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# "Use of ATTACHed Interrupts in the UCSD p-System"

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## ABSTRACT

Version IV.0 of the UCSD p-System supports concurrent processes with the use of the SIGNAL and WAIT primitive operations on semaphores. By use of the ATTACH primitive, semaphores may also be signalled by asynchronous interrupts.

This allows for application programs written in Pascal to respond to real-time external events. A sample program which does terminal emulation with file transmit and receive functions will be presented, along with a program which illustrates control of hardware functions of bit-oriented devices from a high-level language.

The UCSD p-System provides a convenient basis for software development on a large variety of microcomputers. Highly interactive, user-friendly programs may be constructed to fill a variety of single-user, personal workstation computing needs. However, many useful applications of microcomputers involve response to real-time events, and asynchronous control of devices which do not fall into the usual categories of printers, consoles, or character-oriented devices. The control of bit-oriented and analog devices by programs running under the UCSD p-System has been difficult or impossible until the release of Version IV.0.

Even without entering the realm of real-time machine control, a very common problem facing the programmer of a p-System personal workstation has been the construction of a 'terminal emulator' program, to allow communications to a remote host computer through a modem or other serial communications link. Appendix 1 contains a listing of a UCSD Pascal program which solves this problem for the specific case of communicating with Telemail, an electronic mail service available on GTE Telenet. The program is not represented as being completely general-purpose and user-configurable, nor is it transportable to other p-System versions in object code form. However, modifications to the source text to fit other machines would be minor, provided the target implementation supports the attachment of external events to semaphore data structures.

For tutorial purposes, a much smaller and simplified version of the program is listed in Appendix 2. The basic algorithm is as follows:

repeat

{ if a key is struck on the keyboard, send the character out to the modem }

{ if a character is received from the modem, display the character on the screen }

until finished;

A first attempt to code this in Pascal might look something like this:

repeat

  read(keyboard,ch);  
  write(remote,ch);  
  read(remote,ch);  
  write(output,ch);

until finished;

... which is quickly found to be of little use in practical time-sharing applications, since only one character from the host can be displayed for every character from the keyboard.

A solution which works on Version II.1 uses the Unit\_Status system intrinsic to find out how many characters are in the input queue for the console and remote units:

repeat

  Unit\_Status(1,digits,1);  
  if digits[0] <> 0  
  then  
    begin  
      for i := 1 to digits[0] do  
        begin  
          read(keyboard,ch);  
          write(remote,ch)  
        end;  
    end;

  Unit\_Status(7,digits,1);  
  if digits[0] <> 0  
  then  
    begin  
      for i := 1 to digits[0] do  
        begin  
          read(remote,ch);  
          write(output,ch)  
        end;  
    end;

until finished;

While this solution is adequate as presented, the overhead of the polling technique, combined with the desire to have more functions supported, make it difficult to keep up with a continuous 300 baud data stream. Practical terminal emulators with features such

as file transmission and printer hardcopy became very large and complex, resorting to obscure Pascal coding tricks and to assembly-language external procedures in an attempt to sustain a 300 or 1200 baud data rate.

Version IV.0, as currently implemented on all TI 990 computers which support interrupts from character-oriented p-System devices, allows a 'full-function' terminal emulator program to be written with comparative ease, since language constructs are available which match the problem to be solved. This makes the main body of the terminal emulator appear effectively as:

```
repeat
  {Nothing}
until finished;
```

. . .since all the work is done by processes which are activated in response to external events.

These language extensions include a new data type (SEMAPHORE), a new block type (PROCESS), and five new pre-defined global procedures (ATTACH, SEMINIT, START, SIGNAL and WAIT). All except ATTACH are intended to be machine-independent constructs, and can be used on systems which do not support external asynchronous events. The use of these language features is described in the Version IV.0 Users' Guide, however, since the ATTACH intrinsic is somewhat machine-dependent, a description of the implementation on TI 990 computers is given here.

Just as a real processor needs to finish (or at least, bring to some orderly suspension point) the current machine instruction before handling an external interrupt, so must the p-machine. In practice, all of the p-machine interrupts which were generated by the real machine during the interpretive execution of the prior p-machine instruction are recognized before the next p-machine instruction is fetched. P-machine interrupts are selectively enabled by ATTACHing a SEMAPHORE to an interrupt level, and disabled by ATTACHing the value NIL to an interrupt level. The priority of the p-machine interrupt is determined by the priority of the PROCESS which is WAITing on the SEMAPHORE. In the current 990 implementation, 32 p-machine interrupts are supported; 64 will be supported in the IV.1 release in an effort to standardize the use of ATTACH on all p-System processors.

It is important to note the difference between a p-machine interrupt and an interrupt generated by hardware and handled by the real processor. For example, the 990/10 receives a hardware interrupt on level 5 every 1/120th of a second. The machine code which handles this interrupt maintains a 32-bit integer which represents the time of day, but only on the full 1-second intervals does it generate the p-machine interrupt level 16, and then only if level 16 has been enabled by having had a SEMAPHORE ATTACHed to it. As a consequence, the DS990 Model 1 can run exactly the same Pascal PROCESS for handling the p-machine level 16 interrupt, even though the real-time clock on the Model 1 generates hardware level 2 interrupt every 250 milliseconds. These differences are handled in the machine code which services the interrupt, so that the Pascal programmer sees a consistent p-machine interrupt structure.

