51-10 CF44 & U 66-6 H647 & \\
\hline U 48-12 1478 & U 51-11 H647 & & \\
\hline U 48-13 6A02 & U 51-12 6A02 & & Data-Out Latch \\
\hline U 48-14 1478 & U 51-13 CF45 & & Schematic 1 \\
\hline U 48-15 A83F & U 51-14 high & & \\
\hline U 48-161478 & U 51-15 high & & U 88-1 pulsing \\
\hline U 48-17 6A03 & & & U 88-11 pulsing \\
\hline U 48-18 6A03 & & & \\
\hline & Misc Gates & & \\
\hline U 49-2 H647 & Schematic 2 & & Ready Flip-flops \\
\hline U 49-3 6A6P & & & Schematic 1 \\
\hline U 49-4 FAPF & U 52-1 CF44 & & \\
\hline U 49-5 795H & U 52-2 0000 & & U 92-1 pulsing \\
\hline U 49-6 F04P & U 52-3 low & & U 92-2 high \\
\hline U 49-7 9U17 & U 52-40000 & & U 92-3 pulsing \\
\hline U 49-8 36PF & U 52-5.CF44 & & U 92-4 high \\
\hline U 49-9 0000 & U 52-6 CF44 & & U 92-5 pulsing \\
\hline U 49-11 CF44 & U 52-8 6A03 & & U 92-6 pulsing \\
\hline U 49-12 8AA8 & U 52-9 0000 & & U 92-8 pulsing \\
\hline U 49-13 2353 & U 52-10 H647 & & U 92-9 pulsing \\
\hline U 49-14 7F0A & U 52-11 H647 & & U 92-10 high \\
\hline U 49-15 F519 & U 52-12 H647 & & U 92-11 pulsing \\
\hline U 49-16 76A8 & U 52-13 6A03 & & U 92-12 pulsing \\
\hline U 49-17 H62A & & & U 92-13 pulsing \\
\hline \multicolumn{4}{|l|}{U 49-18 6A03} \\
\hline & Wait-State & & \\
\hline \multirow[t]{2}{*}{} & \multicolumn{2}{|l|}{Shift Register} & Board ID Gates. \\
\hline \multicolumn{4}{|l|}{\multirow[b]{2}{*}{Schematic 2 Schematic 2}} \\
\hline & & & \\
\hline & U 53-9 high & & U 93-4 high \\
\hline U 50-1 low & U 53-10 H647 & & U 93-5 low \\
\hline U 50-2 high & U 53-11 0000 & & U 93-6 pulsing \\
\hline U 50-3 6A03 & U 53-13 1478 & & U 93-8 pulsing \\
\hline U 50-4 H647 & & & U 93-9 high \\
\hline U 50-5 6A03 & & & U 93-10 low \\
\hline U 50-6 H647 & & & U 93-11 pulsing \\
\hline U 50-12 CF44 & & & U 93-12 pulsing \\
\hline U 50-13 0000 & & & U 93-13 pulsing \\
\hline
\end{tabular}