Another advantage to this de-coupling of hardware and software is that several p-machine interrupts can be generated by the same hardware interrupt under different circumstances, for example, a 0.1 second and a 10 second p-machine interrupt. Or more than one hardware interrupt could signal the same p-machine interrupt. Obviously, every hardware interrupt must have some machine code in place to handle the interrupt, but the amount of processing required in machine code could be as simple as acknowledgement of the interrupt bit and a generation of the appropriate p-machine interrupt. External (machine code) procedures are easily written which can be called from a Pascal program to effect CRU I/O and TILINE I/O.

Appendix 3 describes the requirements of a software driver which takes the output of a text formatter program and controls a letter-quality printer. In this case, the printer has a 24-bit parallel interface. The encoding of the print-stream information was designed with an assembly-language driver program in mind, but the Pascal solution given was much easier to write, and could be transported with a minimum of trouble. Further, the same Pascal source can be easily modified to interface a variety of different output devices to the same print-stream protocol, including the H-P 7220A plotter which produced the overhead projection texts.

The preparation and production of this paper on a personal workstation computer running the UCSD p-System is a (somewhat needless) demonstration of the usefulness of the p-System in an office environment. Likewise, the fact that the entire p-System can be maintained and re-generated on the same machine is no surprise to system software developers who have used the p-System. However, the introduction of several new factors in Version IV.0 now makes possible the application of the p-System to a large subset of the problems which previously required assembly-language operating systems for real-time process control. Use of ATTACHed Pascal PROCESSES, coupled with machine-code interrupt handlers, external I/O primitive routines, and the use of the Native Code Generator to produce machine code from Pascal p-code, will allow many real-time applications to be easily implemented in a high-level, transportable language and Operating System.

#### Appendix 1

```
-----
Terminal emulator program for use with
GTE Telenet and the Telemail service.

Uses interrupts from the keyboard, remote,
and 1-second interval timer, ATTACHed to
SEMAPHOREs which are WAITed on by several
PROCESSES.

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-----
```

```
program telemail;
const
  clocksig = 16;
  keysig = 17;
  remsig = 18;
var
  ptr: integer;
  tick,
  godump,
  waiting;
```

```

keyready,
remready,
eolecho,
reply: semaphore;
pid: processid;
p: packed record
  case integer of
    1: ( a: packed array
        [0..80] of char);
    2: ( s: string[80]);
    3: ( k: integer);
    4: ( x: integer;
        online: boolean);
  end;
keych,
remch,
ret: packed array [0..1] of char;
ch: char;
dumping,
quitting: boolean;
i,
j: integer;
fname,
mail,
username,
password,
altuser,
altpass,
termtype,
logoff: string;
ff: file;           {the log file}
gg: interactive;   {the file to transmit}
buff: packed array [0..1023] of char;

```

process busy;

```

-----
The OS does not tolerate a user program
that has every process totally blocked.
This process has lower priority than the
main program, and cannot be blocked itself,
since it doesn't wait on anything. If it
is scheduled, it will be pre-empted sooner
or later by another task of higher priority.
-----

```

```

begin
  while not quitting do {waste time};
  signal(reply);
end {busy};

```

process clocker;

```

-----
This process has the highest priority, and
ensures that there will be an opportunity
for task switching at one-second intervals.
The signal(reply) ensures that the program
doesn't become deadlocked due to a lost
character echo.
-----

```

```

begin
  while not quitting do
    begin
      wait(tick);
      signal(reply);
    end;
  attach(nil,clocksig);
end {clocker};

```

process dumper;

```

-----
This process lies dormant until a file is
opened for transmission by procedure dof5.
It then transmits the text a line at a time,
putting a local copy on the console, and waits
for the echo of the carriage return. (This
delay avoids overrunning the Telenet input
buffers, which were set up with human typists
in mind.) A possible deadlock could occur if
the echo is lost, but can be cured by entering
a carriage return from the keyboard. During
this process, the getrem process does not put
echoed chars to the screen or log file.
-----

```

```

var
  s: string[255];

```

```

begin
  repeat
    wait(godump);
    seminit(eolecho,0);
    if dumping then
      begin
        while not eof(gg) do
          begin
            readln(gg,s);
            writeln(s);
            moveright(s[1],s[2],length(s));
            unitwrite(8,s[2],length(s),,
              16396);
            unitwrite(8,ret,1,,16396);
            wait(eolecho);
          end;
        close(gg,lock);
        writeln('---Closing File: ',fname,
          '---');
        writeln;
        dumping := false;
      end;
    until quitting;
  end {dumper};

```

procedure dof1;

```

begin
  unitwrite(8,mail[2],(length(mail) - 1),,16396);
  unitwrite(8,ret,1,,16396);
end {dof1};

```

procedure dof2;

```

begin
end {dof2};

```

procedure dof3;

```

begin
end {dof3};

```

procedure dof4;

```

begin
end {dof4};

```

procedure dof5;

```

begin
  attach(nil,keysig);

```

```

-----
We need to temporarily de-attach the keyboard
signal, in order to do an ordinary readln of
the file name.
-----

```

```

writeln;
j := 99;

```

[\$1-]

```

repeat
  write('Enter name of text file ',
    'to transmit, or <esc> <ret> -->');
  readln(fname);
  if fname[1] <> chr(27)
  then
    begin
      fname := concat(fname,'.text');
      reset(gg,fname);
      j := ioresult;
      if j <> 0 then
        writeln('No such file');
      close(gg);
    end
  else
    j := 0;
until j = 0;

```

[\$1+]

```

if fname[1] <> chr(27) then
  begin
    reset(gg,fname);
    writeln('---Transmitting File: ',fname,
      '---');
    dumping := true;
    signal(godump);
  end;

```

```

-----
Now, we can re-attach the semaphore to the
keyboard interrupt so that the getkey process
can handle characters.
-----

```

```

    attach(keyready,keysig);
end {dof5};

procedure dof6;
begin
    unitwrite(8,altuser[2],(length(altuser)-1),,16396);
    unitwrite(8,ret,1,,16396);
    for j := 1 to 2000 do {waste time};
    unitwrite(8,altpass[2],(length(altpass)-1),,16396);
    unitwrite(8,ret,1,,16396);
end {dof6};

procedure dof7;
begin
    unitwrite(8,username[2],(length(username)-1),,16396);
    unitwrite(8,ret,1,,16396);
    for j := 1 to 2000 do {waste time};
    unitwrite(8,password[2],(length(password)-1),,16396);
    unitwrite(8,ret,1,,16396);
end {dof7};

procedure dof8;
begin
    unitwrite(8,logoff[2],(length(logoff)-1),,16396);
    unitwrite(8,ret,1,,16396);
    quitting := true;
end {dof8};

```

```
process getkey;
```

```

-----
|This process is activated by a character being
|placed in the keyboard queue. The specialkey
|function returns TRUE if the key is one of the
|'F1' thru 'F8' keys on the 911 VDT, and trans-
|lates the keys to ASCII '1' thru '8'.
-----

```

```
function specialkey: boolean;
```

```

begin {specialkey}
    specialkey := false;
    if ord(ch) in [146..153] then
        begin
            ch := chr(ord(ch) - 97);
            specialkey := true;
        end;
    end;
end {specialkey};

```

```
begin {getkey}
```

```

repeat
    wait(keyready);
    if not quitting
    then
        begin
            {get from keyboard}
            unitread(2,keych,1,,12);
            ch := keych[0];
            if specialkey
            then
                begin
                    case ch of
                        '1': dof1;
                        '2': dof2;
                        '3': dof3;
                        '4': dof4;
                        '5': dof5;
                        '6': dof6;
                        '7': dof7;
                        '8': dof8;
                    end {CASE}
                end
            else {not specialkey}
                begin
                    {put to remote}
                    unitwrite(8,keych,1,,16396);
                end
            end
            and
            {if quitting}
            begin
                attach(nil,keysig);
            end;
        until quitting;
    end {getkey};

```

```
process getrem;
```

```

-----
|This process is activated by a character being
|placed in the remote queue. The echoed chars
|are normally placed in the logfile, except for
|control chars, and during file transmission,
|since the echo is unreliable from Telenet, and
|another copy of the text is not needed.
-----

```

```
var
    iord: integer;
```

```

begin
    repeat
        wait(remready);
        if not quitting
        then
            begin
                {get from remin}
                unitread(7,remch,1,,16384);
                ch := remch[0];
                iord := ord(ch);
                if iord <> 10 then
                    begin
                        if not dumping then
                            begin
                                {put to screen}
                                unitwrite(1,remch,1);
                                signal(reply);
                            end;
                        end;
                    if dumping and (iord = 13) then
                        signal(eolecho);
                    if not dumping
                then
                    if (iord = 13)
                    or ((iord > 31) and (iord < 127))
                    then
                        begin
                            buff[ptr] := ch;
                            ptr := ptr + 1;
                            if ptr = 1024 then
                                begin
                                    ptr := blockwrite(ff,
                                        buff,2);
                                    ptr := 0;
                                    fillchar(buff,1024,chr(0));
                                end;
                            end;
                        end
                    else {quitting}
                        begin
                            attach(nil,remsig);
                        end;
                    until quitting;
                end {getrem};
            end;
        until quitting;
    end {getrem};

```

```
procedure initialize;
```

```

-----
|Initializes all the strings, and opens the
|next available logfile on the default volume.
|Unitclears the remote and console units.
-----

```

```
begin
```

```

    ret[0] := chr(13);
    {The four strings which follow need to be changed
    to the appropriate values for each user. Note
    the unused ':' at the beginning, which is used to
    force word alignment for those PME's that are
    sensitive to word alignment on unitwrites.}
    username := ':xxxxxxx';
    password := ':xxxxxxx';
    altuser := ':xxxxxxx';
    altpass := ':xxxxxxx';
    logoff := ':bye';
    mail := ':Mail';
    termtype := ':D1';
    dumping := false;
    quitting := false;
    {S1-}
    i := 0;
    j := 0;
    repeat
        i := i + 1;
        p.s := '.x';
        p.s[2] := chr(i + 64);
        fname := concat('termlog',p.s,'.text');
        reset(ff,fname);
        j := ioresult;
        if j = 0
        then