SIGNATURE TABLE LOOP C.
LOOP C signatures are valid while running the Data Acquisition Test.
Start = Positive edge of TP 11 on the sof tware performance analyzer.
Stop \(=\) Positive edge of TP 10 on the software performance analyzer.
Clock = Positive edge of TP7 on the sof tware performance analyzer.
Clock Qualifier = No qualified clocks are necessary.
Ground \(=\) Use a ground lead from the probe to a ground point on the software performance analyzer.
high \(=\) a solid HIGH on the node under test.
low \(=\) a solid LOW on the node under test.
All logic is positive logic.
\(\mathrm{Vh}=\mathrm{F} 186\)
\begin{tabular}{|c|c|c|c|}
\hline NODE SIG & NODE SIG & NODE SIG & NODE SIG \\
\hline \multirow[t]{3}{*}{Misc Buffers Schematic 7} & U 6-9 PA98 & \multirow[t]{4}{*}{Status RAM Load Latch Schematic 5} & \multirow[t]{3}{*}{Status RAM Schematic 5} \\
\hline & U 6-11 02U6 & & \\
\hline & U 6-12 85 H 5 & & \\
\hline U 5-1 1650 & U 6-15 1H4U & & U 11-8 low \\
\hline U 5-2 high & U 6-16 UCCU & U 10-1 low & U 11-10 FH61 \\
\hline U 5-3 CCF6 & U 6-17 3C2A & U 10-2 82A2 & U 11-12 9U6H \\
\hline U 5-4 3721 & U 6-18 9A07 & U 10-3 4HPH & U 11-14 9780 \\
\hline U 5-5 U6A? & U 6-19 high & U 10-4 5748 & U 11-16 0183 \\
\hline U 5-6 6H9C & & U 10-5 8AAU & U 11-17 high \\
\hline U 5-7 CCF6 & & U 10-6 P2U1 & U 11-18 low \\
\hline U 5-9 CCF6 & Analyzer Status & U 10-7 CAUH & U 11-19 low \\
\hline U 5-11 7A40 & Latch & U 10-8 F718 & U 11-20 F497 \\
\hline U 5-13 7A40 & Schematic 7 & U 10-9 CH 3 U & U 11-22 high \\
\hline U 5-15 3721 & & U 10-11 0000 & \\
\hline U 5-17 7A40 & U 7-1 low & U 10-12 AUF1 & \\
\hline \multirow[t]{3}{*}{U 5-19 low} & U 7-2 high & U 10-13 CC67 & \multirow[t]{3}{*}{Misc Gates Schematic 7} \\
\hline & U 7-3 2A67 & U 10-14 H6CF & \\
\hline & U 7-4 P1H0 & U 10-15 6C90 & \\
\hline Analyzer Status & U 7-5 low & U 10-16 8H68 & U 20-1 CCF6 \\
\hline Latch & U 7-6 high & U 10-178800 & U 20-2 CCF6 \\
\hline \multirow[t]{2}{*}{Schematic 7} & U 7-9 high & U 10-18 6258 & U 20-3 7A40 \\
\hline & \(\mathrm{U} 7-11 \mathrm{H} 1 \mathrm{AU}\) & U 10-19 F117 & U 20-4 AF1H \\
\hline U 6-1 low & U 7-12 high & & U 20-5 high \\
\hline U 6-2 low & U 7-15 low & & U 20-6 6H9C \\
\hline U 6-3 2A67 & U 7-16 low & & U 20-8 6H9C \\
\hline U 6-4 P1H0 & U 7-18 9A07 & & U 20-9 high \\
\hline U 6-5 low & U 7-19 high & & U 20-10 AF1H \\
\hline U 6-6 high & & & U 20-11 CCF6 \\
\hline & & & U 20-12 high \\
\hline & & & U 20-13 7A40 \\
\hline
\end{tabular}
\begin{tabular}{|c|c|c|c|}
\hline NODE SIG & NODE SIG & NODE SIG & NODE SIG \\
\hline \multirow[t]{3}{*}{Misc Flip-flops Schematic 7} & \multirow[t]{3}{*}{Misc Gate Schematic 5} & Context 2 Logic & Context State \\
\hline & & Array & Flip-flops \\
\hline & & Schematic 5 & Schematic 5 \\
\hline \multicolumn{4}{|l|}{U 22-1 FC83} \\
\hline U 22-2 low & U 41-11 1H46 & U 58-1 low & U 68-1 33A3 \\
\hline U 22-3 high & U 41-12 993U & U 58-2 9U6H & U 68-2 CHC 4 \\
\hline U 22-4 high & U 41-13 7076 & U 58-10 P658 & U 68-3 7F32 \\
\hline U 22-5 3721 & & U 58-11 A65H & U 68-4 76H8 \\
\hline U 22-6 U6A7 & & U 58-12 1945 & U 68-5 P658 \\
\hline U 22-7 high & Inverter & U 58-13 76H8 & U 68-6 34A3 \\
\hline U 22-9 low & Schematic 5 & U 58-14 low & U 68-7 U525 \\
\hline U 22-10 high & & U 58-15 7UAU & U 68-9 CCF6 \\
\hline U 22-11 AHC1 & U 50-8 low & U 58-16 U0C0 & U 68-10 U47U \\
\hline U 22-12 6F37 & U 50-9 high & U 58-17 HAUF & U 68-11 35U9 \\
\hline U 22-13 low & & U 58-18 7CC9 & U 68-12 A65H \\
\hline U 22-14 7A40 & & U 58-19 C741 & U 68-13 1945 \\
\hline \multirow[t]{2}{*}{U 22-15 6C93} & Context State & U 58-20 U525 & U 68-14 3P4C \\
\hline & Flip-flops & U 58-21 U47U & U 68-15 UUFH \\
\hline U 23-1 low & Schematic 5 & U 58-22 UUFH & \\
\hline U 23-2 low & & U 58-23 CHC4 & \\
\hline U 23-3 CCF6 & U 56-1 33A3 & U 58-27 FH61 & Context I/O \\
\hline U 23-4 high & U 56-2 81P9 & U 58-28 high & Decoder \\
\hline U 23-5 low & U 56-3 406U & & Schematic 5 \\
\hline U 23-6 high & U 56-4 7CC9 & & \\
\hline U 23-7 AF1H & U 56-5 7UAU & Read/Write Gates & U 69-1 F718 \\
\hline U 23-9 6H9C & U 56-6 H9FC & Schematic 2 & U 69-2 CAUH \\
\hline U 23-10 1496 & U 56-7 184H & & U 69-3 4152 \\
\hline U 23-11 high & U 56-9 CCF6 & U 65-1 80H4 & U 69-4 8P00 \\
\hline U 23-12 low & U 56-10 F17P & U 65-2 HP21 & U 69-5 H165 \\
\hline U 23-13 high & U 56-11 00U8 & U 65-3 F497 & U 69-6 high \\
\hline U 23-14 6P04 & U 56-12 U0C0 & U 65-4 HP21 & U69-7 1650 \\
\hline \multirow[t]{3}{*}{U 23-15 3721} & U 56-13 HAUF & U65-5 0000 & U 69-9 P649 \\