```

## Appendix 2

```

        close(ff,lock)
    else
        close(ff);
until j <> 0;
{${+}
rewrite(ff,fname);
fillchar(buff,1024,chr(0));
ptr := blockwrite(ff,buff,2);
ptr := 0;
unitclear(1);
unitclear(7);
unitclear(8);
end {initialize};

begin {main}

    initialize;

    write(chr(12));
    writeln('Waiting for connection...');
    writeln('214\748-0127 (300)...214\748-6371 (1200)');

    repeat
        p.online := false;
        unitstatus(7,p.a,1);
    until p.online;

    unitclear(7);
    writeln('Use F1 for "Mail" command');
    writeln('Use F5 to select transmit file');
    writeln('Use F6 for Alternate user');
    writeln('Use F7 for Username/password');
    writeln('Use F8 for Quitting');
    unitclear(1);

    seminit(remready,0);
    seminit(keyready,0);
    seminit( godump,0);
    seminit( reply,0);
    seminit( tick,0);

    attach( tick,clocksig);
    attach(remready,remsig);
    attach(keyready,keysig);

    start( getkey,pid,800,142);
    start( getrem,pid,500,140);
    start( dumper,pid,500,129);
    start( clocker,pid,500,145);
    start( busy,pid,200,120);

    { Get Telenet's attention by sending 2 carriage returns
      at human speed, then define the video terminal}

    for i := 1 to 1000 do {waste time};
    unitwrite(8,ret,1,,16396);
    for i := 1 to 1000 do {waste time};
    unitwrite(8,ret,1,,16396);

    for i := 1 to 1000 do {waste time};
    unitwrite(8,termtype[2],2,,16396);
    unitwrite(8,ret,1,,16396);

    repeat
        wait(reply);
    until quitting;

    if ptr <> 0 then
        ptr := blockwrite(ff,buff,2);
    close(ff,lock);

    signal(keyready);
    signal(remready);
    signal(godump);

    attach(nil,clocksig);
    attach(nil,keysig);
    attach(nil,remsig);

    for i := 1 to 3000 do {waste time};
    writeln;
    writeln('Returning to PascalSystem');

end {telemail}.

```

```

-----
Terminal emulator program tutorial.
Provides basic TTY emulation only.

Uses interrupts from the keyboard, remote,
and 1-second interval timer, ATTACHED to
SEMAPHORES which are WAITed on by several
PROCESSES.

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-----

```

```
program tutorial;
```

```

const
    clocksig = 16;
    keysig = 17;
    remsig = 18;

```

```

var
    tick,
    keyready,
    remready: semaphore;
    pid: processid;
    keych,
    remch,
    ch: char;
    quitting: boolean;

```

```
process busy;
```

```

-----
The OS does not tolerate a user program
that has every process totally blocked.
This process has lower priority than the
main program, and cannot be blocked itself,
since it doesn't wait on anything. If it
is scheduled, it will be pre-empted sooner
or later by another task of higher priority.
-----

```

```

begin
    while not quitting do {waste time};
end {busy};

```

```
process clocker;
```

```

-----
This process has the highest priority, and
ensures that there will be an opportunity
for task switching at one-second intervals.
-----

```

```

begin
    while not quitting do
        wait(tick);
    end {clocker};

```

```
process getkey;
```

```

-----
This process is activated by a character being
placed in the keyboard queue.
-----

```

```

begin {getkey}
    repeat
        wait(keyready);
        {get from keyboard}
        unitread(2,keych,1,,12);
        {put to remote}
        unitwrite(8,keych,1,,16396);
    until quitting;
end {getkey};

```

```
process getrem;
```

```

-----
This process is activated by a character being
placed in the remote queue.
-----

```

```

begin
    repeat
        wait(remready);
        {get from remin}
        unitread(7,remch,1,,16384);
        {put to screen}
        unitwrite(1,remch,1);
    until quitting;
end {getrem};

```

```
procedure initialize;
```

```

-----
|Unitclears the remote and console units.
|-----

```

```

begin
  quitting := false;
  unitclear(1);
  unitclear(7);
  unitclear(8);
end {initialize};

begin {main}
  initialize;

  seminit(remready,0);
  seminit(keyready,0);
  seminit(   tick,0);

  attach(   tick,clocks);
  attach(remready,rem);
  attach(keyready,keys);

  start( getkey,pid,800,142);
  start( getrem,pid,500,140);
  start( clocker,pid,500,145);
  start(  busy,pid,200,120);

  repeat
    wait(tick);
  until quitting;

  {Note that there is no provision for quitting, and that
  the (higher priority) process clocker is also waiting
  on tick.}

end {tutorial}.

```

### T2WPUNIT Interface Description

The text formatter program generates a print-stream which may be directed either to a file or to a printer. If the print-stream is directed to a file, it may subsequently be printed with the de-spooling program. Both of these programs interface with the physical printer by means of a unit T2WPUNIT which contains a signal public procedure WPINTERFACE(ch: char) to which the print-stream is sent byte-by-byte.

```

UNIT T2WPUNIT;
INTERFACE
  procedure wpinterface(ch: char);
IMPLEMENTATION
  var
    first_time: boolean;
  procedure wpinterface;
  begin
    if first_time then
      begin
        first_time := false;
        {here initialize printer}
      end;
      {here process print-stream byte ch}
    end {wpinterface};
  BEGIN {T2WPUNIT}
  first_time := true;
  ***;
  END {T2WPUNIT}.

```

For documents printed in fixed-pitch mode, the print-stream is a simple ASCII stream. Each line of print is sent from left to right and terminated by a CR. The CR is usually followed by one or more LF's according to the amount of paper movement required be-

tween lines. However, where overprinting is required (e.g. for underlining), the CR is not followed by a LF. For fixed-pitch printers which are not capable of overprinting (because they have no non-advancing end-of-line function), the WPINTERFACE driver can throw away all characters after a CR until a LF is encountered. When single-forms mode is selected, the print-stream contains an ASCII group-separator character GS to signify that the driver should pause for a new sheet of paper to be positioned (or possibly should activate an automatic sheet feeder).

For documents printed in variable-pitch mode, the print stream contains tightly encoded information on horizontal printhead movement, vertical paper movement, print-element character selection, hammer energy, special print effects, and single-forms control. Such variable-pitch information is always introduced in the print-stream by the ASCII sequence NUL-NUL-SO to indicate to the WPRINTINTERFACE driver that variable-pitch mode is required. The driver must decode the print-stream and produce the requested printer actions. The following page defines the contents of the print-stream when in variable-pitch mode.

### Appendix 3

#### Variable-Pitch Print-Stream Description

Drivers are instructed to enter variable-pitch mode by the sequence NUL-NUL-SO, and to leave variable-pitch mode by the sequence NUL-NUL-SI. Once in variable-pitch mode, the driver must respond to the following character sequences:

```

Type 1: (2 bytes)  1rrr rrrr  eeem mmmm
Type 2: (2 bytes)  01dd mmmm  mmmm mmmm
Type 3: (1 byte)   00cc cccc

```

where:

rrrrrr = 7-bit character (code or rotation)

eee = 3-bit hammer energy (zero if n/a)

m...m = 5-bit or 12-bit movement distance:

in 1/120-inch increments for horizontal movement  
in 1/48-inch increments for vertical movement

dd = 2-bit movement direction:

00 = right (forward tabulation)  
01 = left (reverse tabulation)  
10 = down (forward line feed)  
11 = up (reverse line feed)

cccc = 5-bit special action code:

NUL = no action  
GS = pause after single form  
BS = set direction = backward  
HT = set direction = forward  
CR = home printhead, set direction = forward  
ESC = next Type-1 sequence defines underline  
SI = return to fixed-pitch mode

Any Type-3 byte value from 30 to 3F hexadecimal sets special-effects:

byte = 0011 xdbu where:

u = underscore mode  
b = boldface mode  
d = double-strike mode  
x = (not defined yet)