\hline & U 56-14 3U24 & U 65-6 F186 & U 69-10 31C6 \\
\hline & U 56-15 UPA2 & U 65-8 7HPC & U 69-11 high \\
\hline \multicolumn{2}{|l|}{IMB/Control} & U 65-9 high & U 69-12 33A3 \\
\hline \multicolumn{2}{|l|}{I/O Decoder} & U 65-10 CF6H & U 69-13 5U64 \\
\hline \multirow[t]{2}{*}{Schematic 7} & Misc Flip-flop & U 65-11 F497 & U 69-14 high \\
\hline & Schematic 5 & U 65-12 80H4 & U 69-15 CH8C \\
\hline U 24-1 F718 & & U 65-13 HP21 & \\
\hline U 24-2 CAUH & U 57-1 2P5F & & \\
\hline U 24-3 5748 & U 57-2 high & & \\
\hline U 24-4 4152 & U 57-3 U0C0 & & \\
\hline U 24-5 H540 & U 57-4 high & & \\
\hline U 24-6 high & U 57-5 1H46 & & \\
\hline U 24-7 6C93 & & & \\
\hline U 24-9 FC83 & & & \\
\hline U 24-10 6P04 & & & \\
\hline U 24-11 H1AU & & & \\
\hline U 24-12 1496 & & & \\
\hline U 24-13 7A40 & & & \\
\hline U 24-14 02U6 & & & \\
\hline U 24-15 high & & & \\
\hline
\end{tabular}
\begin{tabular}{|c|c|}
\hline NODE SIG & NODE SIG \\
\hline \multirow[t]{2}{*}{Mode Latch} & \multirow[t]{2}{*}{PV Test Buffer Schematic 5} \\
\hline & \\
\hline U 72-2 1607 & U 75-1 P649 \\
\hline U 72-5 F65C & U 75-2 4821 \\
\hline U 72-6 76F7. & U 75-4 H2FH \\
\hline U 72-9 2P5F & U 75-6 7F37 \\
\hline U 72-12 high & U 75-8 9U6H \\
\hline U 72-15 5202 & U 75-11 FH61 \\
\hline U 72-16 4070 & U 75-13 CP6H \\
\hline U 72-19 F909 & U 75-15 993U \\
\hline & U 75-17 2U11 \\
\hline & U 75-19 P649 \\
\hline \multicolumn{2}{|l|}{PV Test Latch} \\
\hline Schematic 5 & Context 1 Logic \\
\hline & Array \\
\hline U 73-2 4821 & Schematic 5 \\
\hline U 73-5 H2FH & \\
\hline U 73-6 7F37 & U 76-1 low \\
\hline U 73-15 CP6H & U 76-10 P658 \\
\hline U 73-16 993U & U 76-11 A65H \\
\hline \multirow[t]{3}{*}{U 73-19 2U11} & U 76-12 1945 \\
\hline & U 76-13 76H8 \\
\hline & U 76-14 low \\
\hline PV Test Buffer & U 76-15 7UAU \\
\hline \multirow[t]{2}{*}{Schematic 5} & U 76-16 U0C0 \\
\hline & U 76-17 HAUF \\
\hline U 74-2 81P9 & U 76-18 7CC9 \\
\hline U 74-4 F17P & U 76-19 76F7 \\
\hline U 74-6 CHC4 & U 76-20 U525 \\
\hline U 74-8 U47U & U 76-21 U47U \\
\hline U 74-11 U525 & U 76-22 UUFH \\
\hline U 74-13 UUFH & U 76-23 CHC4 \\
\hline U 74-15 184H & U 76-27 FH61 \\
\hline U 74-17 UPA2 & U 76-28 high \\
\hline
\end{tabular}

Inverters
Schematic 5
U 77-5 F186
U77-6 0000
U 77-8 C74 U 77-9 76F7

SIGNATURE TABLE LOOP D.
LOOP D signatures are valid while running the Time, Event, and Sequence Counter Test.

Start = Positive edge of TP11 on the sof tware performance analyzer. Stop \(=\) Positive edge of TP10 on the sof tware performance analyzer. Clock \(=\) Positive edge of TP7 on the software performance analyzer. Clock Qualifier = No qualified clocks are necessary.

Ground = Use a ground lead from the probe to a ground point on the sof tware performance analyzer.
high \(=\) a solid HIGH on the node under test.
low \(=\) a solid LOW on the node under test.
All logic is positive logic.

\section*{\(\mathrm{Vh}=91 \mathrm{H} 4\)}
NODE SIG

Event Counter Schematic 6

U 60-8 CH23
U 60-9 25 FU
U 60-10 low
U 60-11 91 H 4

Time Counter Schematic 6
U61-8 \(\mathrm{CH}_{2} 3\) U61-9 CH9U U 61-10 low U61-11 07P6
\begin{tabular}{|c|c|}
\hline NODE SIG & NODE SIG \\
\hline Sequence Counter & \multirow[t]{2}{*}{Statistics I/O Decoder Schematic 6} \\
\hline Schematic 6 & \\
\hline \multicolumn{2}{|l|}{U 62-8 CH23} \\
\hline U 62-9 UPPC & U 85-1 2P2P \\
\hline U 62-10 low & U 85-2 90U6 \\
\hline \multirow[t]{3}{*}{U 62-11 91H4} & U 85-3 AFHF \\
\hline & U 85-4 low \\
\hline & U 85-5 U089 \\
\hline Data Bus & U 85-6 high \\
\hline Transceiver & U 85-7 high \\
\hline \multirow[t]{2}{*}{Schematic 6} & U 85-9 high \\
\hline & U 85-10 07P6 \\
\hline U 70-1 2P2P & U 85-11 CH9 \\
\hline U 70-2 9P58 & U 85-12 91H4 \\
\hline U 70-3 3H4A & U 85-13 25FU \\
\hline U 70-4 0HP4 & U 85-14 91H4 \\
\hline U 70-5 3Us4 & U 85-15 UPPC \\
\hline U 70-6 CPSU & \\
\hline U 70-7 8U3C & \\
\hline U 70-8 65 H 6 & \\
\hline U 70-9 U7FF & \\
\hline U 70-11 U4F7 & \\
\hline U 70-12 5H5U & \\
\hline U 70-13 9FC 4 & \\
\hline U 70-14 AA65 & \\
\hline
\end{tabular}

\section*{SIGNATURE TABLE LOOP E.}

LOOP E signatures are valid while running the Statistics Test.
Start = Positive edge of TP11 on the software performance analyzer.
Stop = Positive edge of TP 10 on the software performance analyzer.
Clock = Positive edge of TP7 on the software performance analyzer.
Clock Qualifier \(=\) No qualified clocks are necessary.
Ground = Use a ground lead from the probe to a ground point on the sof tware performance analyzer.
high \(=\) a solid HIGH on the node under test.
low \(=\) a solid LOW on the node under test.
All logic is positive logic.
\(\mathrm{Vh}=\mathrm{AC} 79\)
\begin{tabular}{|c|c|c|c|}
\hline NODE SIG & NODE SIG & NODE SIG & NODE SIG \\
\hline \multirow[t]{3}{*}{Misc Gates Schematic 7} & U 23-10 9318 & \multirow[t]{3}{*}{Time Counter Schematic 6} & \multirow[t]{3}{*}{Interrupt Controller Schematic 6} \\
\hline & U 23-11 high & & \\
\hline & U 23-12 low & & \\
\hline U 5-4 0000 & U 23-14 P126 & U 61-2 low & \multirow[t]{3}{*}{U 63-1 low U 63-2 H393} \\
\hline \multirow[t]{2}{*}{U 5-6 5958} & \multirow[t]{3}{*}{U 23-15 0000} & U61-30000 & \\
\hline & & U 61-4 1-6H & \\
\hline U 8-1 P01C & & U 61-34 UP8H & U 63-3 6FA0 \\
\hline \multirow[t]{2}{*}{U 8-5 0U3A} & \multirow[t]{3}{*}{Event Counter Schematic 6} & U 61-35 UP8H & U 63-4 719 H \\
\hline & & U 61-36 UP8H & U 63-5 7F31 \\
\hline U 19-1 high & & U 61-37 0000 & U 63-6 7H6H \\
\hline U 19-2 113P & U 60-2 low & U 61-38 low & U 63-7 F948 \\
\hline U 19-3 high & U 60-3 0000 & U 61-39 UP8H & U 63-8 2P5A \\
\hline U 19-4 P126 & U 60-4 1-6H & & U 63-9 U042 \\
\hline U 19-5 P126 & U 60-29 1 \({ }^{\text {c } 6 \mathrm{H}}\) & & U 63-10 H67F \\
\hline U 19-6 P126 & U 60-30 1 1 C 6 H & Sequence Counter & U 63-11 HH92 \\
\hline U 19-12 113P & U 60-31 1 1 C 6 H & \multirow[t]{2}{*}{Schematic 6} & U 63-12 low \\
\hline \multirow[t]{3}{*}{U 19-13 high} & U 60-32 1-6H & & U 63-13 low \\
\hline & U 60-33 C014 & U 62-4 1C6H & U 63-14 low \\
\hline & U 60-34 UP8H & U 62-32 0000 & U 63-15 low \\
\hline Misc Flip-flops & U 60-35 UP8H & U 62-33 0000 & U 63-16 high \\
\hline \multirow[t]{2}{*}{Schematic 7} & U 60-36 UP8H & U 62-34 AC79 & U 63-17 1489 \\
\hline & U 60-37 0000 & U 62-35 AC79 & U 63-20 804F \\
\hline U 23-1 low & U 60-38 low & U 62-36 AC79 & U 63-21 P01C \\
\hline U 23-2 low & U 60-39 UP8H & U 62-37 0000 & U 63-24 AU43 \\
\hline U 23-3 C014 & & U 62-38 0000 & U 63-25 low \\
\hline U 23-4 high & & U 62-39 AC79 & U 63-26 AC79 \\
\hline U 23-5 low & & & U 63-27 8427. \\
\hline U 23-6 high & & & U63-28 high \\
\hline U 23-7 U221 & & & \\
\hline U 23-9 5958 & & & \\
\hline
\end{tabular}