Type-1 sequences cause the print-head to move mmmm 120ths of an inch to the left or right (whichever was set by the last Type-2 or Type-3 sequence), and then the character rrrrrr to be printed with hammer energy eee.

```

{$N+}
UNIT T2WPUNIT;
{UNIT for the NEC Spinwriter with parallel card
and using ABSOLUTE SPOKE mode}
INTERFACE
PROCEDURE wpinterface(ch: char);
IMPLEMENTATION
const
wpcru = 64; {base address of interface card}
[cpu output bits]
restore = 12; {sbo to restore, sbz to run}
select = 16; {sbo to select}
riblft = 20; {sbo for lower ribbon part (black)}
halfsp = 11; {lsb of horizontal movement}
waybit = 10; {sbz = right or down (head wrt paper)}
lpback = 13; {sbo to read bits back for test}
pwstb = 18; {print wheel strobe}
pfstb = 17; {paper feed strobe}
carstb = 19; {carriage strobe}
[cpu input bits]
papout = 22; {true if paper out}
ribout = 21; {true if ribbon out}
pcheck = 20; {true if printer in check}
pready = 16; {true if printer ready}
pfready = 17; {true if paper feed ready}
pwready = 18; {true if print wheel ready}
carready = 19; {true if carriage ready}

type
onebit = 0..1;
twobits = 0..3;
threebits = 0..7;
nibble = 0..15;
fivebits = 0..31;
sixbits = 0..63;
sevenbits = 0..127;
ubyte = 0..255;
twelvebits = 0..4095;
bits = packed array [0..15] of boolean;
typekind = (type3,type2,type1a,type1b);
waykind = (right,left,down,up); {direction of head wrt paper}
t3kind = (action,s_effects);
actionkind = (prefix,ud1,ud2,ud3,uv4,ud5,ud6,ud7,
setback,setnorm,ud10,ud11,ud12,home,entervp,exitvp,
ud16,ud17,ud18,ud19,ud20,ud21,ud22,ud23,
ud24,ud25,ud26,setus,ud28,holdit,ud30,ud31);
word0 = packed record {for byte-swapping}
r_byte: ubyte;
l_byte: ubyte;
end;
word1 = packed record {for TYPE 1 commands}
movement: fivebits;
energy: threebits;
rotation: sevenbits;
istype1: boolean;
end;
word2 = packed record {for TYPE 2 commands}
movement: twelvebits;
direction: waykind;
whichtype: typekind;
end;
word3 = packed record {for TYPE 3 commands- actions}
res1: ubyte;
t3action: actionkind;
whicht3: t3kind;
whichtype: typekind;
end;
word4 = packed record {for TYPE 3 commands- effects}
res1: ubyte;
us_on: boolean;
bf_on: boolean;
ds_on: boolean;
xx_on: boolean; {not currently used}
res2: onebit;
whicht3: t3kind;
whichtype: typekind;
end;
[word5 is just an integer and is denoted by i3]
word6 = packed record {for 1355 Diablo in Rib. Opt. 2}
spoke: sevenbits;
ribbon: threebits;
energy: twobits;
res1: nibble;
end;
[word7 is a packed array of bits]
word8 = packed record {for NEC Spinwriter in Absolute mode}
spoke: sevenbits;
abs: boolean;
energy: threebits;
res1: fivebits;
end;
urec = packed record
case integer of
0: (w0: word0);
1: (w1: word1);
2: (w2: word2);
3: (w3: word3);
4: (w4: word4);
5: (i3: integer);
6: (w6: word6);
7: (bit: bits);
8: (w8: word8);
end;

var
inrec,outrec,usrec,cruword: urec;
intype1,intype2,inusdef,fixdpitch: boolean;
vdir,hdir: waykind;
bold,dubstrike,underlining: boolean;
vrtpos,horpos,nulcount: integer;
first_time: boolean;
PROCEDURE CPUIDLE; EXTERNAL;
PROCEDURE SETBASE(CRUBASE: INTEGER); EXTERNAL;
PROCEDURE CLEARBIT(BITNUM: INTEGER); EXTERNAL;
PROCEDURE SETBIT(BITNUM: INTEGER); EXTERNAL;
PROCEDURE LOADCRU(DATA,NUMBITS: INTEGER); EXTERNAL;
PROCEDURE STORECRU(VAR DATA: INTEGER; NUMBITS: INTEGER); EXTERNAL;
FUNCTION TESTBIT(BITNUM: INTEGER): BOOLEAN; EXTERNAL;
PROCEDURE wpinterface; (* PUBLIC PROCEDURE, PARAMETERS DECLARED ABOVE *)
procedure check_ready;

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var
ch: char;
acked: boolean;
pa: packed array [0..10] of integer;
begin {check_ready}
cpuidle; {allow cpu to idle until interrupt}
if (not testbit(pready))
or
(testbit(papout))
or
(testbit(ribout))
or
(testbit(pcheck))
then
begin
unitclear(1);
acked := false;
while not acked
do
begin
write(chr(13+128)); {Return without auto linefeed}
write('Printer needs attention- press <space>',chr(7));
cpuidle;
pa[0] := 0;
unitstatus(1,pa,1); {get number of keys buffered for input}
if pa[0] <> 0 then read(keyboard,ch);
if ch = ' ' then acked := true;
end;
unitclear(1);
gotoxy(0,100);
writeln('Correct printer condition (paper, ribbon, cover)');
writeln('Printing will resume when <enter> is pressed');
repeat read(keyboard,ch) until ch = chr(160);
end;
end; {check_ready}
procedure hardinit;
var
i: integer;
begin {hardinit}
cruword.i5 := 0;
loadcru(cruword.i5,16); {clear all data lines}
setbit(select); {select the printer}
setbit(restore); {tell it to restore}
clearbit(pfstb); {deactivate strobe line}
clearbit(pwstb); {deactivate strobe line}
clearbit(carstb); {deactivate strobe line}
setbit(riblft); {raise the ribbon}
for i := 1 to 500 do; {waste some time}
clearbit(restore); {let go of restore line}
i := i + 1;
while (i < 3000) and (testbit(pready) = false)
do i := i + 1;
if not testbit(pready)
then
begin
writeln('Cannot open printer');
end;
end; {hardinit}
procedure print_it(k: urec);
var
timeout,i: integer;
begin {print_it}
check_ready;
cruword.i5 := 0;
cruword.w8.spoke := k.w1.rotation;
cruword.w8.energy := k.w1.energy;
cruword.w8.abs := true;
loadcru(cruword.i5,12);
if testbit(papout) then check_ready;
timeout := 1;
while (timeout < 30000)
and
(not testbit(pwready))
do
begin
check_ready;
timeout := timeout + 1;
end;
setbit(pwstb);
clearbit(pwstb);
end; {print_it}
procedure move_carriage(howfar: integer; whichway: waykind);
var
timeout,tempmove,bigmove,lsb,lead: integer;
begin {move_carriage}
if whichway = right then horpos := horpos + howfar
else horpos := horpos - howfar;
check_ready;
if not underlining
then
begin
while howfar > 0
do
begin
if howfar > 1023 then tempmove := 1023 else tempmove := howfar;
howfar := howfar - 1023;
bigmove := tempmove div 2;
lsb := tempmove mod 2;
if lsb = 1 then setbit(halfsp) else clearbit(halfsp);
case whichway of
right: clearbit(waybit);
left: setbit(waybit);
end;
loadcru(bigmove,10);
timeout := 1;
while (timeout < 30000)
and
(not testbit(carready))
do
begin
check_ready;
timeout := timeout + 1;
end;
setbit(carstb);
clearbit(carstb);
end; {while howfar > 0}

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end      {of then clause on "if not underlining" }
else    {if underlining}
begin
  while howfar > 0
  do
    begin
      printit(usrec);
      case whichway of
        right: clearbit(waybit);
        left:  setbit(waybit);
      end;
      bigmove := 0;      {that is 0/60ths}
      setbit(halfsp);  [+ 1/120th}
      howfar := howfar - 1;
      loadcru(bigmove,10);
      timeout := 1;
      while (timeout < 30000)
      and
        (not testbit(carready))
      do
        begin
          check_ready;
          timeout := timeout + 1;
        end;
        setbit(carstb);
        clearbit(carstb);
      end; {while howfar > 0}
    end; {of the "if not underlining"}
  end; {move_carriage}
  procedure move_paper(howfar: integer; whichway: waykind);
  var
    tempmove: integer;
  begin {move_paper}
    if whichway = down then vrtpos := vrtpos + howfar
    else vrtpos := vrtpos - howfar;
    check_ready;
    setbit(halfsp);
    case whichway of {DOWN means printhead down, paper UP}
      down: clearbit(waybit);
      up:   setbit(waybit);
    end;
    while howfar > 0
    do
      begin
        if howfar > 1023 then tempmove := 1023 else tempmove := howfar;
        howfar := howfar - 1023;
        loadcru(tempmove,10);
        timeout := 1;
        while (timeout < 30000)
        and
          (not testbit(pready))
        do
          begin
            check_ready;
            timeout := timeout + 1;
          end;
          setbit(pfstb);
          clearbit(pfstb);
        end;
      end; {move_paper}
    end; {home_head}
    procedure home_head;
    begin {home_head}
      hdir := left;
      move_carriage(horpos,hdir);
      hdir := right;
      horpos := 0;
    end; {home_head}
    procedure turn_vp;
    begin {turn_vp}
      fixedpitch := false;
    end; {turn_vp}
    procedure turn_vp;
    begin {turn_vp}
      fixedpitch := true;
    end; {turn_vp}
    procedure initialize;
    begin
      intype1 := false;
      intype2 := false;
      fixedpitch := true;
      nulcount := 0;
      inusdef := false;
      setbase(wpcru);
      vdir := down;
      hdir := right;
      usrec.i5 := 0;
      usrec.wl.istype1 := true;
      bold := false;
      dubstrike := false;
      underline := false;
      vrtpos := 0;
      horpos := 0;
      hardinit;
      turn_vp;
      home_head;
    end; {initialize}
    procedure ex_pause;
    var
      cg: char;
    begin {ex_pause}
      writeln('Printing suspended by [single forms]');
      writeln('Printing will resume when <enter> is pressed');
      repeat read(keyboard,cg) until cg = chr(160);
    end; {ex_pause}
    procedure ex_type1;
    var
      saveusf: boolean;
      bdir: waykind;
      howfar: integer;
    begin {ex_type1}
      if inusdef
      then
        begin
          usrec.i5 := outrec.i5;
          inusdef := false;
          exit(ex_type1);
        end;
      howfar := outrec.wl.movement;

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move_carriage(howfar,hdir);
print_it(outrec);
if dubstrike and (not bold) then print_it(outrec);
if bold
then
begin
  case hdir of
    right: bdir := left;
    left:  bdir := right;
  end;
  saveusf := underlining;
  underlining := false;
  move_carriage(1,hdir);
  print_it(outrec);
  print_it(outrec);
  move_carriage(1,bdir);
  print_it(outrec);
  underlining := saveusf;
end;
end; {ex_type1}
procedure ex_type2;
var
  howfar: integer;
begin {ex_type2}
  case outrec.w2.direction of
    right: hdir := right;
    left:  hdir := left;
    down:  vdir := down;
    up:    vdir := up;
  end;
  if (outrec.w2.direction = down) or (outrec.w2.direction = up)
  then
  begin
    howfar := outrec.w2.movement;
    move_paper(howfar,vdir);
  end
  else
  begin
    howfar := outrec.w2.movement;
    move_carriage(howfar,hdir);
  end;
end; {ex_type2}
procedure ex_type3;
begin {ex_type3}
  if nulcount = 2
  then
  begin
    nulcount := 0;
  end;
  if outrec.w4.whicht3 = action
  then
  begin
    case outrec.w3.t3action of
      prefix: nulcount := nulcount + 1;
      setback: hdir := left;
      setnorm: hdir := right;
      home: home_head;
      entervp: turn_vp;
      exitvp: turn_vp;
      setus: inusdef := true;
      holdit: ex_pause;
    end; {case}
  end
  else
  begin
    if outrec.w4.bf_on then bold := true else bold := false;
    if outrec.w4.ds_on then dubstrike := true else dubstrike := false;
    if outrec.w4.us_on then underlining := true else underlining :=
false;
  end;
end; {ex_type3}
procedure process_it;
var
  pat packed array [0..1] of char;
begin {process_it}
  if fixedpitch and (ch <> chr(0)) and (nulcount <> 2)
  then
  begin
    pa[0] := chr(ord(ch));
    unitwrite(6,pa,1,,12);
    exit(process_it);
  end;
  if intype1
  then
  begin
    outrec.w0.r_byte := ord(ch);
    intype1 := false;
    ex_type1;
    exit(process_it);
  end;
  if intype2
  then
  begin