Appendix E - Model 64310A


Appendix F - Model 64310 A

\section*{SIGNATURE TABLE LOOP F}

LOOP F signatures are valid while running the Inter-Module Bus Test
NOTE

The IMB CABLE MUST BE REMOVED during signature analysis. This causes the test display to indicate a failure.

\section*{Start = Positive edge of TP1 1 on the software performance analyzer.}

Stop = Positive edge of TP10 on the software performance analyzer.
Clock = Positive edge of TP7 on the software performance analyzer.

\section*{Clock Qualifier = No qualified clocks are necessary.}

Ground = Use a ground lead from the probe to a ground point on the sof tware performance analyzer.

ECL signatures require a 5005 A Signature Multimeter:
To change from TTL to ECL --->
press the data threshold button three times.
To change from ECL to TTL --->
press the data threshold button five times.
high \(=\mathrm{a}\) solid HIGH on the node under test.
low \(=\) a solid LOW on the node under test.
All logic is positive logic.

\section*{\(\mathrm{Vh}=86 \mathrm{H} 2\)}
\begin{tabular}{|c|c|c|}
\hline NODE SIG & NODE SIG & NODE SIG \\
\hline TTL-to-ECL Converter & ECL-to-TTL Converter & Analyzer Status \\
\hline Schematic 7 & Schematic 7 & Latch \\
\hline U 1-2 86H2 ECL & U 3-5 53C9 & \\
\hline U 1-3 5386 ECL & U 3-7 53C9 ECL & U 7-1 low \\
\hline \(\mathrm{U} 1-52 \mathrm{~A} 3 \mathrm{U}\) & U 3-11 5386 ECL & U 7-6 7HU8 \\
\hline U 1-6 2A3U & U 3-12 5386 & U 7-9 C7C4 \\
\hline U 1-7 7P01 & & U 7-11 7297 \\
\hline U 1-10 7HU8 & & U 7-12 C7C4 \\
\hline U 1-11 54 PU & Misc Buffer & U 7-15 54PU \\
\hline U 1-12 53C9 ECL & Schematic 7 & U 7-19 7P01 \\
\hline
\end{tabular}

Schematic 7
U 7-19 7P01
\(\begin{array}{lll}\mathrm{U} & 5-4 & \text { low } \\ \mathrm{U} & 5-6 & 2 \mathrm{~A}\end{array}\)

\section*{NODE SIG}

Misc Gate
Schematic 7
U 8-1 low
U 8-2 low
U 8-3 high
U 8-4 high
U 8-5 low
U 8-6 high
U 17-1 2 A 3 U
U 17-2 low
U 18-1 low
U 18-2 low
U18-4 P40H
U18-5 P432
U 20-4 5386
U 20-4 5386
U
\(20-5\)
C 7 C 4
\(\mathrm{U} 20-8 \mathrm{P} 40 \mathrm{H}\)
20-8 P40H
U 20-10 53 C

\section*{Run Flip-flop} Schematic 7

U 22-1 high
U 22-2 low
U 22-3 high
U 22-4 high
U 22-5 low
Trigger Flip-flop Schematic 7

U 23-7 AFPH
U 23-9 2A3U
U 23-10 315
U 23-11 high
U 23-12 low

Appendix G - Model 64310A

\section*{SIGNATURE TABLE LOOP G.}

LOOP G signatures are valid while running an emulator analyzer stimulus test.

\section*{NOTE}

This test is not part of the software performance analyzer PV. It must be run from emulation PV. These signatures are valid whether or not the emulation bus cables are connected.
Start = Positive edge of TP 11 on the software performance analyzer.
Stop = Positive edge of TP 10 on the software performance analyzer.
Clock = Positive edge of TP7 on the sof tware performance analyzer.
Clock Qualifier = No qualified clocks are necessary.
Ground = Use a ground lead from the probe to a ground point on the sof tware performance analyzer.
high \(=\) a solid HIGH on the node under test.
low \(=\mathrm{a}\) solid LOW on the node under test.
All logic is positive logic.
\(\mathrm{Vh}=614 \mathrm{P}\)
NODE SIG

Misc Gates
Schematic 7
U 18-1 9174 J 18-2 9174 U18-5 614 P T18-6 U03A J 18-6 U03A \(\begin{array}{lll}\mathrm{U} 20-4 & 614 \mathrm{P} \\ \mathrm{U} 20-5 & 0000\end{array}\) U 20-5 0000 \begin{tabular}{l} 
U 20-6 \\
U \\
\(20-8\) \\
614 P \\
\hline
\end{tabular} \begin{tabular}{l} 
U 20-8 \\
U \(20-9\) \\
\hline
\end{tabular} 20-9 0000 U 20-10 614P
\begin{tabular}{|c|c|c|}
\hline NODE SIG & NODE SIG & NODE SIG \\
\hline Address Range 1 & Address Range 2 & \multirow[t]{2}{*}{Comparator 2 I/O Decoder} \\
\hline Comparators & Comparators & \\
\hline Schematic 3 & Schematic 4 & Schematic 4 \\
\hline U 27-1 high & U 42-1 high & U 54-4 0000 \\
\hline \multirow[t]{2}{*}{U 27-23 CCFH} & \multirow[t]{2}{*}{U 42-23 65 HP} & U 54-5 9728 \\
\hline & & U 54-6 40P6 \\
\hline U 28-1 high & U 43-1 high & U 54-74401 \\
\hline \multirow[t]{2}{*}{U 28-23 2F59} & \multirow[t]{2}{*}{U 4j-23 2962} & U 54-9 482F \\
\hline & & U 54-10 54A3 \\
\hline U 29-1 high & U 44-1 high & U 54-11 high \\
\hline \multirow[t]{2}{*}{U 29-23 7149} & \multirow[t]{2}{*}{U 44-23 A 38A} & U 54-12 high \\
\hline & & U 54-13 F509 \\
\hline U 30-1 high & U 45-1 high & U S4-14 F2F4 \\
\hline U 30-23 CHA8 & U 45-23 35PH & U 54-15 0490 \\
\hline U 31-1 high & U 46-1 high & \\
\hline U 31-23 88P9 & U 46-23 A447 & \\
\hline U 32-1 high & U 47-1 high & \\
\hline U 32-23 A9P9 & U 47-23 254U & \\
\hline
\end{tabular}

Don't Care Latch
Schematic 3
U 59-2 FF09
or 7783
U 59-11 667P
U 59-19 559P

Comparator 1
I/O Decoder
Schematic 3
U67-4 0000
U 67-5 9728
U 67-6 6588
U 67-7 F8A7
U 67-9 HFP6
U 67-10 4H17
U 67-11 667P
U 67-12 high
U 67-13 P9A
U67-14 1007
U 67-15 HA83

Mode Latch
Schematic 5
U 72-12 2 PP1```


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