    outrec.w0.r_byte := ord(ch);
    intype2 := false;
    ex_type2;
    exit(process_it);
  end;
  inrec.w0.l_byte := ord(ch);
  if inrec.w2.whichtype = type3
  then
  begin
    outrec.w0.l_byte := ord(ch);
    ex_type3;
    exit(process_it);
  end
  else
  begin
    if inrec.w1.istype1
    then
      begin
        outrec.w0.l_byte := ord(ch);
        intype1 := true
      end
    else
      begin
        outrec.w0.l_byte := ord(ch);
        intype2 := true;

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    end;
end; {process_it}
begin {wpinterface}
  if first_time then
  begin
    first_time := false;
    initialize;
    end;
  process_it;
end; {wpinterface}
BEGIN {T2WPUNIT}
first_time := true; {UNIT initialization}
***;
{no UNIT termination}
END {T2WPUNIT}.
;
; Machine code for the external functions
;
  .proc machine
  limi 1 ; To simulate the effect of a
  blwp @8 ; Machine check (level 2 interrupt)
  b *r11
  .proc cpuidle
  idle
  b *r11
  .proc setbase,i
  .def crubase,ws
; pascal declaration;
; procedure setbase(i: integer); external;
; where i is the crubase desired (decimal)
;
;990 instruction is: li r12,i
;
  mov *r10+,crubase ; Pop stack into private storage
  b *r11 ; Return to pascal
crubase .word 0
ws .block 32 ; Workspace for the others
  .proc setbit,i
  .ref crubase,ws
; pascal declaration;
; procedure setbit(i: integer); external;
; where i is the bitnumber desired
;
;990 instruction is: sbo i
;
  mov *r10+,ws+2 ; Pop stack into new r1
  blwp start ; Do the stuff
  b *r11 ; Return to pascal
start .word ws,ep
inst sbo 0 ; Instruction mask
ep mov crubase,r12 ; Get current base from private storage
mov inst,r5 ; Op code for sbo
andi r1,00ffh ; Insure parm passed is 00 in first byte
soc r1,r5 ; R5 now has proper sbo instruction
x r5 ; Execute it
rtwp ; Done
  .proc clearbit,i
  .ref crubase,ws
; pascal declaration;
; procedure clearbit(i: integer); external;
; where i is the bitnumber desired
;
;990 instruction is: sbz i
;
  mov *r10+,ws+2 ; Pop stack into new r1
  blwp start ; Do the stuff
  b *r11 ; Return to pascal
start .word ws,ep
inst sbz 0 ; Instruction mask
ep mov crubase,r12 ; Get current base from private storage
mov inst,r5 ; Op code for sbz
andi r1,00ffh ; Insure parm passed is 00 in first byte
soc r1,r5 ; R5 now has proper sbz instruction
x r5 ; Execute it
rtwp ; Done
  .proc loadcru,2
  .ref crubase,ws
; pascal declaration;
; procedure loadcru(i,j: integer); external;
; where i is the 16-bit pattern desired, j is number of bits
;
;990 instruction is: li rx,i
;
  mov *r10+,ws+2 ; Pop # of bits into new r1
  mov *r10+,ws+4 ; Pop data word into new r2
  blwp start ; Go do it
  b *r11 ; Return to pascal
start .word ws,ep
inst ldc r2,0 ; Instruction mask
ep mov crubase,r12 ; Get current base from private storage
mov inst,r5 ; Puts 'ldcr r2,0' instruction in r5
andi r1,000fh ; Mask # of bits to 0-15
sla r1,6 ; Shift to spot required in instruction
soc r1,r5 ; Or into r5
x r5 ; Execute it
rtwp ; Done
  .proc storecru,2
  .ref crubase,ws
; pascal declaration;
; procedure storecru(var i: integer; j: integer); external;
; where i is the 16-bit result area, j is number of bits
;
;990 instruction is: stcr rx,j
;
  mov *r10+,ws+2 ; Pop # of bits into new r1
  mov *r10+,ws+4 ; Pop address of data into new r2
  blwp start ; Go do it
  b *r11 ; Return to pascal
start .word ws,ep
inst stcr *r2,0 ; Instruction mask
ep mov crubase,r12 ; Get current base from private storage
mov inst,r5 ; Puts 'stcr *r2,0' instruction in r5
andi r1,000fh ; Mask # of bits to 0-15
sla r1,6 ; Shift to spot required in instruction
soc r1,r5 ; Or into r5
x r5 ; Execute it
rtwp ; Done
  .func testbit,i
  .ref crubase,ws
; pascal declaration;
; function testbit(i: integer): boolean; external;
; where i is the bitnumber
;
;990 instruction is: tb i
; (returns true if bit is 1)
;
  mov *r10+,ws+2 ; Pop # of bits into new r1
  ai r10,2 ; Point to word provided on stack
; Note- the stack pointer is left pointing to result word
  blwp start ; Go do it
  mov ws,*r10 ; Push r0 of new ws
  b *r11 ; Return to pascal
start .word ws,ep
inst tb 0 ; Instruction mask
ep mov crubase,r12 ; Get current base from private storage
mov r0 ; Assume bit is false
andi r1,00ffh ; Insure displacement is in range
mov inst,r5 ; Get copy of instruction
soc r1,r5 ; Or in displacement
x r5 ; Execute test bit
jne $1 ; Jump if bit was false
inc r0 ; If bit was 1, r0 := 1
$1 rtwp ; All done
  .end

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US

## The Two Faces of UCSD Pascal

By Rich Gleaves  
Volition Systems

Rich Gleaves of Volition Systems submits the slides from a talk of his. I (as usual) dropped out where and when the talk was. I have included the first few slides of his talk of which the outline was as follows:

THE TWO FACES OF UCSD PASCAL  
UCSD PASCAL - INDUSTRY IMPACT  
UCSD PASCAL - HISTORY  
UCSD PASCAL SYSTEM VERSIONS  
UCSD PASCAL vs. STANDARD PASCAL  
UCSD PASCAL EXTENSIONS  
PROGRAM SEGMENTATION  
SEPARATE COMPILATION - UNITS  
UCSD I/O HIERARCHY  
INTERACTIVE I/O  
RANDOM ACCESS FILES

UNIT I/O  
STRINGS  
BYTE ARRAY MANIPULATION  
DYNAMIC STORAGE  
PROCEDURE TERMINATION  
EVEN MORE TRICKS  
RECORD AND ARRAY COMPARISON

If you would like to have the bodies for all these slides, please contact Volition Systems. ed.

### THE TWO FACES OF UCSD PASCAL

- Friendly beginner's language

Used at UCSD to teach introductory computer programming to non-science students. UCSD Pascal's